

AD-A183 985

LIGHTWEIGHT TOWED HOWITZER DEMONSTRATOR PHASE 1 AND  
PARTIAL PHASE 2 VOLUM (U) FMC COR MINNEAPOLIS MINN  
NORTHERN ORDNANCE DIV R RATHE ET AL APR 87

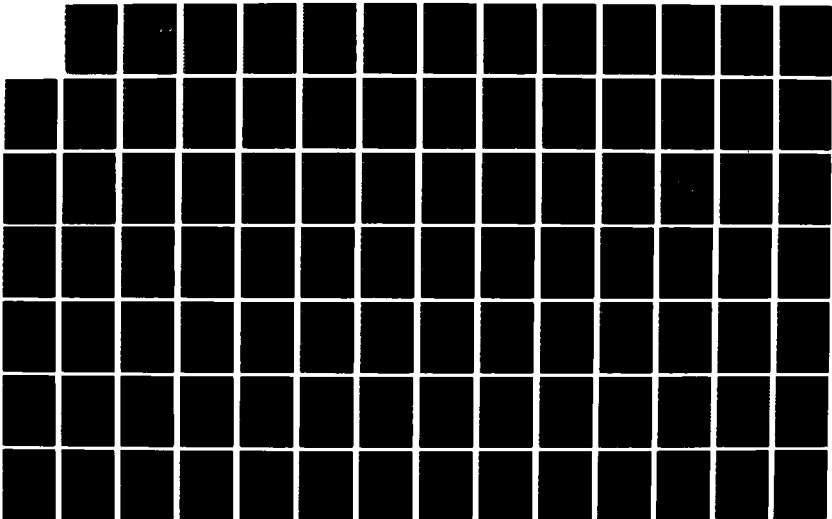
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FMC-E-3041-VOL-C-PT-1 DAAA21-86-C-0047

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MICROCOPY RESOLUTION TEST CHART

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DTIC FILE COPY

Lightweight Towed Howitzer Demonstrator

Final Report

Volume C - Part 1

Dynamic Analysis Report

April 1987

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ELECTE  
SEP 03 1987  
S C&D D

AD-A183 985

Contract Number DAAA21-86-C-0047

FMC CORPORATION  
Northern Ordnance Division  
4800 East River Road  
Minneapolis, Minnesota 55421

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SECURITY CLASSIFICATION OF THIS PAGE (When Data Entered)

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1. REPORT NUMBER	2. GOVT ACCESSION NO.	3. RECIPIENT'S CATALOG NUMBER
	AD-A183 985	
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18. SUPPLEMENTARY NOTES  None		
19. KEY WORDS (Continue on reverse side if necessary and identify by block number) 55mm towed gun howitzer, advanced weapons, composite cradle, composite hydraulic actuators, composite trails, field artillery weapon, firing stability analysis, howitzers, hydraulic control valves with force feedback, hydraulic joystick control of gun direction, hydraulic inertial rammer, hydraulic opening breech, hydraulic primer autoloader, <del>lightweight towed howitzer demonstrator (LTHD)</del> load out of battery howitzer, mortar howitzer, recoil energy recovery, recoil mechanism, <del>using</del> metal matrix composites, titanium muzzle brake, titanium platform, titanium spade, titanium walking beams, thermal stability, towing stability analysis, unconventional weapons, <del>and weight reduction of artillery</del>		
20. ABSTRACT (Continue on reverse side if necessary and identify by block number)  The LTHD (Lightweight Towed Howitzer Demonstrator) was to be a 9,000 lb equivalent to the M198, transportable via Blackhawk helicopter, with reduced emplacement time using fewer personnel. The FMC design achieved weight reduction via a mortar-like configuration, composites structure, and hydraulic actuators. Recovery of power from the recoil system, in turn, facilitated crew reduction via hydraulic emplacement, four-way joystick tube lay, and power ramming. FMC completed Concept Development (Ph I) and two-thirds of Detailed Design (Ph II) prior to funds running out. <i>Keep...</i>		

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Vol/Sec	Description
C	Dynamic Analysis
C/050	Table of Contents
C/060	Mass-Coordinate Data File
C/070	Computer File Inventory
C/100	Breech Actuator
C/110	Elevation and Equilibration
C/120	Energy Storage Accumulator
C/130	Equilibration Intensifier
C/140	Firing Stability
C/150	Lanyard Actuator
C/160	Load Position Actuator
C/170	Loading System
C/180	Parking and Service Brakes
C/190	Primer Autoloader
C/200	Recoil System
C/210	Recoil System Abandoned Dec B6 (fixed orifice)
C/220	Reservoir Accumulator
C/230	Towing Stability
C/240	Traverse Actuator
C/250	Tube
C/260	Tube Laying Accuracy
C/270	Walking Beam Actuators



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LINK - TAB	<input type="checkbox"/>
Unrecorded	<input type="checkbox"/>
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Signature _____	
Date _____	
Signature _____	

**A-1**

## DESCRIPTION: MASS-COORDINATE DATA FILE

## STATUS:

All component weights were recorded on the parts list (TDP, Dwg. 12585710-125) as they became known. This data, along with CAD-calculated values of individual component center of gravities, was entered into data files compatible with a CG and inertia-calculating computer program on the VAX called GRAVITY.BAS.

To simplify the stability analysis, component inertias about their own centers of gravity was neglected. The stability program (HOP.BAS) which reads in this data does, however, calculate the system inertia from the pivot point for hop. A better approximation of the tube inertia is used in this calculation. It has been estimated when the values for component inertias are ignored the resulting system inertia value is approximately 10 percent low.

The coordinate system used in all calculations is defined as follows:

Origin - defined as the intersection of the barrel center line with the trunnion center at the trunnion height (18.25 inches off ground).

X - the line in the horizontal plane perpendicular to the barrel centerline, with the positive direction to the left of barrel centerline.

Y - the line in the vertical plane perpendicular to the barrel centerline, with up being the positive direction.

Z - same as the barrel centerline, with the positive direction towards the muzzle.

The three data files containing the weight and CG data are described as follows:

LFBR.DAT (LTHD, Fire position of system, Battery position of barrel, Recoil components only). This separate data file is created so that the stability program (HOP.BAS) which uses this data can "move" these components separately during the simulation.

LFTE.DAT (LTHD, Fire position of system, Tow position of components, (non-recoiling) Elevating and traversing components only). (By definition, these components only rotate and do not translate.) This data file allows HOP.BAS to elevate and traverse only these components and the recoiling components.

LFTS.DAT (LTHD, Fire position of system, Tow position of components (except trails), Stationary components only). These

are all components that are not contained in the above two data files. They never translate and rotate only if hop occurs.

The reader is referred to the parts list for individual component weights or the following pages of this section for listings of the above data files which contain both weight and C.G. data.

AUTHOR: Scott Dacko

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GGGGGGGGGG  
GGGGGGGGGG

M	M	222	000	EEEE	999	666
MM	MM	2 2	0 0	E	9 9	6
M	M	2	0 00	E	9 9	6
M	M	2	0 0 0	EEEE	9999	6666
M	M	2	00 0	E	9	6 6
M	M	2	0 0	E	9	6 6
M	M	22222	000	EEEE	999	666

LL	FFFFFFFFFFFF	BBBBBBBBBB	RRRRRRRRR		
LL	FFFFFFFFFFFF	BBBBBBBBBB	RRRRRRRRR		
LL	FF	BB	BB	RR	RR
LL	FF	BB	BB	RR	RR
LL	FF	BB	BB	RR	RR
LL	FF	BB	BB	RR	RR
LL	FFFFFFFFFF	BBBBBBBBBB	RRRRRRRRR		
LL	FFFFFFFFFF	BBBBBBBBBB	RRRRRRRRR		
LL	FF	BB	BB	RR	RR
LL	FF	BB	BB	RR	RR
LL	FF	BB	BB	RR	RR
LL	FF	BB	BB	RR	RR
LLLLLLLLLLLL	FF	BBBBBBBBBB	RR	RR	
LLLLLLLLLLLL	FF	BBBBBBBBBB	RR	RR	

	PPPPPPPP	RRRRRRRR	TTTTTTTTTT	;;;	222222			
	PPPPPPPP	RRRRRRRR	TTTTTTTTTT	;;;	222222			
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	PP	PP	RR	RR	TT	;;;	22	22
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....	PP	RR	RR	TT	;;		22	
....	PP	RR	RR	TT	;;		22	
....	PP	RR	RR	TT	;;		2222222222	
....	PP	RR	RR	TT	;;		2222222222	

\*File HSC000\$DUA9:[M20.DACKO SG.VMS.WEIGHT]LFBR.PRT;2 (1422,51,2), last revised on 9-MAR-1987 09:31, is a 5-block sequential file owned by UIC [M20,DACKO\_SG]. The records are variable length with implied (CR) carriage control. The longest record is 65 bytes.

Job LFBR (1358) queued to LN on 8-APR-1987 14:08 by user M20E96, UIC  
[M20,DACKO SG], under account M22 at priority 100, started on printer  
VENUS\$TXM6: on 8-APR-1987 14:08 from queue LNSYS.

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LFBR  
 TOTAL WEIGHT = 3870.15 ← RECOIL WEIGHT  
 C.G. X COORD (IN) = -.274826  
 C.G. Y COORD (IN) = -.119819  
 C.G. Z COORD (IN) = 199.476  
 JYZ (FT-LB-S<sup>2</sup>) = 35568.8  
 JXY (FT-LB-S<sup>2</sup>) = 3.24387  
 JXZ (FT-LB-S<sup>2</sup>) = 35571

DESCRIPTION	WEIGHT	X	Y	Z
5725	5	-13.5	10.88	118
5726	1	-11.5	1.25	105.48
5727	1	-4.25	2.5	105.48
5728	8.76	5	8.75	216.27
5766	181	0	-1.8	366.7
5781.01	26.8	0	0	128.747
5781.02	16.82	0	0	164.747
5781.03	19.44	0	0	200.057
5781.04	22.77	0	0	237.747
5781.05	27.66	0	0	340.997
5782	12.33	0	0	214.45
5786	1	0	4.03	349.8
5787	24	0	0	347.8
5788	24.67	0	0	189.01
5789	495	-2	0	113.2
5802	45	-2	-1	105
5816	92.15	0	0	188.13
5947	91.22	0	0	178.125
5948	91.5	0	0	178.125
5954	3.652	0	0	120.623
5955	5.842	0	0	118.807
5963	86.43	7.38	-2.72	234.577
5964	79.11	-7.38	0	234.577
5965	.17	3.62	6.28	120.371
5966	.33	3.62	6.28	120.8
5967	1.06	0	0	121.25
5968	4.78	0	0	214.45
5969	7.4	0	0	214.43
6002.01	.05	0	4	349
6002.02	6.36	0	0	214.457
6002.02	6.25	0	0	214.457
6002.03	.6	0	0	121.25
6033	1	0	0	207.13
9999	2480	0	0	203.857

4

M	M	222	000	EEEE	999	666
MM	MM	2 2	0 0	E	9 9	6
M M	M	2	0 00	E	9 9	6
M	M	2	0 0 0	EEEE	9999	6666
M	M	2	00 0	E	9	6
M	M	2	0 0	E	9	6
M	M	22222	000	EEEE	999	666

LL	FFFFFFFFFFFF	TTTTTTTTTTTT	EEEEEEEEEEEE
LL	FFFFFFFFFFFF	TTTTTTTTTTTT	EEEEEEEEEEEE
LL	FF	TT	EE
LL	FF	TT	EE
LL	FF	TT	EE
LL	FF	TT	EE
LL	FFFFFFFFFF	TT	EEEEEEEEEE
LL	FFFFFFFFFF	TT	EEEEEEEEEE
LL	FF	TT	EE
LL	FF	TT	EE
LL	FF	TT	EE
LL	FF	TT	EE
LLLLLLLLLLLL	FF	TT	EEEEEEEEEEEE
LLLLLLLLLLLL	FF	TT	EEEEEEEEEEEE

	PPPPPPPP	RRRRRRRR	TTTTTTTTTT	;;;;	5555555555		
	PPPPPPPP	RRRRRRRR	TTTTTTTTTT	;;;;	5555555555		
	PP	PP	RR	RR	TT	;;;;	55
	PP	PP	RR	RR	TT	;;;;	55
	PP	PP	RR	RR	TT		555555
	PP	PP	RR	RR	TT		555555
	PPPPPPPP	RRRRRRRR	TT	;;;;		55	
	PPPPPPPP	RRRRRRRR	TT	;;;;		55	
	PP	RR	RR	TT	;;;;	55	
	PP	RR	RR	TT	;;;;	55	
....	PP	RR	RR	TT	;;	55	55
....	PP	RR	RR	TT	;;	55	55
....	PP	RR	RR	TT	;;	555555	
....	PP	RR	RR	TT	;;	555555	

File HSC000\$DUA9:[M20.DACKO SG.VMS.WEIGHT]LFTE.PRT;5 (2432,1,2), last revised on 9-MAR-1987 09:16, is a 20 block sequential file owned by UIC [M20,DACKO SG]. The records are variable length with implied (CR) carriage control. The longest record is 65 bytes.

Job LFTE (1359) queued to LN on 8-APR-1987 14:08 by user M20E96, UIC  
[M20,DACKO SG], under account M22 at priority 100, started on printer  
VENUS\$TXM6: on 8-APR-1987 14:08 from queue LNSYS.

LFTE

TOTAL WEIGHT = 2478.3

C.G. X COORD (IN) = .526638

C.G. Y COORD (IN) = 2.89592

C.G. Z COORD (IN) = 161.457

JYZ (FT-LB-S<sup>2</sup>) = 155.3.8

JXY (FT-LB-S<sup>2</sup>) = 51.5709

JXZ (FT-LB-S<sup>2</sup>) = 15485.9

DESCRIPTION	WEIGHT	X	Y	Z
5712	135	0	-.72	199.08
5713	135	0	-.72	199.08
5716	44	0	29.87	34.13
5718	130	12.5	1.75	181.5
5719	130	-12.5	1.75	181.5
5720	166	2.5	21.75	179
5728	10.5	5	8.75	169
5729	59.5	0	10.5	135.66
5760	2.5	0	-8.5	242.25
5761	1	0	-8.5	242.25
5763	20.13	0	-8.5	242.25
5764	20	0	-8.5	242.25
5771	.37	0	-15.875	173.75
5772	3.42	0	-14.5	150.55
5774	.63	0	-14.5	173.75
5775	.16	0	-14.25	173.75
5776	2.7	0	-14.5	173.75
5777	2.78	0	-14.5	171.58
5779	1.8	0	-8.5	242.25
5780	22.75	0	-13.46	158.83
5790	5.68	0	-16.31	173.75
5831	414	0	.526	93.518
5863	2.2	0	1.031	35
5864	3.34	0	1.031	35
5865	2.5	0	1.031	35
5892	2	16.5	14.25	240
5893	2	16.5	7.25	240
5894.01	1	19	14.25	236
5894.02	2	-16.5	14.25	240
5895	2	-16.5	7.25	240
5896	2	0	0	236
5900	15	14.25	0	28
5902	7	5.81	10.625	130
5912	19.2	-.22	0	127
5913	2.5	6.062	6.25	127
5914	2	13.875	9.375	127
5915	2.5	0	0	236
5916	2.5	6.5	-8	127
5917	1.5	7.25	5.125	127
5918	1.5	7.25	5.125	127
5921	1	0	0	236
5922	12	5.84	-2.015	236
5923	2	0	0	127
5925	18	0	12.75	65
5943	220	0	1.528	127
5944	250	0	0	236
5945	85.62	0	0	182
5949	14.6	0	0	182
5950	21.8	0	0	182
5951	4.95	0	0	235
5952	5.16	0	0	124.15
5959	1.04	0	-12	127

5960	2.07	0	1.625	127
5961	3.45	0	1.625	127
5971	2	0	0	236
5973	.106	0	2.75	123.875
5975	85.46	0	0	182
5976	2	0	0	236
5977	2	0	0	236
5978	2	7	11.44	127
5979	2	7	11.44	127
5980	2	-10	10.56	127
6002.68	1	0	16	236
6002.69	1	0	0	239
6002.7	1.26	0	-11.75	232.5
6002.71	.25	0	-10.25	233.88
6002.72	1.39	0	-10.25	235.12
6002.74	.11	0	17.12	232.5
6002.75	.19	0	16.5	235
6002.76	.11	0	14.5	234
6002.77	.04	0	15.12	232.5
6002.78	5.8	0	-8.5	241.5
6002.79	.27	0	16.4	102
6002.8	.28	0	-10.75	127
6002.81	.14	0	15.5	127
6002.82	.28	14.25	0	28
6002.83	.2	0	-14	14.47
6002.84	.46	0	1.031	35
6002.85	.36	0	1.031	35
6002.86	.18	0	-14.5	150.8
6002.87	.68	0	-14.5	170.75
6002.88	.1	0	-15	173.75
6002.89	.07	0	-15	173.75
6002.9	.19	0	-15	172.75
6002.9	.19	0	-15	173.75
6003.45	.03	0	-11.94	232.5
6003.46	.03	0	15.18	232.5
6003.47	.25	0	-8.5	242.25
6003.48	.1	0	15.78	102
6003.49	.16	0	1.625	127
6003.5	.3	0	1.031	35
6003.51	.07	0	-4.125	140.75
6003.52	.11	0	-14.5	150.8
6003.53	.2	0	-14.5	170.75
6004.01	8	0	-8.5	242.25
6005.51	.07	0	-13.56	232.5
6005.52	.03	0	-10.25	238.5
6005.53	.08	0	-11.25	235.12
6005.54	.02	0	-12.12	232.5
6005.55	.05	0	17.38	232.5
6005.56	.03	0	16.25	235
6005.57	.03	0	15.25	232.5
6005.58	.04	0	15.93	102
6005.59	.04	0	1.625	127
6005.6	.04	14.25	0	28
6005.61	.04	0	-14	14.47
6005.62	.04	0	-4.125	140.75
6005.63	.12	0	-14.5	150.8
6005.64	.18	0	-14.5	170.75
6006.34	.27	0	-11.81	232.5
6006.35	.01	0	-2.75	149.25
6006.36	.8	0	-14.5	173.75
6006.37	.422	0	-14.5	173.75
6007.15	1.25	0	0	240



6007.15	.04	0	-2.75	149.75
6009.06	.08	0	-12.38	232.5
6009.07	.08	0	15.75	232.5
5009.08	.19	0	1.625	127
6010.11	.02	0	30.02	-44.75
6014.01	.01	0	-13	232.5
6026.03	.84	0	30.02	-44.75
7000	7.5	0	16	236
7001	5	0	0	240
7002	1.23	0	-13.25	232.5
7003	.88	0	-12.62	232.5
7004	.43	0	-12.18	232.5
7005	8.9	0	-10.62	234.25
7006	.77	0	16.5	232.5
7007	.7	0	-12	232.5
7008	.18	0	14.88	232.5
7009	.05	0	15.5	232.5
7010	.02	0	-12.12	232.5
7011	2.3	0	16.62	234
7012	1.41	0	15.88	232.5
7013	.73	0	15.44	232.5
7014	1.17	0	15.56	233
7015	32	0	24.23	60.54
7016	8.48	0	17.2	101
7017	1.19	0	15.375	127
7018	10	0	-14	14.47
7019	.25	0	-4.125	140.75
7020	.72	0	-4.16	157.18
7021	.12	0	0	166.2
7022	.41	0	-15.4	173.75
7023	.7	0	-14.5	174.5
7024	.8	0	-10.44	127
9994	25	15	8	127
9995	36.12	0	0	181.5
9997	170.4	0	0	181.5
9998	11.97	2.5	21.75	175
9999	.2	0	-8.5	245.56
9999	.13	0	1.031	35

7

IIIIIIIIII  
IIIIIIIIII  
IIIIIIIIII

8

PPPPPPPP	RRRRRRRR	TTTTTTTTTT	;;;	11		
PPPPPPPP	RRRRRRRR	TTTTTTTTTT	;;;	11		
PP	PP	RR	RR	TT	;;;	1111
PP	PP	RR	RR	TT	;;;	1111
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PP	RR	RR	TT	;;	111111	

Job LFTS (1360) queued to LN on 8-APR-1987 14:08 by user M20E96, UIC [M20,DACKO SG], under account M22 at priority 100, started on printer VENUS\$TXM6: on 8-APR-1987 14:08 from queue LNSYS.

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IIIIIIIIII

LFTS

TOTAL WEIGHT = 2551.55

C.G. X COORD (IN) = 0

C.G. Y COORD (IN) = -3.58506

C.G. Z COORD (IN) = 26.9763

JYZ (FT-LB-S<sup>2</sup>) = 784.343

JXY (FT-LB-S<sup>2</sup>) = 13.6123

JXZ (FT-LB-S<sup>2</sup>) = 770.731

DESCRIPTION

WEIGHT

X

Y

Z

9900

1325.72

0

-6.9

51.92

9901

1225.83

0

0

0

**DESCRIPTION:    COMPUTER FILE INVENTORY**

**STATUS:**    A complete listing of all computer programs and data files used in performing dynamic analysis is included in this section. Individual programs and files are described in the sections of this volume where appropriate.

Some files listed that are shown in S. Dacko's directory are old or not applicable to LTHD work and should be ignored.

**AUTHOR:**    Scott Dacko, John Green, Jeff Ireland

TO: SCOTT DACKO  
FROM: Jim Dillon

SYSTEM : VAX-8600 (VENUS)

VOLUME NAME : A026T1

SUBJECT: VOLUNTARY FILE ARCHIVING

Save set VAE870318.BCK created on 18-MAR-1987 13:40:09.13

[M20.DACKO\_SG.VMS]120K.OUT;2  
[M20.DACKO\_SG.VMS]62500.OUT;3  
[M20.DACKO\_SG.VMS]62500C.OUT;2  
[M20.DACKO\_SG.VMS]70000.OUT;2  
[M20.DACKO\_SG.VMS]70K0.OUT;2  
[M20.DACKO\_SG.VMS]70K10.OUT;2  
[M20.DACKO\_SG.VMS]70K20.OUT;2  
[M20.DACKO\_SG.VMS]70K30.OUT;2  
[M20.DACKO\_SG.VMS]70K40.OUT;2  
[M20.DACKO\_SG.VMS]79000.OUT;3  
[M20.DACKO\_SG.VMS]79000C.OUT;2  
[M20.DACKO\_SG.VMS]90000.OUT;2  
[M20.DACKO\_SG.VMS]CURRENT.GRG;8  
[M20.DACKO\_SG.VMS]EHGD.GRG;1  
[M20.DACKO\_SG.VMS]EHSIX.GRS;2  
[M20.DACKO\_SG.VMS]ENERGY.EXE;45  
[M20.DACKO\_SG.VMS]ENERGY.FOR;60  
[M20.DACKO\_SG.VMS]ENERGY.OBJ;45  
[M20.DACKO\_SG.VMS]ENGHOURS.GKD;2  
[M20.DACKO\_SG.VMS]ENGHOURS.GKI;2  
[M20.DACKO\_SG.VMS]FC.GKD;4  
[M20.DACKO\_SG.VMS]FC.GKI;4  
[M20.DACKO\_SG.VMS]FCG.GRG;1  
[M20.DACKO\_SG.VMS]FCGS.GRS;1  
[M20.DACKO\_SG.VMS]GLOBAL.COM;27  
[M20.DACKO\_SG.VMS]GLOBAL.COM;26  
[M20.DACKO\_SG.VMS]HCP.BAS;12  
[M20.DACKO\_SG.VMS]HCP.EXE;7  
[M20.DACKO\_SG.VMS]HCP.OBJ;7  
[M20.DACKO\_SG.VMS]HCP3.SAT;2  
[M20.DACKO\_SG.VMS]HCP3.DAT;2  
[M20.DACKO\_SG.VMS]HCPBACKUP.BAS;2  
[M20.DACKO\_SG.VMS]INTRO.TXT;4  
[M20.DACKO\_SG.VMS]LFTDRIG.DAT;1  
[M20.DACKO\_SG.VMS]LINKRESET.DAT;1  
[M20.DACKO\_SG.VMS]LOADARM.EXE;1  
[M20.DACKO\_SG.VMS]MBT.EXE;5  
[M20.DACKO\_SG.VMS]MBT.FOR;6  
[M20.DACKO\_SG.VMS]MBT.OBJ;5  
[M20.DACKO\_SG.VMS]MCTIUM3M.DAT;3  
[M20.DACKO\_SG.VMS]MUZLERKETEMP.EXE;4  
[M20.DACKO\_SG.VMS]MUZLERKETEMP.FOR;6

DIRECTORY (870318)

[M20.DACKO\_SG.VMS]MUZLBRKETEMP.LIS;4  
[M20.DACKO\_SG.VMS]MUZLBRKETEMP.MAP;3  
[M20.DACKO\_SG.VMS]MUZLBRKETEMP.OBJ;4  
[M20.DACKO\_SG.VMS]OUT.OUT;4  
[M20.DACKO\_SG.VMS]OUT.TJL;1  
[M20.DACKO\_SG.VMS]PROF.DAT;23  
[M20.DACKO\_SG.VMS]RECHOP.DAT;1  
[M20.DACKO\_SG.VMS]RECOIL.BAS;3  
[M20.DACKO\_SG.VMS]RECOIL.EXE;2  
[M20.DACKO\_SG.VMS]RECOIL.OBJ;2  
[M20.DACKO\_SG.VMS]RECPROF4.GKD;2  
[M20.DACKO\_SG.VMS]RECPROF4.GRI;2  
[M20.DACKO\_SG.VMS]RECPROFS.GKD;3  
[M20.DACKO\_SG.VMS]RECPROFS.GRI;3  
[M20.DACKO\_SG.VMS]RESET.LST;1  
[M20.DACKO\_SG.VMS]RPG.GFG;1  
[M20.DACKO\_SG.VMS]RPGS.GFS;1  
[M20.DACKO\_SG.VMS]SETHUST.LOG;3  
[M20.DACKO\_SG.VMS]TEMP1.OUT;1  
[M20.DACKO\_SG.VMS]TEMP2.OUT;1  
[M20.DACKO\_SG.VMS]TEMP3.OUT;1  
[M20.DACKO\_SG.VMS]WTDISTNW.BAS;1  
[M20.DACKO\_SG.VMS]WTDISTNW.EXE;1  
[M20.DACKO\_SG.VMS]WTDISTNW.OBJ;1  
[M20.DACKO\_SG.VMS]WTDISTW.BAS;2  
[M20.DACKO\_SG.VMS]WTDISTW.EXE;1  
[M20.DACKO\_SG.VMS]WTDISTW.OBJ;1

TO: JOHN GREEN

FROM: Jim Dillon

SYSTEM : VAX 8500 (VENUS)

VOLUME NAME : A  $\phi$ 26 T1

SUBJECT: VOLUNTARY FILE ARCHIVING

Save set VARE70218.BCK created on 18-MAR-1987 13:30:33.24

[M90.GREEN\_JE.VMS.LTHD]DYNFLOW.GRL;42  
[M90.GREEN\_JE.VMS.LTHD]DYNPRESS.GRL;42  
[M90.GREEN\_JE.VMS.LTHD]DYNTHETA.GRL;42  
[M90.GREEN\_JE.VMS.LTHD]ELEVATION.BAS;52  
[M90.GREEN\_JE.VMS.LTHD]ELEVATION.SAV;36  
[M90.GREEN\_JE.VMS.LTHD]GRAPH.GRG;154  
[M90.GREEN\_JE.VMS.LTHD]HELIUM.DAT;1  
[M90.GREEN\_JE.VMS.LTHD]NITROGEN.DAT;1  
[M90.GREEN\_JE.VMS.LTHD]NITROGEN.ENG;1  
[M90.GREEN\_JE.VMS.LTHD]RESET.PRT;1  
[M90.GREEN\_JE.VMS.LTHD]SIMULATION.P01;2  
[M90.GREEN\_JE.VMS.LTHD]SIMULATION.P02;2  
[M90.GREEN\_JE.VMS.LTHD]SIMULATION.P03;2  
[M90.GREEN\_JE.VMS.LTHD]SIMULATION.P04;1  
[M90.GREEN\_JE.VMS.LTHD]SIMULATION.P05;1  
[M90.GREEN\_JE.VMS.LTHD]SIMULATION.P06;1  
[M90.GREEN\_JE.VMS.LTHD]SIMULATION.P07;1  
[M90.GREEN\_JE.VMS.LTHD]SIMULATION.P08;1  
[M90.GREEN\_JE.VMS.LTHD]SIMULATION.P09;1  
[M90.GREEN\_JE.VMS.LTHD]SIMULATION.P10;2  
[M90.GREEN\_JE.VMS.LTHD]SIMULATION.P11;3  
[M90.GREEN\_JE.VMS.LTHD]SIMULATION.P12;1  
[M90.GREEN\_JE.VMS.LTHD]STATIC.GRC;6  
[M90.GREEN\_JE.VMS.LTHD]STATIC.GRI;6  
[M90.GREEN\_JE.VMS.LTHD]STATIC.GRL;75  
[M90.GREEN\_JE.VMS.LTHD]STATIC.GRS;6

TO: Jeff IRELAND

FROM: Jim DILLON

SYSTEM : VAX 8600 (VENUS)

VOLUME NAME : Aφ26 T1

SUBJECT: VOLUNTARY FILE ARCHIVING

Save set VAF270318.BCK created on 19-1AR-1987 13:40:09.13

[M20.IRELAND\_JV.VMS]ADDDAT.FOR;3  
[M20.IRELAND\_JV.VMS]EN2.FOR;1  
[M20.IRELAND\_JV.VMS]ENERGY.FOR;1  
[M20.IRELAND\_JV.VMS]GLOBAL.COM;1  
[M20.IRELAND\_JV.VMS]HCP.BAT;1  
[M20.IRELAND\_JV.VMS]HCP.DAT;1  
[M20.IRELAND\_JV.VMS]JUR2.FOR;34  
[M20.IRELAND\_JV.VMS]JUR3.FOR;1  
[M20.IRELAND\_JV.VMS]JURIF1.FOR;5  
[M20.IRELAND\_JV.VMS]JURIFICE.FOR;1  
[M20.IRELAND\_JV.VMS]JUT.DAT;13  
[M20.IRELAND\_JV.VMS]JRA2.FOR;1  
[M20.IRELAND\_JV.VMS]JRAM.FOR;1  
[M20.IRELAND\_JV.VMS]JTEST.FOR;3  
[M20.IRELAND\_JV.VMS]JTC2.FOR;1  
[M20.IRELAND\_JV.VMS]JTCQUE.FOR;7  
[M20.IRELAND\_JV.VMS]JXAL.DAT;4



PART NUMBER: 12585725

C/100

DESCRIPTION: BREECH ACTUATOR

STATUS:

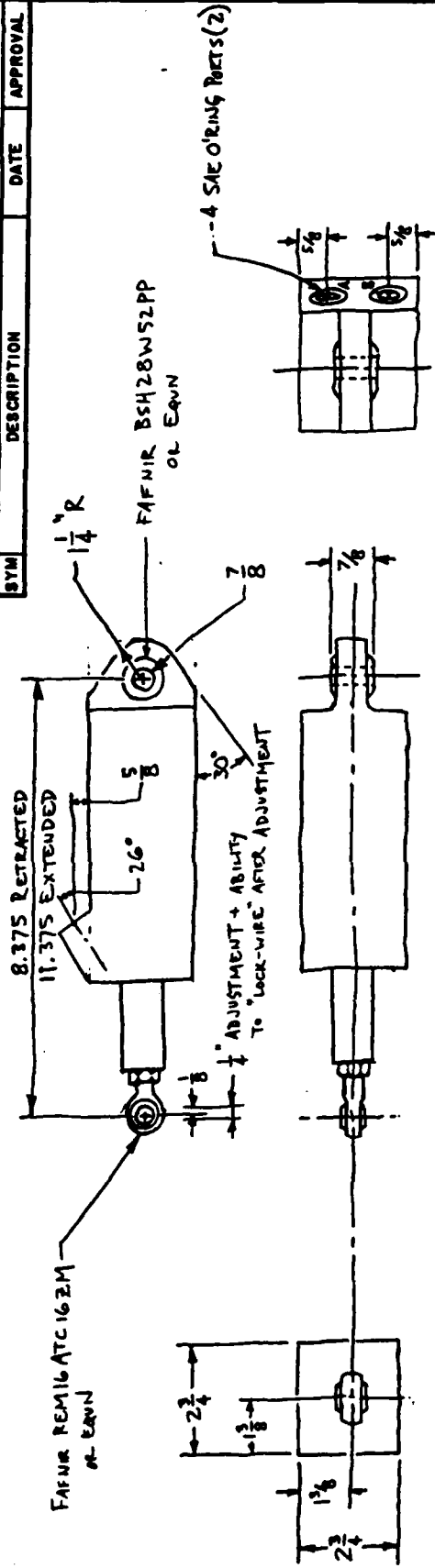
The breech actuation system consists of a hydraulic actuator, a mounting bracket, a modified breech crank, along with hoses, fittings and connectors. Layouts of this can be found in in the TDP, Cannon Assembly.

Breech actuator. A preliminary breech actuator drawing (TDP, Dwg. 12585725) showing all critical dimensions has been prepared by FMC and is to be finalized by York. Actuator size and pressure requirements have been determined based on torque data from Benet tests as well as FMC time cycle needs. Along with the actuator is a pilot-operated check to prevent accidental actuator retract (and breech closure) with hose failure. Also the actuator can only open the breech if the tube is in load position to prevent interference and damage with the cradle in other tube positions.

Breech crank. A modified Benet Crank drawing has been finalized by FMC and provided to Benet for manufacture. The non-functional Benet Crank ears are specified to be cut away to save weight.

Hoses, fittings and connectors. All hoses, fittings and connectors have been finalized and are specified on FMC technical data package gang-sheets. Layouts of these components can be found in the TDP, Cannon Assembly.

AUTHORS: Joe Turek, Jeff Ireland, Scott Dacko, Bart Anderson



B	A	Position
PRESSURE	RETURN	RETRACTED
RETURN	RETURN	EXTENDED

$\text{OPEN} = \frac{10339}{2507} = 4.12$

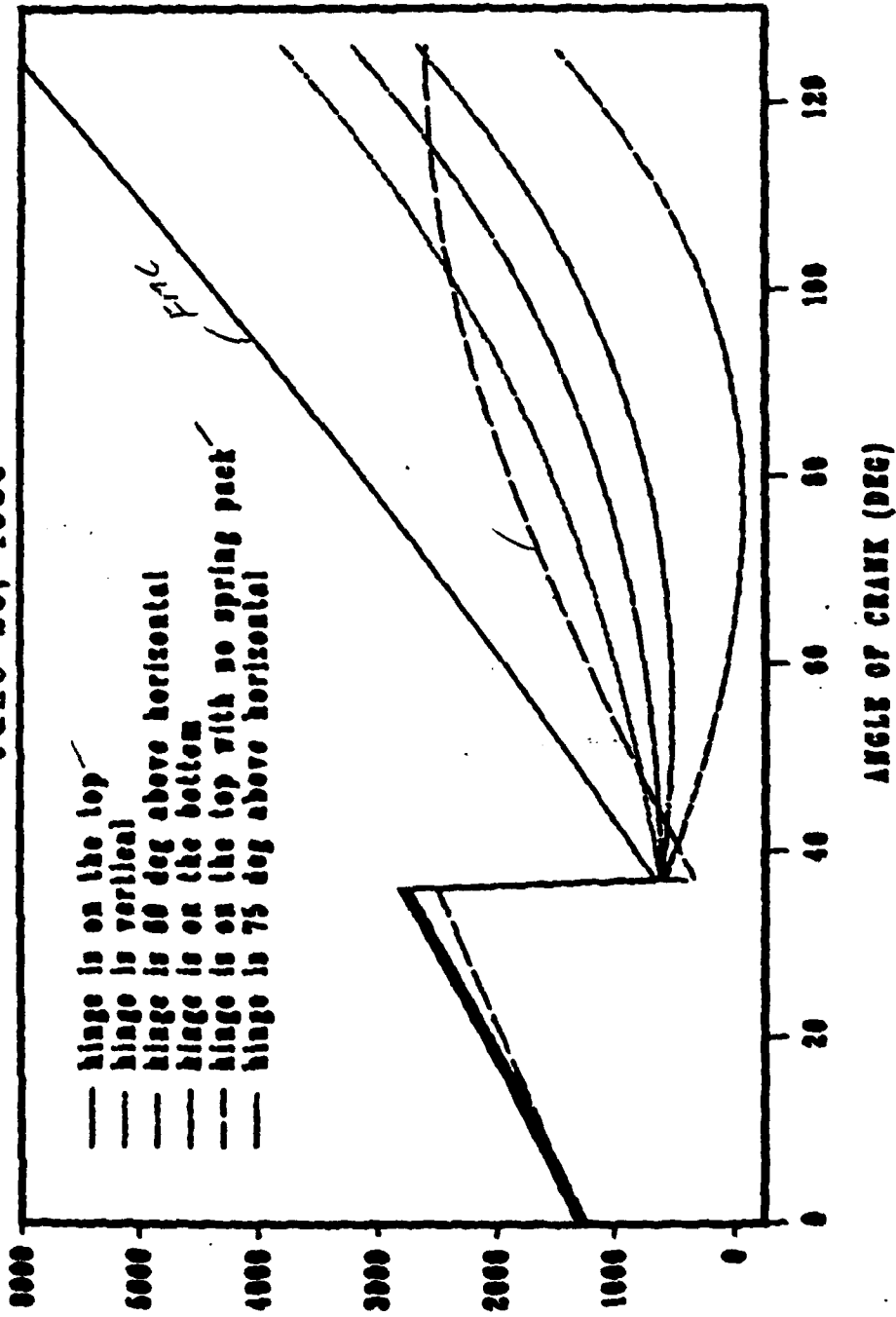
**PART NO.**

PART NO.		U.S. ARMY ARMAMENT RESEARCH, DEVELOPMENT AND ENGINEERING CENTER DOVER, NEW JERSEY 07801-9001	
BREECH ACTUATOR			
SIZE	F2CM NO.	T-1258 5725 / B	
B	19200		
SCALE	UNIT WT.	SHEET	
ORIGINAL DATE OF DRAWING			
DO NOT SCALE DRAWING			
UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES			
TOLERANCES ON DECIMALS & FRACTIONS & ANGLES &			
THIRD ANGLE PROJECTION			
MECHANICAL PROPERTIES			
YP			
TS			
EL2			
RA			
BH			
PH			
NEXT ASSY		USED ON	
APPLICATION			

SM-CAR FORM 66, 1 JUN 66(TEMP) REPLACES ARRADCOM FORM 66, AUG 77, WHICH MAY BE USED UNTIL EXHAUSTED

# TORQUE REQUIRED TO OPEN BREECH

June 26, 1986



(47-11) 20201

NAVY

Northern Ordnance Division  
 Fort Monmouth

BREECH MECHANISM

OLD

3

DESCRIPTION	W (lbf)	r (in)	Mr <sup>2</sup> (lbf-in-sec <sup>2</sup> )	I <sub>0</sub> (lbf-in-sec <sup>2</sup> )
CARRIER	79.0	50	5.117	.512
BLOCK	107.0	10.0	27.720	2.772
GEAR SECTOR	6.0	10.0	1.554	.155
AUTO PRIMER	30.0	13.5	14.164	1.416
OBTURATOR PAD	26.0	10.0	6.736	.674
SPRING PACK	10.0	0.0	0.0	} .135
PIVOT SHAFT	22.0	0.0	0.0	
			55.291	5.664

$$I_{TOTAL} = (55.291 + 5.664) \text{ lbf-in-sec}^2$$

$$= 60.955 \text{ lbf-in-sec}^2$$

$$T_{OPEN_{AVE}} \approx 2000.0 \text{ lbf-in}$$

$$\ddot{\theta} = A \cos(\omega t)$$

$$\dot{\theta} = (A\omega) \sin(\omega t) + c_1 \quad t=0, \dot{\theta}=0, c_1=0$$

$$\theta = -(A/\omega^2) \cos(\omega t) + c_2 \quad t=0, \theta=0, c_2 = A/\omega^2$$

$$\theta = (A/\omega^2) (1 - \cos(\omega t))$$

FORD PROPERT DISTANCE DIVISION

FORCE INPUT AT 1.0 IN RADIUS

$$F_{IN} = (2000.0 \text{ lbf} + 2865.0 \text{ lbf-in}) / 1.0 \text{ in} \\ = 4865.0 \text{ lbf}$$

$$F_{PISTON} = 4865.0 \text{ lbf} (4.75 / 2.75) = 8403.0 \text{ lbf}$$

$$\pi/4 (D_p^2 - (1.0 \text{ in})^2) (2450 \text{ lbf/in}^2) = 8403.0 \text{ lbf}$$

$$D_p = 2.375 \text{ in}$$

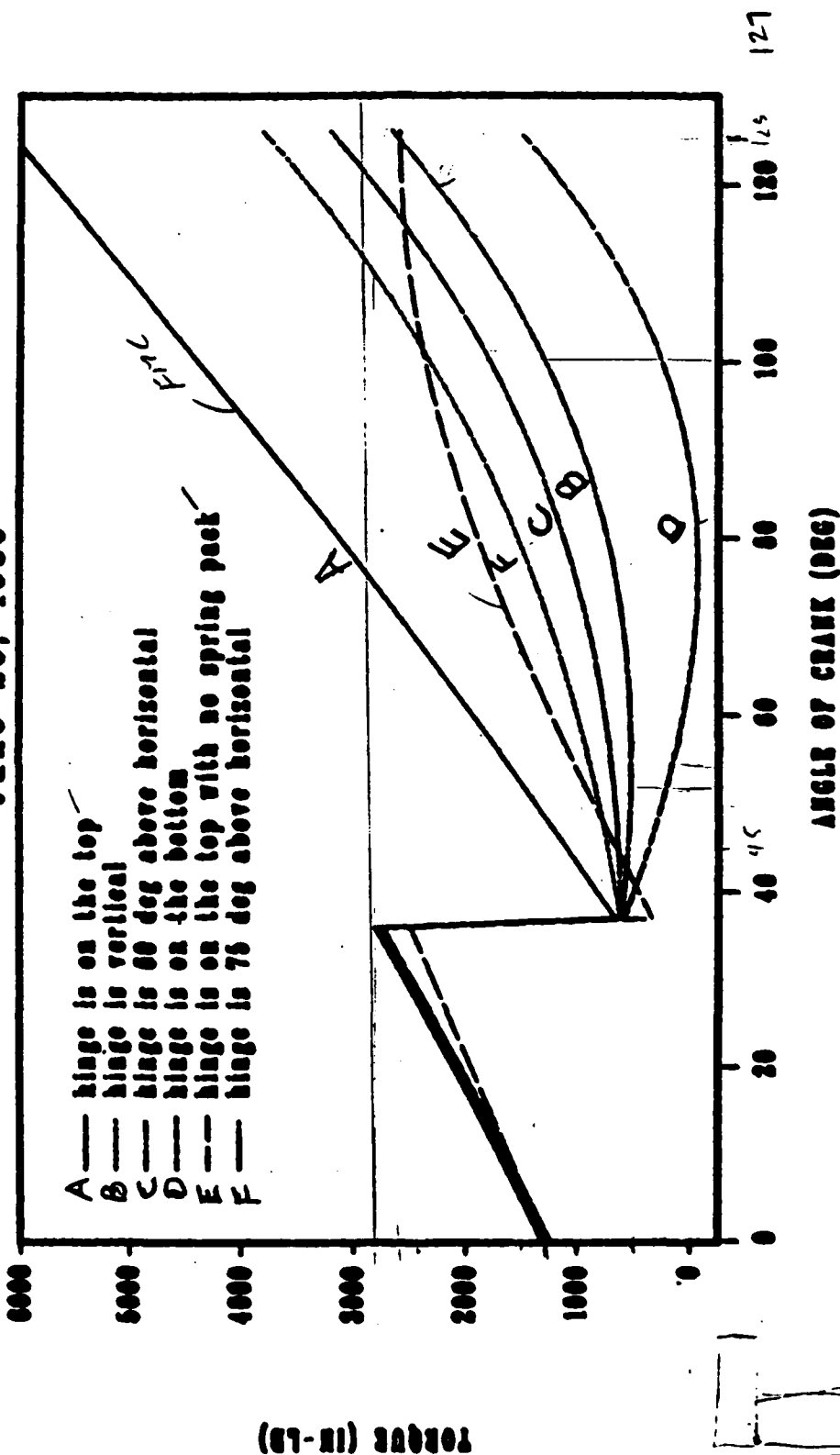
$$D_R = 1.000 \text{ in}$$

$$\text{STROKE} = 2.250 \text{ in}$$

37° TO ROTATE BREACH 45° BENET 8611.1  
 90° TO SWING BREACH DOOR OPEN 90°  
 127°

# TORQUE REQUIRED TO OPEN BREACH

June 26, 1986



6

FMC

Northern Ordnance Division  
Minneapolis

ACTUAL WEIGHT M185 BREECH 7/18/8

JEFF IRELAND  
PAUL MELQUIST

BREECH BLOCK 107 LB (3)

CARRIER (w/SPRINGS  
RACK) 79 LB (2)

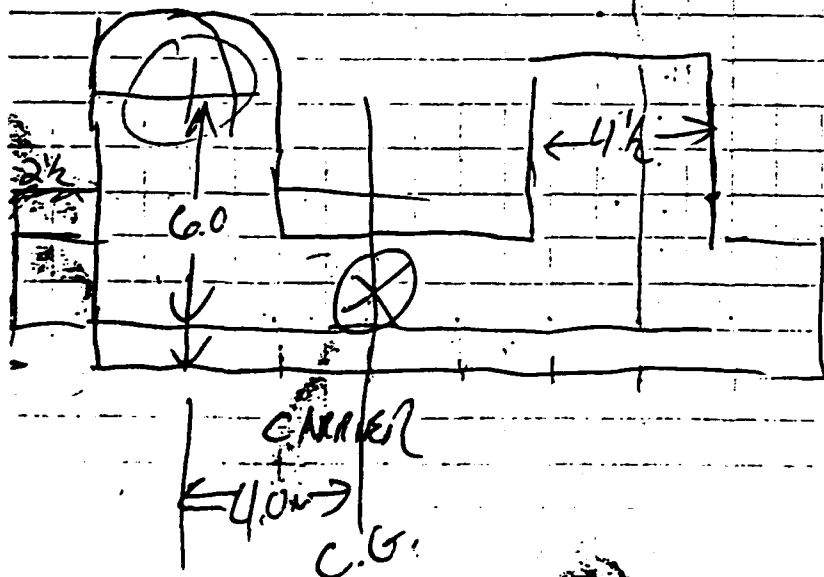
GEAR SECTOR 6 LB (1)

M109 FIRING MECH  
CARRIER BLOCK 10 LB (3)REPLACE WITH FIRING  
MECHANISMOBTURATOR PAD 26 LB (3)  
(MUSHROOM w/NUT)

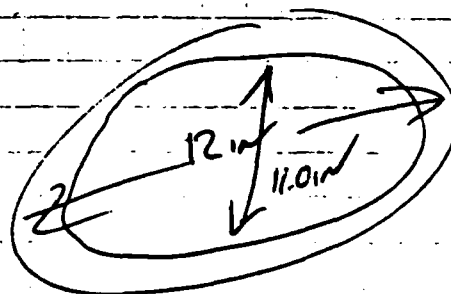
SPRING PACK (w/ADJUSTOR) 10 LB (1)

PIVOT SHAFT (CRANK) 22 LB (1)

PIVOT SHAFT TO BREECH C/L 10.0 IN

PIVOT SHAFT DIA. O.D. 3 IN  
I.D. 2 IN  
LENGTH = 13.10 INLOW THROW ON  
CRANK

BREECH



ROUGH SIZING

$$\theta = 70^\circ = \frac{7\pi}{18} \quad \text{AT } t = .35 \text{ SEC}$$

$$(A/\omega^2) = \frac{7\pi}{18}$$

$$\omega t = \pi/2$$

$$\omega = 4.488 \text{ RAD/SEC}$$

$$A = 24.608 \text{ RAD/SEC}^2$$

$\ddot{\theta}$  DECEL

$$\ddot{\theta}_{\text{MAX}} = A/\omega = 5.483 \text{ RAD/SEC} = 314.16^\circ/\text{SEC}$$

$$20^\circ = \frac{(314.16^\circ)}{2} t$$

$$t = .127 \text{ SEC}$$

$$\ddot{\theta}_{\text{DECEL}} = \frac{314.16^\circ/\text{SEC}}{.127 \text{ SEC}} = 2,473.7^\circ/\text{SEC}^2 = 43.174 \text{ RAD/SEC}^2$$



$$0 < \Delta < 37^\circ$$

TORQUE	$\Delta$
1250 in-lbf	$0^\circ$
2800 in-lbf	$37^\circ$

$$T = \frac{(2800 - 1250) \text{ in-lbf}}{37^\circ - 0^\circ} \Delta + 1250 \text{ in-lbf}$$

$$T = 41.891 \left( \frac{\text{in-lbf}}{\text{DEG}} \right) \Delta + 1250 \text{ in-lbf}$$

$$37^\circ < \Delta < 127^\circ$$

TORQUE	$\Delta$
500 in-lbf	$55^\circ$
2750 in-lbf	$127^\circ$

$$T = K (\Delta - 55^\circ)^2 + C$$

$$\Delta = 55^\circ \quad C = 500 \text{ in-lbf}$$

$$\Delta = 127^\circ \quad K = 1/2.304$$

$$T = [(\Delta - 55^\circ)^2 / 2.304 + 500] \text{ in-lbf}$$

1. CONTROL VALVE
2. LOAD POSITION VALVE
3. P.O. CHECK VALVE
4. INLET TO BREECH ACTUATOR
5. OUTLET OF BREECH ACTUATOR

$$V_p = 3.053 \text{ in/sec}$$

$$A_p = \pi/4 ((2.75 \text{ in})^2 - (1 \text{ in})^2) = 5.154 \text{ in}^2$$

$$Q_p = 15.735 \text{ in}^3/\text{sec}$$

PIPE LENGTH

1. 150 IN FROM BREECH ACTUATOR TO RESERVOIR

ASSUME  $3/8$  IN I.D.

2. 500 IN LENGTH TO BREECH ACTUATOR.

$$V_{\text{PIPE}} = \frac{15.735 \text{ in}^3/\text{sec}}{\pi/4 (.375 \text{ in})^2} = 142.468 \text{ in/sec}$$

$$Re = \frac{VD_H}{\nu} = \frac{142.468 \text{ in/sec} (.375 \text{ in})}{.8 \text{ in}^2/\text{sec}} = 66.782$$

$$f = 64/Re = .958$$

$$\frac{\Delta P}{L} = \frac{f}{D_E} \left( \frac{PV^2}{2g} \right) = \left( \frac{.958}{.375 \text{ in}} \right) \frac{(.0308 \text{ in}^3/\text{in}^3) (142.468 \text{ in/sec})^2}{2 (386.087 \text{ in/sec}^2)} = 2.069 \text{ PSI/IN}$$

ASSUME  $1/2$  IN I.D.

$$V_{\text{PIPE}} = \frac{15.735}{\pi/4 (1/2)^2} = 80.138 \text{ in/sec}$$

$$Re = \frac{80.138 (1/2)}{.8} = 50.086$$

$$f = 64/Re = 1.278$$

$$\frac{\Delta P}{L} = \left( \frac{1.278}{.5 \text{ in}} \right) \frac{(.0308) (80.138)^2}{2 (386.087)} = .655 \text{ PSI/IN}$$

375  
100  
7/16

BREECH MECHANISM

INERTIA WHILE BLOCK IS UNTHREADING

BREECH BLOCK	107.0 lbf	
GEAR SECTOR	60 lbf	$\gamma = 6.0$
OBTURATOR PAD	<u>260 lbf</u>	
	139.0 lbf	

$$I = \frac{1}{2} M r^2 = \frac{1}{2} (139 \text{ lbf} / 386 \text{ IN/SEC}^2) (6.0 \text{ IN})^2$$

$$I = 6.5 \text{ lbf-IN-SEC}^2$$

$$I = 60.955 \text{ lb}_f\text{-in-sec}^2$$

$$T_{OPEN} = 3000 \text{ lb}_f\text{-in}$$

$$I\ddot{\Theta} = F_p R_g - T_{OPEN}$$

$$F_p = \left[ P_a - \left( \frac{(A_p - A_r) \dot{X}}{115.5 A_{or}} \right)^2 \right] (A_p - A_r) - \left[ P_r + \left( \frac{A_r \dot{X}}{115.5 A_{or}} \right)^2 \right] A_p$$

$$\ddot{\Theta} = \ddot{X} / R_g$$

$$\text{STROKE} = \Theta_{max} R_g = 127^\circ (\pi/180^\circ) (R_g) \quad \Theta_{max} = 127^\circ$$

$$\text{STROKE} = 2.217 R_g$$

$$\left( \frac{I \ddot{X}}{R_g} \right) = \left[ \left[ P_a - \left( \frac{(A_p - A_r) \dot{X}}{115.5 A_{or}} \right)^2 \right] (A_p - A_r) - \left[ P_r + \left( \frac{A_r \dot{X}}{115.5 A_{or}} \right)^2 \right] A_p \right] R_g - T_{OPEN}$$

$$\frac{I \ddot{X}}{R_g^2} = (P_a(A_p - A_r) - P_r A_p - \frac{T_{OPEN}}{R_g}) - \left( \frac{\dot{X}}{115.5} \right)^2 \left[ \frac{(A_p - A_r)^3}{A_{or}^2} + \frac{A_r^3}{A_{or}^2} \right]$$

FOR ROUGH SIZING ASSUME  $P_a = 2250 \text{ PSI}$   $P_r = 500 \text{ PSI}$   $\dot{X} = 0$

$$\frac{1}{2} \ddot{X} t^2 = 2.217 R_g \quad t = .5 \text{ sec}$$

$$\ddot{X} = 17.733 R_g$$

$$\frac{I (17.733 R_g)}{R_g^2} = (P_a - P_r) A_p - P_a A_r - \frac{T_{OPEN}}{R_g}$$

$$\left( 17.733 \frac{I}{R_g} + \frac{T_{OPEN}}{R_g} + P_a A_r \right) / (P_a - P_r) = A_p$$

$$A_r = \pi (1.0)^2 / 4 = .7854 \text{ in}^2$$

$$R_g = 1.0 \text{ in}$$

$$A_p = 3.3417 \text{ in}^2$$

$$D_p = 2.063 \text{ in}$$

$$\text{USE } D_p = 2.125 \text{ in}$$

$$\ddot{x} = A \cos \omega t$$

$$\dot{x} = \frac{A}{\omega} \sin \omega t + C_1 \quad t=0, \dot{x}=0, C_1=0$$

$$x = -\frac{A}{\omega^2} \cos \omega t + C_2 \quad t=0, x=0$$

$$0 = -\frac{A}{\omega^2} + C_2$$

$$C_2 = A/\omega^2$$

$$x = A/\omega^2 (1 - \cos \omega t)$$

$$\dot{x} = (A/\omega) \sin \omega t$$

$$\ddot{x} = A \cos \omega t$$

$$t=0, \dot{x}=0, \ddot{x}=A$$

$$\ddot{x} = [P_a(A_p - A_R) - P_R A_p - T_{OPRN}/R_g] R_g^2 / I$$

$$A = \ddot{x} = 32.339 \text{ in/sec}^2$$

$$x = A/\omega^2 = 2.217 R_g$$

$$\omega = [A/(2.217 R_g)]^{1/2}$$

$$\omega = 3.819$$

$$P_a = 2250 \text{ PSI}$$

$$P_R = 350 \text{ PSI}$$

$$T_{OPRN} = 3000 \text{ lb-in}$$

$$R_g = 1.0 \text{ in}$$

$$I = 60.955 \text{ kg-m}^2$$

$$A_p = 3.5465 \text{ m}^2$$

$$A_R = .7854 \text{ m}^2$$

# BREACH ACT.

13

$$PSI \quad 7056 - 1252 = 5804$$

MIN SEAL FRIC  
AREA C46

MIN SEAL FRIC  
AREA C46

$$(3000 - 75) (2.125^2 - 1^2) \frac{\pi}{4} - (300 + 15) 2.125^2 \frac{\pi}{4}$$

$$= 6804$$

$$TORQUE 500 LBS \times 12 = 6000 \text{ IN LBS}$$

$$F = \frac{6000}{.75} = 8000 \text{ LBS OF FORCE}$$

$$A \quad 2.75 \text{ ROT} = 3.976$$

$$RTD \quad .745$$

$$H. \quad 3.19$$

$$A = \frac{F}{PSI} = \frac{8000}{3000} = 2.667$$

TO OPEN RETRACT

$$2\frac{1}{2} \text{ DIA W/ 1 ROT} = 2.76 = A$$

$$(3000 - 75) (2.125^2 - 1^2) \frac{\pi}{4} - (300 + 15) 2.125^2 \frac{\pi}{4} =$$

$$(2925) (3.5156) \frac{\pi}{4} - (315) (4.5156) \frac{\pi}{4}$$

$$4076$$

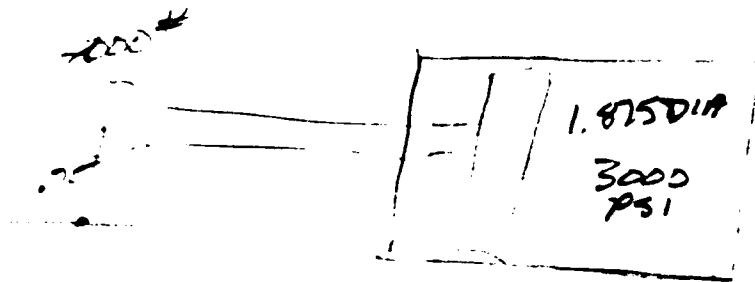
$$- 1117.16 = 6959$$

$$6959$$

$$\text{OPEN TORQUE} = 452.3$$

$$1117$$

$$5 = 1$$



$$A = 2.25 = 3.976$$

$$A = 1 = .785$$

$$3.19 \times 3000 \text{ PSI} = 9570$$

$$\begin{array}{r} 9570 \times 3000 \\ \hline 28710 \\ 3000 \end{array} = 9570$$

$$A = 2.667 = 8000 = @ 3000 \text{ PSI}$$

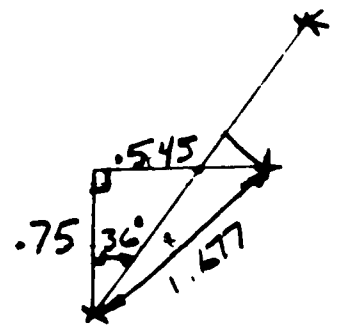
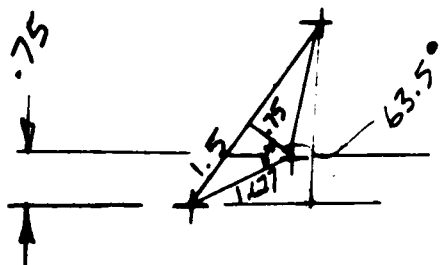
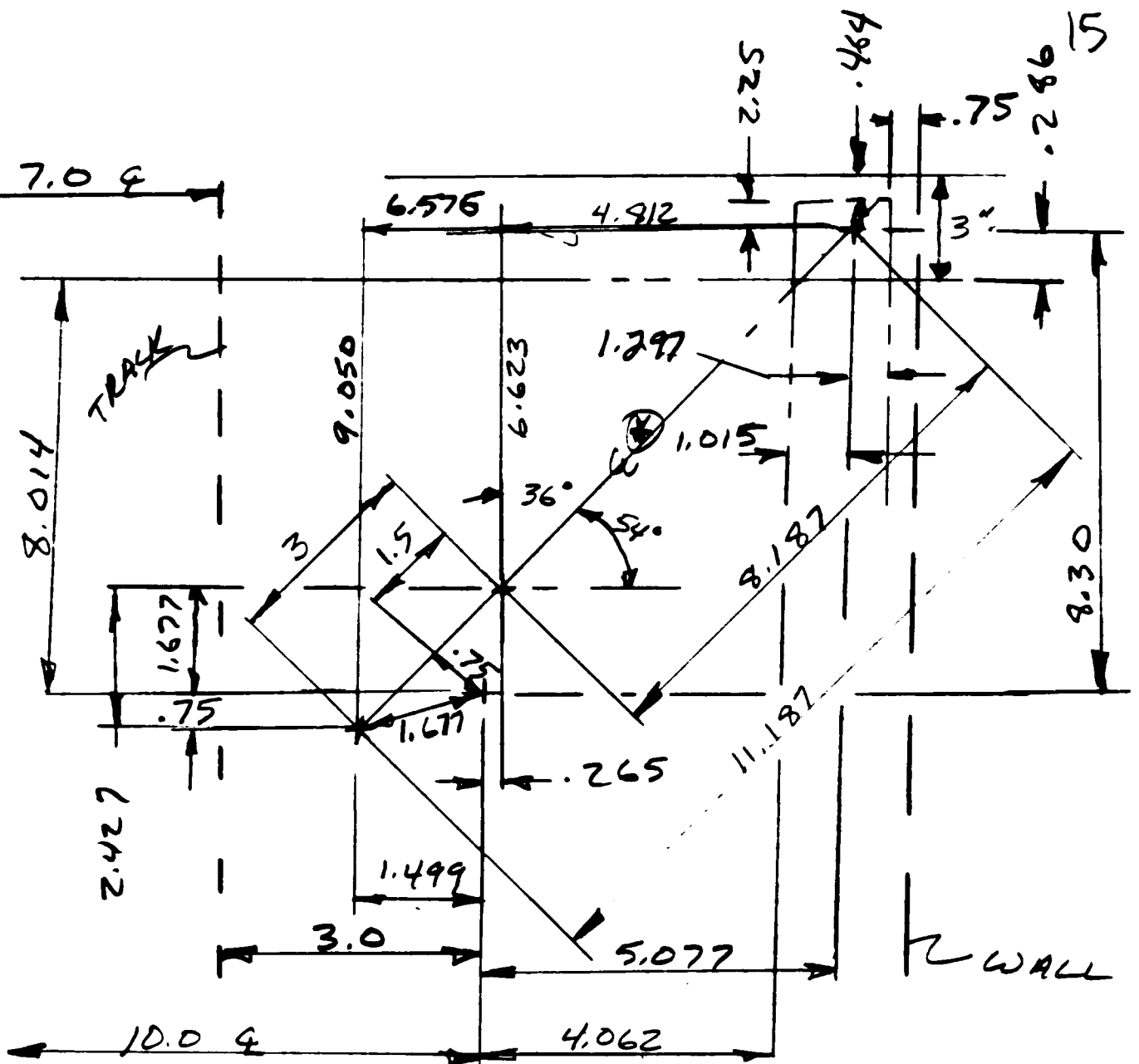
$$A = 2.76 \times 3000 \text{ PSI} = 8283 =$$

$$1.875 \text{ DIA} = (A \ 2.76)$$

1.02

$$\begin{array}{r} .276 \\ - .785 \\ \hline 1.975 \end{array} = 5925 =$$

$$\begin{array}{r} 10100 \\ - 2.76 \\ \hline 1.530 \end{array} = 4598 =$$



\* & BREECH ALT.

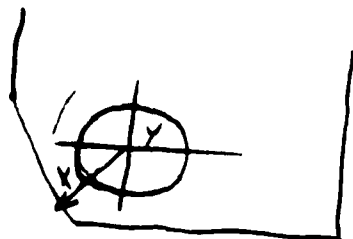


Breach cut end

16

$\frac{3}{4}$  DIA PIN IN ALUM BLOCK

A = .75

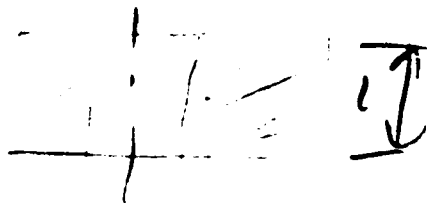


$x = 1.625 R$

$y = .875$  P.N

DEPT 1"

$P = 4000$



$$\frac{4000}{.75} = 10.666 = S$$

$$\frac{23,080}{10,666}$$

2.16 TO 1

$$4 \ 40,000 (.577) = 23,080$$

## 17

Hand-drawn technical drawing of a mechanical assembly, likely a valve or actuator, showing dimensions and components. The drawing is oriented vertically with the main body on the right and the actuator on the left.

**Dimensions (Vertical, from top to bottom):**

- Overall height: 2.500
- Top section height: 2.000
- Section below top: .125
- Section below that: .125
- Section below that: .562
- Section below that: .062
- Section below that: .328
- Section below that: 2.077
- Section below that: 1.577
- Section below that: 2.50
- Section below that: .528
- Section below that: 2.528

**Dimensions (Horizontal, from left to right):**

- Overall width: 2.500
- Width of top section: .078
- Width of middle section: .475
- Width of bottom section: .062

**Labels and Components:**

- CRANK**: Label pointing to the top section of the assembly.
- CYL END**: Label pointing to the central cylindrical part of the assembly.
- LOCK NUT**: Label pointing to the bottom section of the assembly.

The drawing shows a central cylindrical component with a flange at the top and a lock nut at the bottom. The dimensions are given in inches, and the components are labeled in capital letters.

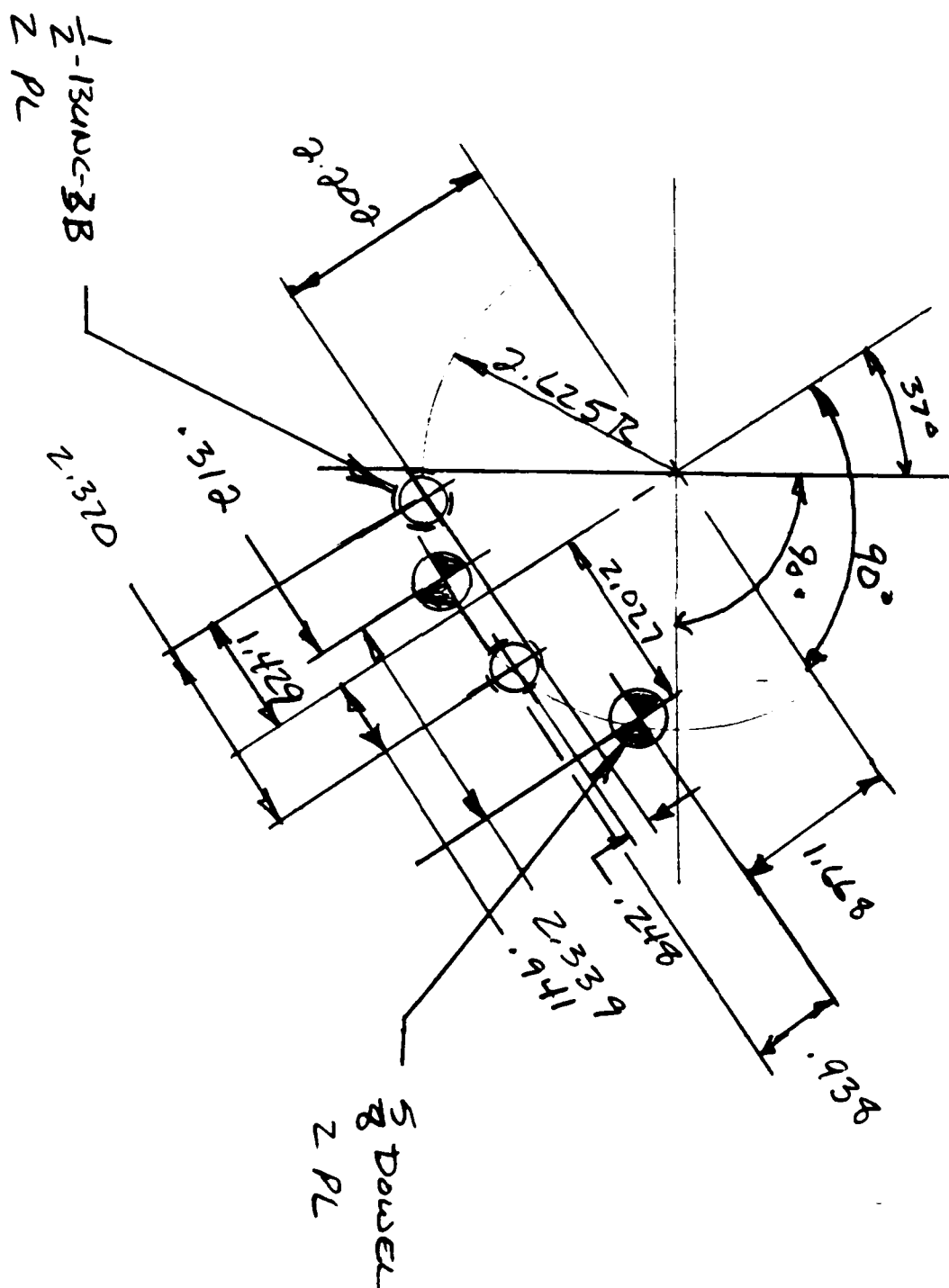
7.778 LL  
1/2 - 20 uNF

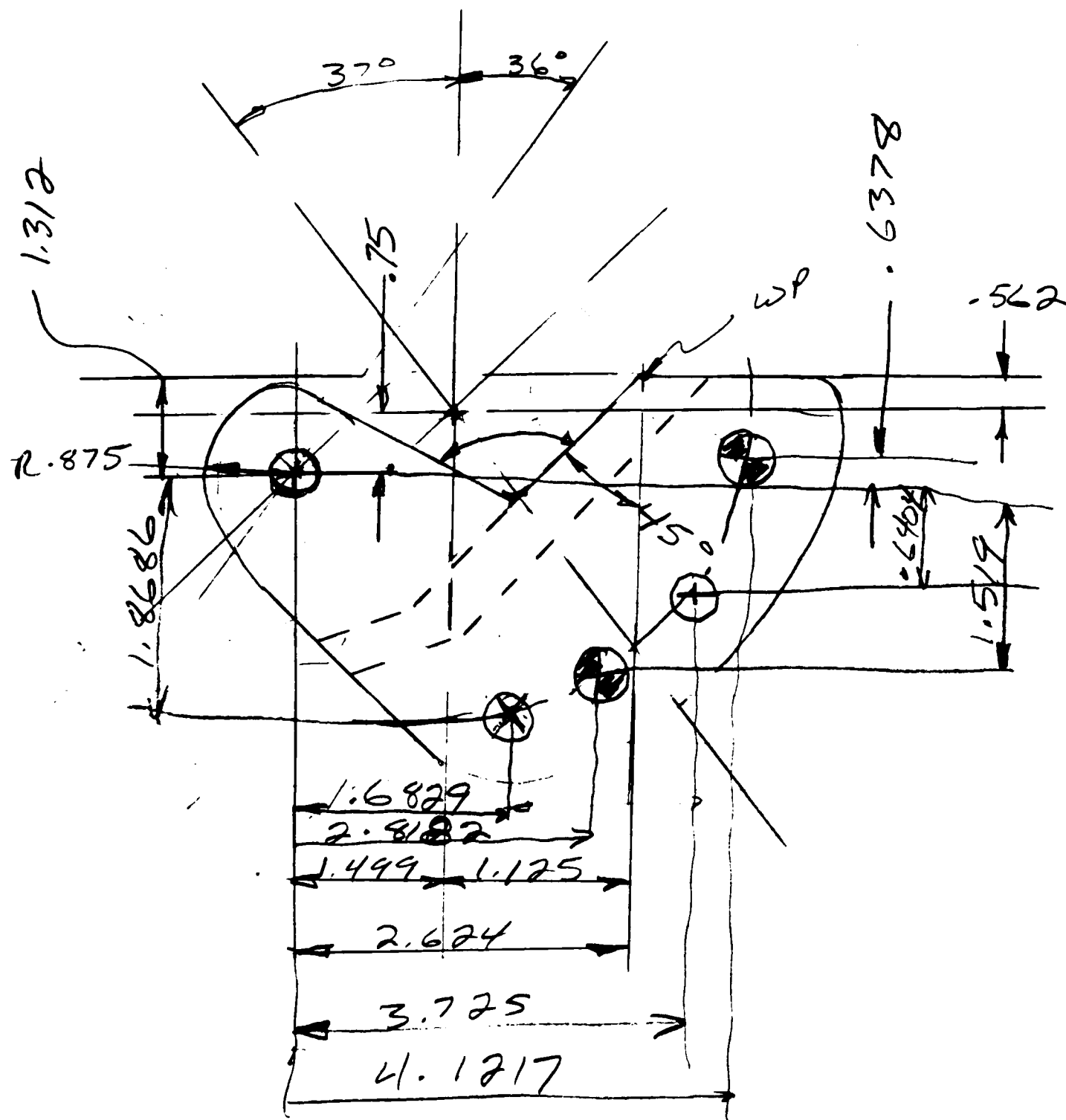
GAIP  
32 - 40

.078	.085
2.000	2.010
1.062	
<u>1.328</u>	.067
2.468	<u>1.328</u>
	2.490 max

$$\begin{array}{r} 2.528 \\ - .015 \\ \hline 2.513 \\ 2.490 \\ \hline .023 \end{array} \qquad \begin{array}{r} 2.528 \\ + .015 \\ \hline 2.543 \\ 2.468 \\ \hline .065 \end{array}$$

2014

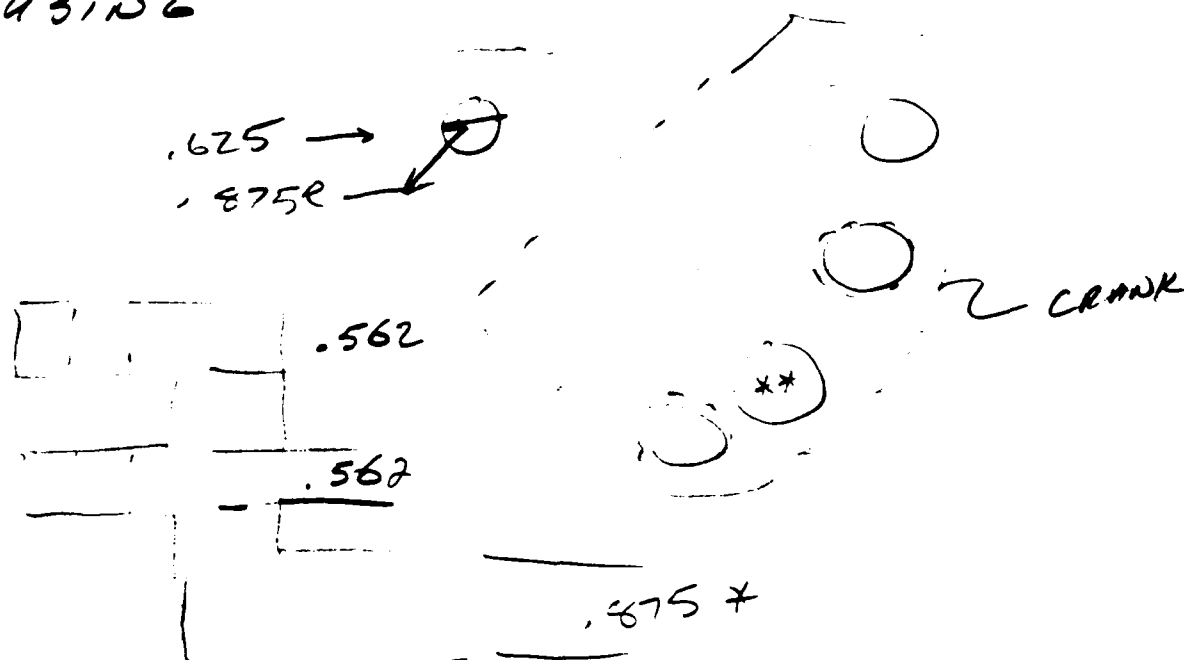




1/2" DIA PIN IN ACT & ROD END

$$1/2 = A = .1963 \quad \frac{8000^*}{.1963} = 40,743 = S$$

USING



$$A = \frac{.875}{.625} \times .562 = .351 \times 4 = 1.405$$

$$\frac{8000}{1.405} = 5,693$$

$$40,000 (577) = \frac{23080}{5693} = 4.053 \text{ TO } 1$$

$$\begin{aligned} .485 \times .625 \times 2 &= .351 \\ .562 \times .625 \times 2 &= .606 \\ \hline &= .957 \end{aligned}$$

$$\frac{8000}{.957} = \frac{23080}{5357} = 2.76 \text{ TO } 1$$

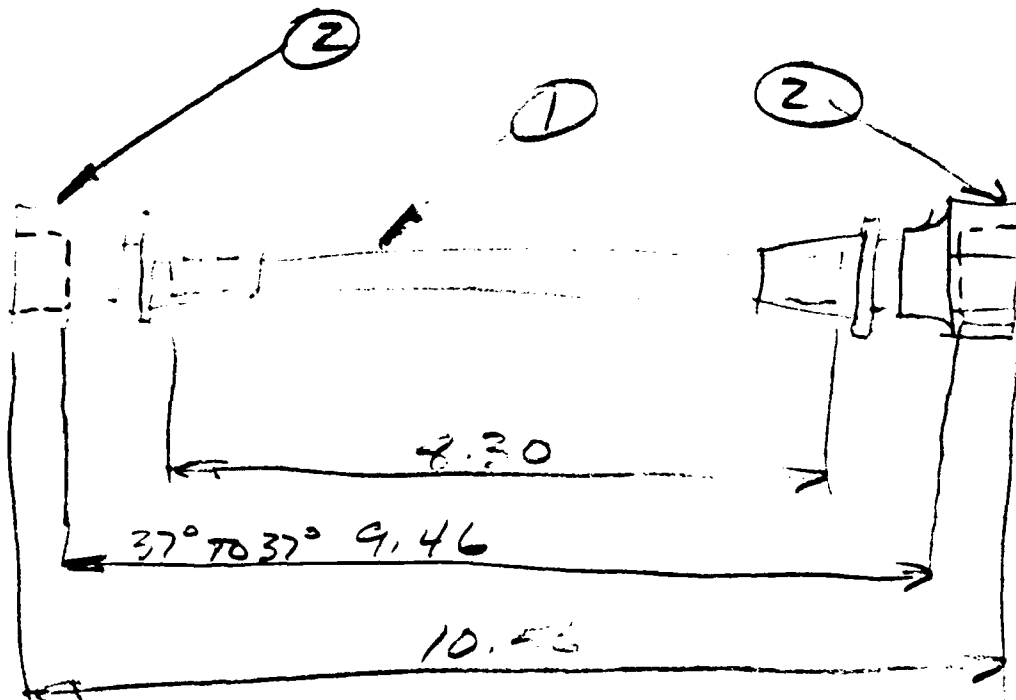
S. FAVOR

BREECH  
T-12586037/A  
RETURN  
HOSE ASSY

002

16

21



ITEM	NAME	QTY	DESC.	WT	TOL WT	PART #
1	HOSE	1	ALRQ 2807-4 X 8.3 LG	.04	.04	
2	FITTING STR	2				

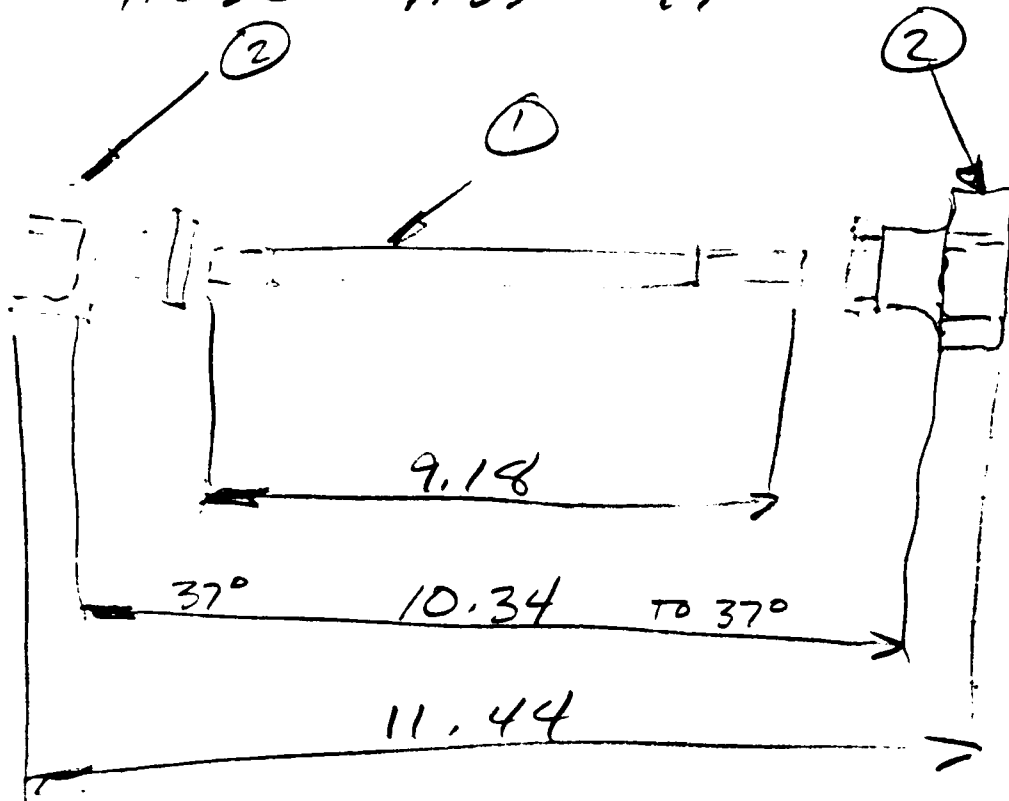
T-12586037/A

001

22

PRESSURE  
(TOP)

HOSE ASSY 17



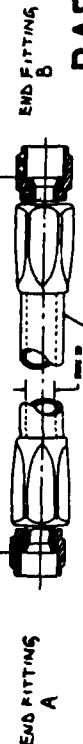
QTY	NAME	DIS	WT	PS	PART
1	HOSE	1 AERD 2907-4 Y 9.18 LG	.05	.05	
2	FIRING	2			

REVISIONS		
SYM	DESCRIPTION	DATE

[illegible]

DASH	TUNE	MOSE	RNA	STR	STR	STR	STR
202	4	.19	STR 37°	STR 37°	S. STR	10.56	TE FLOW
001	4	.19	STR 37°	STR 37°	S. STR	11.44	TE FLOW
AEROQUIP 2807-4 (C-190600-4)							
BREECH ACTUATOR							
AEROQUIP 2807-4 (C-190600-4)							
BREECH ACTUATOR							

1



**PART NO.**

PART NO.		U.S. ARMY ARMAMENT RESEARCH, DEVELOPMENT AND ENGINEERING CENTER DOVER, NEW JERSEY 07802-6001			
		HOSE ASSY.-HYDRAULIC			
		SIZE	FSCM NO. <b>B 19200</b>	T-12586037 /A	
		SCALE		UNIT WT.	SHEET 1 OF 1
ORIGINAL DATE OF DRAWING		DRAFTSMAN <i>(Signature)</i> ENGR	CHECKER ENGR		
DO NOT SCALE DRAWING UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES		TOLERANCES ON DECIMALS & FRACTIONS & ANGLES &			
MECHANICAL PROPERTIES		THIRD ANGLE PROJECTION			
	YP				
	TS				
	EL2				
	FA				
	BH				
	RH				
NEXT ASSY	USED ON				
APPLICATION					

SMCAR FORM 66, 1 JUN 66(TEMP) REPLACES ARRADCOM FORM 66, AUG 77, WHICH MAY BE USED UNTIL EXHAUSTED



PART NUMBERS: 12585716, Elevation Actuator  
12585712, 12585713 Equilibration Actuators  
12585720, Equilibration Accumulator

DESCRIPTION: ELEVATION AND EQUILIBRATION

STATUS:

Elevation -

All critical parameters for the elevation actuator (TDF, Dwg. 12585716) have been determined and are presented to the extent complete in the Technical Data Package.

Since the design and analysis of the elevation actuator is highly dependent on the design of the equilibration system, the work in this area was performed integrally with equilibration analysis and is presented as such in the following pages of this section.

Additional elevation cylinder analysis that led to the current design is also contained in a Tube Laying Accuracy report found in section C/260.

Equilibration -

All critical design parameters for the two equilibration actuators (TDF, Dwgs. 12585712, 12585713) and accumulator (TDF, Dwg. 12585720) have been determined through analysis and are shown in the TDF drawings to the extent the TDF is finished.

A complete report summarizing the equilibration (and elevation) system design and analysis is found in the following pages of this section. This information includes analysis objectives, geometry, model initial conditions, torque calculations, static and dynamic analyses with both energy recovery and manual energy usage, variable names for program ELEVATION.BAS, program module descriptions and program listings.

Also included in this section are the final equilibration and elevation analysis results as of March 13, 1987. These results are for the current system geometry as well as component weights, CG's and inertias.

AUTHORS: John Green, Sean Marek

VT-AVAL1515 (961210)  
1024 (961210)

# JOHN GREEN'S NOTES ON LTHD

ELEVATION / EQUILIBRATION ANALYSIS

AS OF 10 DEC 86.

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## ANALYSIS OBJECTIVES

Given the geometry of the Lightweight Towed Howitzer Demonstrator (LTHD), our objectives with this analysis are to size the:

Equilibration cylinders  
Elevation cylinders  
Equilibration accumulator

keeping in mind these time cycle constraints:

When moving both up and down (elevating and depressing), want to go:

<u>from</u>	<u>to</u>	<u>in</u>
600 MILS (33.75°)	800 MILS (45.0°)	2 seconds
and		
600 MILS (33.75°)	1300 MILS (73.125°)	10 seconds

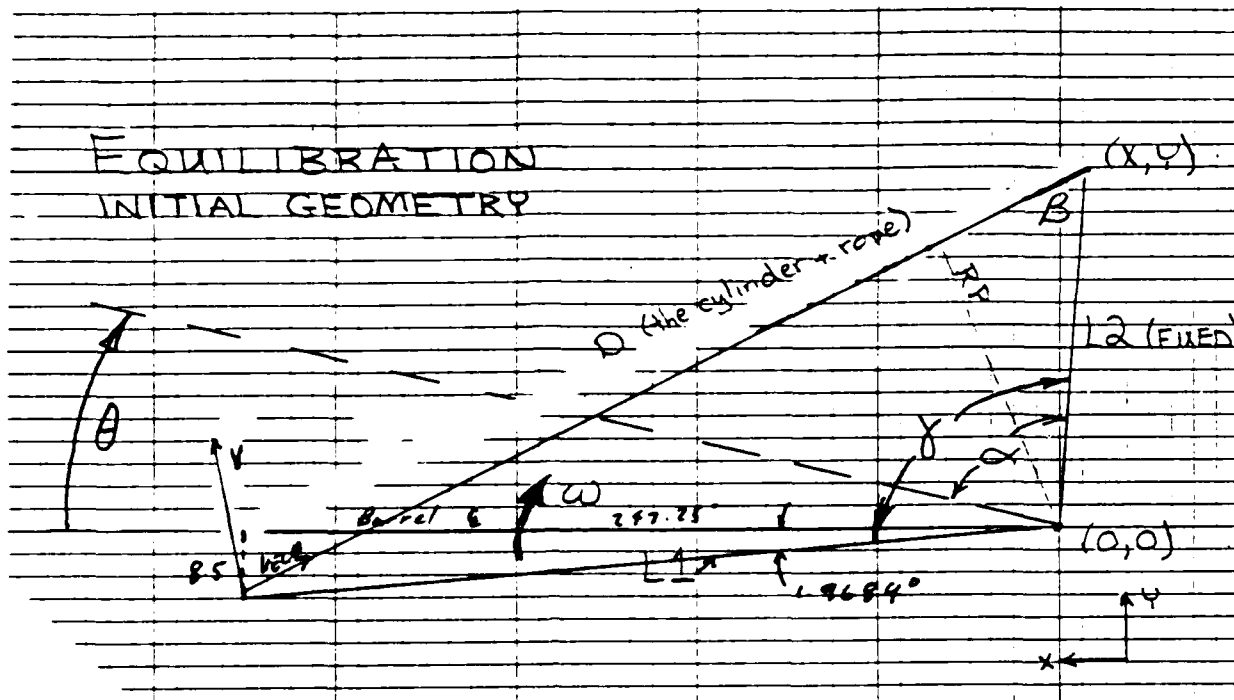
The idea is for the equilibration system to balance most of the weight of the howitzer barrel so that the manual elevation system will be able to position it. The BASIC program has been written to generate the torque of the barrel due to gravity (TGRAV) versus the torque provided by the equilibrator (TEQUIL); in this case we want TGRAV to equal TEQUIL as closely as possible.

To determine the torques around the trunnion pivot point (assigned the X-Y coordinate of (0,0) for this analysis), geometry from the equilibration and elevation systems is used to find the torque "arms" perpendicular to the force on the cylinders. The main input variable for both systems is THETA, the angle at which the barrel is elevated from horizontal.

## GEOMETRY DETERMINATION

3

### Equilibration System



Given X, Y, L1, and THETA (note direction of the X-axis):

$$L2 = \text{SQRT}(X^2 + Y^2)$$

$$\text{GAMMA} = \text{ARCTAN}(-X / Y) + 90^\circ + 1.9684^\circ$$

$$\text{ALPHA} = \text{GAMMA} - \text{THETA}$$

From the Law of Cosines:

$$D = \text{SQRT}(L1^2 + L2^2 - 2 * L1 * L2 * \text{COS}(\text{ALPHA}))$$

From the Law of Sines:

$$\text{BETA} = \text{ARCSIN}(L1 * \text{SIN}(\text{ALPHA}) / D)$$

$$\text{RP} = L2 * \text{SIN}(\text{BETA})$$

$$= L2 * L1 * \text{SIN}(\text{ALPHA}) / D$$

where RP is the perpendicular intercept needed to determine torque (TEQUIL) along D.

To determine the flowrate through the equilibration cylinder (FLOWEQUIL), the angular velocity (OMEGA) is computed from the angular acceleration of the barrel:

$$\text{ANGACCEL} = \text{TORQUE} / I$$

$$\text{OMEGA}_{\text{now}} = \text{OMEGA}_{\text{previous}} + (\text{ANGACCEL} * \text{timestep})$$

From the geometry, the velocity (VELD) along D is found to be:

$$\text{VELD} = \frac{L1 * \text{OMEGA} * \sin(\alpha) + L2}{D}$$

$$\text{FLOWEQUIL} = \text{VELD} * \text{AREA}_{\text{equil cylinder}}$$

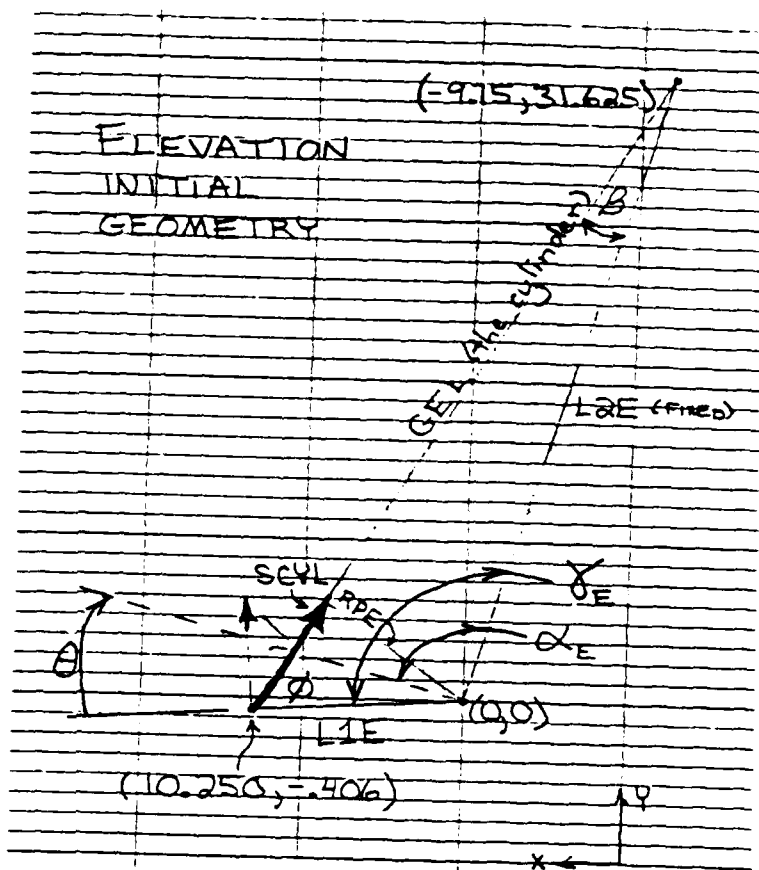
# Elevation System

5

$$L1E = 10.258$$

$$L2E = 33.094$$

$$\gamma_E = \cancel{165.13^\circ} \\ 109.40^\circ$$



Given L1E and L2E, from their coordinates:

$$\text{GAMMAE} = \cancel{165.13^\circ} \quad 109.40^\circ$$

$$\text{ALPHA E} = \text{GAMMAE} - \text{THETA}$$

From the Law of Cosines:

$$\text{GEL} = \text{SQRT}(L1E^2 + L2E^2 - 2 * L1E * L2E * \text{COS}(\text{ALPHA E}))$$

From the Law of Sines:

$$\text{SIN}(\text{BETA E}) = L1E * \text{SIN}(\text{ALPHA E}) / \text{GEL}$$

$$\text{RPE} = L2E * \text{SIN}(\text{BETA E})$$

where RPE is the perpendicular intercept needed to determine torque (TELEV) along GEL.

Since VAX BASIC does not have the ARCSIN function built in, BETA may be found by this formula:

$$\text{BETA} = \text{ARCTAN} \left( \frac{\text{SIN}(\text{BETA E})}{(1.0 - (\text{SIN}(\text{BETA E}))^2)^{1/2}} \right)$$

$$\text{PHI} = 180^\circ - \text{BETA} - \text{ALPHA E}$$

6

To determine the flowrate through the elevation cylinder (FLOWELEV), use the same angular velocity (OMEGA) as for the equilibration system.

The velocity (SCYL) along GEL is found to be:

$$SCYL = L1E * OMEGA * \cos(90^\circ - PHI)$$

$$FLOWELEV = SCYL * AREA2_{elev cylinders}$$

## INITIAL CONDITIONS

Both dynamic and static analyses execute module 7000 of the BASIC code which interpolates from a Nitrogen real gas table to find:

The mass of the gas (MOLE) in the equilibration accumulator.

The volume of gas (VCOMP) to be pumped into the equilibration cylinder to get it to the right ~~charge~~ pressure.

This volume is to compensate for pressure changes due to fluctuating ambient temperatures.

The initial entropy (ENTO) of the nitrogen in the accumulator.

Assuming the Nitrogen accumulator was charged in a lab at the ideal temperature of ~~72~~<sup>70</sup>°F and a specified charge pressure (for example, 3,000 PSI), interpolate from the Nitrogen table to get the specific volume (VOL) of the gas initially in the accumulator.

Given the volume of the equilibrator accumulator (VE), use this VOL to find the mass (MOLE) of the gas in the accumulator:

$$\text{MOLE} = \text{VE} / \text{VOL} \quad (\text{LB-mass})$$

Now given the ambient temperature and <sup>starting</sup> pressure conditions, interpolate from the Nitrogen table for a new VOL in order to find VCOMP (the compensation volume) to be pumped into the cylinder to get it to the right ~~charge~~ pressure. These computations are based on the gun at 0 degrees elevation.

$$\text{VCOMP} = \text{VE} - \text{VOL} * \text{MOLE} - ( (\text{DO} - \text{DF}) * \text{AREAL} )$$

Next the variables get reset, based on the gun at THETA0 elevation:

$$\text{VOLO} = \frac{\text{VE} - \text{VCOMP} - ( (\text{DS} - \text{DF}) * \text{AREAL} )}{\text{MOLE}}$$

Given the initial temperature (TEMP = TEMPO = T<sub>ambient</sub>) and specific volume (VOL = VOLO), interpolate from the Nitrogen table to get the initial pressure (PRESSO) and entropy (ENTO) of the nitrogen in the accumulator.

For dynamic analysis, entropy is assumed to remain constant. ENTO is thereby used only for Nitrogen table interpolation purposes to track the pressure changes.

(NOTE: The initial Nitrogen table we used was in SI units, so we converted all the values to English units except the entropy units because, in this analysis, entropy values are only used for interpolation.)



COMPUTING THE TORQUES

For each value of THETA (currently computed at 1° increments):

$$TGRAV = LCG * WT * \cos(THETA)$$

For the equilibration system, find D for the given THETA. Use D to compute:

$$VOL = \frac{VE - ((D - DF) * AREAL) - VCOMP}{MOLE}$$

Use VOL to interpolate from the nitrogen table to get the pressure (PRESS), which is used in this equilibration system torque equation:

$$TEQUIL = (PRESS - PAMB) * AREAL * RP$$

For the elevation system, find GEL for the given THETA. Use GEL to compute:

$$VOLUME = \text{ABS}((GELI - GEL) * AREA2)$$

The static analysis (for which these torques are found) is assumed to be:

- only elevating the barrel
- isothermal

Therefore the simple pressure/volume relation may be used:

$$PCYL = (PAI * VAI) / (VAI + VOLUME)$$

The elevation system torque is then:

$$TELEV = (PCYL - PAMB) * AREA2 * RPE$$

## ANALYSES: STATIC & DYNAMIC

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The BASIC program executes two analyses results:

The static analysis is initially run to optimize design parameters (charge pressure, sizing the accumulator, cylinders, pistons, etc.) before running the larger, more time consuming dynamic analysis.

The dynamic analysis then gives the cycle times as a result of these static analysis parameters.

There are two methods by which the barrel may be elevated/depressed:

The energy recovery option uses an accumulator (which gets pumped up by the gun recoil) to control barrel elevation.

The manual power option uses a <sup>hand pump</sup> ~~hand crank~~ to control barrel elevation.

This places the additional constraint on the system of a human only being able to maintain an input power of 0.3 horsepower.

### Elevation Cylinder

First the program sets some controlling switches:

SWITCH = 0    when barrel is elevating  
SWITCH = 1    when barrel is depressing

Flag 1 = 1    activates the deceleration routine

Flag 2 = 1    activates the creep speed routine  
to maintain a constant 2deg/sec until  
the cannon reaches its final elevation

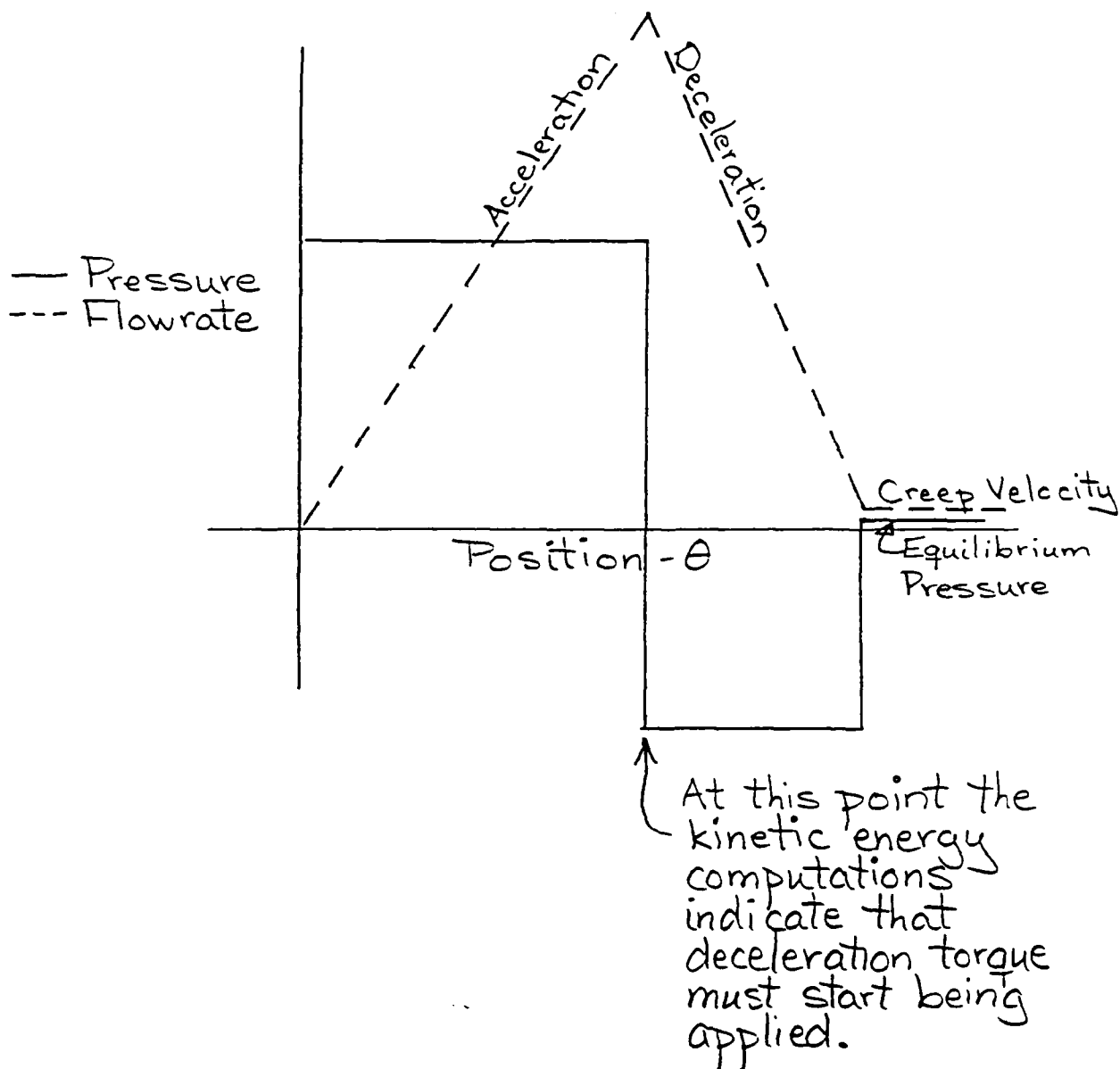
A. For the Energy Recovery option:

10

1. ACCELERATION PHASE.

Use an energy recovery/storage accumulator (which gets pumped up by the gun recoil) to accelerate, and then decelerate, the system when it is elevating.

# Elevation Cylinder Energy Recovery Cycle



Track the kinetic energy (ENERGY) at each time step to determine when to "apply the brakes" (change from acceleration to deceleration).

So from the geometry, the angular velocity (OMEGA) is known at that time step and flags can be set accordingly.

The volume in the elevation cylinder may be figured from:

What comes out of the accumulator =

Volume change due to change in length of the cylinder  
+  
Volume initially expended from the accumulator  
(VOLUME1 = 0 for elevating.)

That is:

$$VOLUME = ABS((GELI - GEL) * AREA2) + VOLUME1$$

The pressure in the cylinder (PCYL) is computed from an equation based on the theoretical condition of an isentropic process and an adiabatic, ideal gas (so temperature is eliminated as a variable).

That equation is:  $P_1 V_1^n = P_2 V_2^n$

and

$$PCYL = \frac{PAI * VAI^n}{(VAI + VOLUME)^n} \quad \text{where } n = 1.4$$

$$ENERGY = 0.5 * I * (OMEGA)^2$$

The torque (TSTOP) required to turn around and stop the acceleration (at that time step):

$$TSTOP = \frac{ENERGY}{ABS(THETA_{end} - THETA_{current}) - .008}$$

where the .008 radians is to assure a creep speed distance.

PSTOP is also figured as a function of TSTOP, even though it is really an (instantaneous) approximation.

$$PSTOP = PAMB + ABS(TSTOP / (AREA3 * RPE))$$

Torque on the elevation cylinder is also computed for this acceleration phase:

$$TELEV_{accel} = (PCYL - PAMB) * AREA2 * RPE$$

As soon as TSTOP or PSTOP exceed a maximum, FLAG1 is thrown and the program jumps down to the deceleration phase.

## 2. DECELERATION PHASE.

Here:

$$PCYL = -PSTOP * GAIN$$

where GAIN is a multiplier/constant input by the person running the program to compensate for a program limitation; the program cannot anticipate what will happen in future computations.

PCYL needs to be negative since pressure is now applied to the back side (AREA3) of the elevation cylinder piston.

$$TELEV_{decel} = (PCYL + PAMB) * AREA3 * RPE$$

As soon as the angular velocity (OMEGA) drops to or below the creep velocity (VMIN), the program jumps down to the creep velocity phase.

## 3. CREEP VELOCITY PHASE.

Once the barrel attains creep velocity, it is assumed that the constant speed yields balanced torques. Therefore:

$$TELEV_{creep} = TGRAV - TEQUIL$$

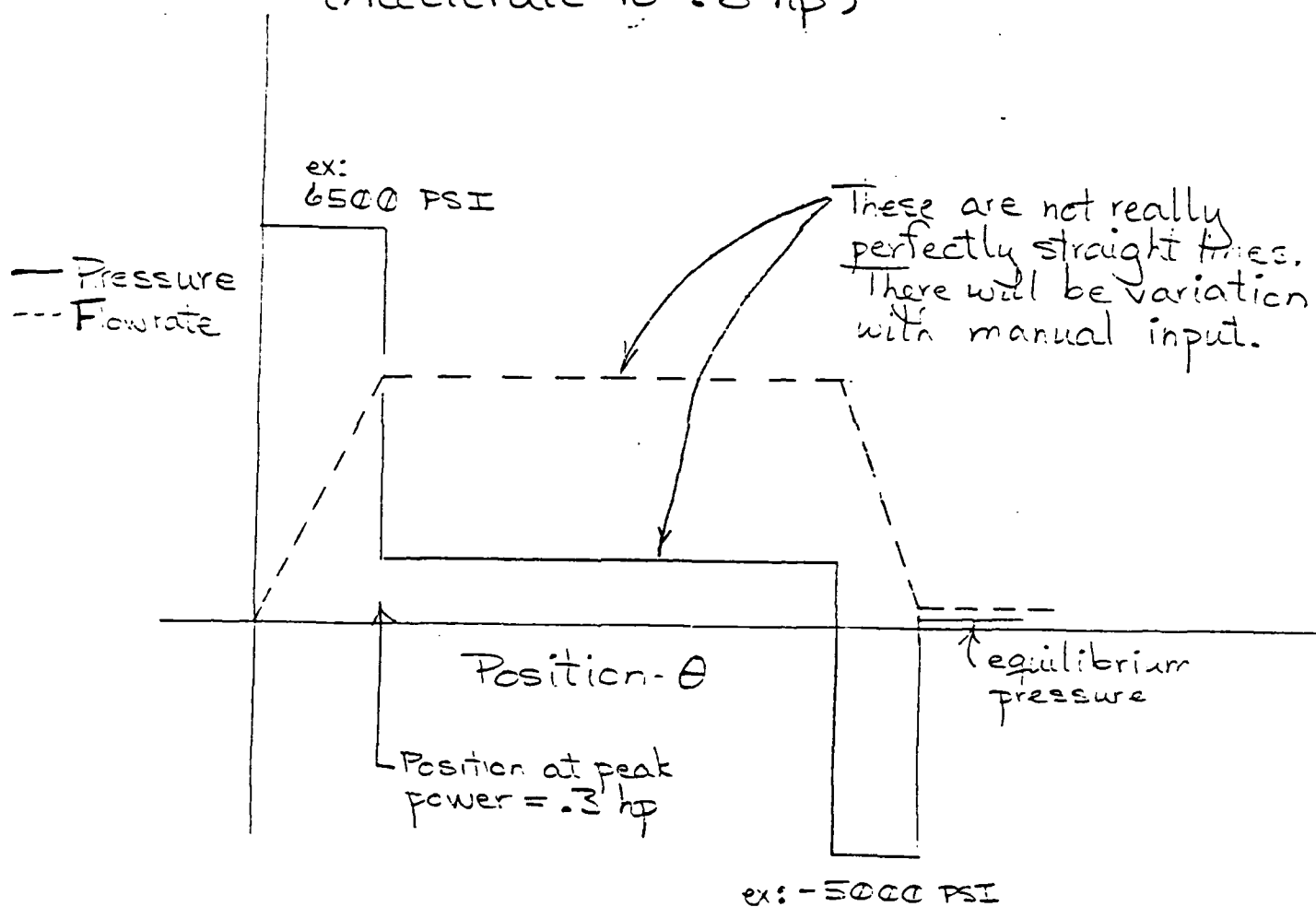
Torque just  
required to keep it  
moving at constant  
speed.

$$PCYL = PAMB + (TELEV / (AREA2 * RPE))$$

- B. For the Manual Power option there is the additional constraint of a human only being able to maintain an input power of 1/3 horsepower.

$$POWMAX = 0.3$$

Elevation Cylinder  
Manual Cycle  
(Accelerate to .3 hp)



From the geometry it is known that:

$$\begin{aligned} \text{SCYL} &= \text{LIE} * \text{OMEGA} * \cos\left(\frac{\text{PI}}{2} - \text{PHI}\right) \\ \text{PCYL} &= \text{PCYLMAX} + \text{PAMB} \end{aligned}$$

From a fluid handbook:

$$\text{VEL}_{\text{cyl}} \text{ (ft/s)} = \frac{231 * \text{Flow Rate (GPM)}}{12 * 60 * \text{Net Area (in}^2\text{)}}$$

Therefore:

$$\text{FLOWRATE} = \text{SCYL} * \text{AREA2} * 60 / 231$$

$$\text{POWER (hp)} = \text{FLOWRATE} * \text{PCYL} / (1714.0 * \text{efficiency})$$

^Assume e = 100%

If POWER > 0.3 then reset the input pressure to maintain a constant power of 0.3 horsepower:

$$\text{PCYL} = \text{PAMB} + \text{ABS}(0.3 * 1714.0 / \text{FLOWRATE})$$

The following computations are the same as for the Energy Recovery option (Section A.):

$$\text{ENERGY} = 0.5 * \text{I} * (\text{OMEGA})^2$$

The torque (TSTOP) required to turn around and stop the acceleration (at that time step):

$$\text{TSTOP} = \frac{\text{ENERGY}}{\text{ABS}(\text{THETA}_{\text{end}} - \text{THETA}_{\text{current}}) - .008}$$

where the .008 radians is to assure a creep speed distance.

PSTOP is also figured as a function of TSTOP, even though it is really an (instantaneous) approximation.

$$\text{PSTOP} = \text{PAMB} + (\text{TSTOP} / (\text{AREA3} * \text{REP}))$$

$$\text{TELEV}_{\text{accel}} = (\text{PCYL} - \text{PAMB}) * \text{AREA2} * \text{RPE}$$

As soon as TSTOP or PSTOP exceed a maximum, FLAG1 is thrown and the program jumps down to the deceleration phase (Section A.2.).

# VARIABLE NAMES FOR PROGRAM ELEVATION.BAS

VARIABLE	COMPUTATION UNITS	DESCRIPTION
A		COUNTER
ACC		NUMBER USED TO CHECK PRECISION OF ITERATION
ALPHA	RAD	ALPHA variable for equilibrator geometry
ALPHAE	RAD	ALPHA variable for elevation geometry
ANGACCEL	RAD/SEC^2	ANGULAR ACCELERATION OF THE BARREL
AREA1	IN^2	PISTON AREA - EQUILIBRATION CYLINDER
AREA2	IN^2	PISTON AREA - ELEVATION (SMALLER SIDE) * 2 CYLINDER
AREA3	IN^2	PISTON AREA - ELEVATION (LARGER SIDE) * 2 CYLINDER
B		COUNTER
BETA		BETA variable for geometry
BSS		
BV		
C		COUNTER
CNT		A COUNTER TO PRINT EVERY 100 DATA POINTS
D		COUNTER
D	IN	SIDE 3, EQUILIBRATION GEOMETRY (THE SLIDING LEG)
DATAOUT\$	string	OUTPUT FILE NAME
DEGTORAD		CONVERSION CONSTANT
DF	IN	D AT THETA = 72 DEGREES
DO	IN	D AT THETA = 0 DEGREES
DRIVERS\$	string	DRIVING FUNCTION OPTION VARIABLE
DS	IN	D AT THETA = THETA0
DT	SEC	TIME STEP
ENERGY	FT-LB	= .5*I*OMEGA^2, CURRENT KINETIC ENERGY OF BARREL ASSY
ENT		CURRENT ENTROPY OF THE EQUILIBRATION GAS
ENTO		INITIAL ENTROPY OF EQUIL GAS AT SIMULATION START
EPS		
EPSP		= EPS/8.0
FLAG1		
FLAG2		
FLOWELEV	GAL/MIN	FLOWRATE INTO ELEVATION CYLINDER
FLOWEQUIL	GAL/MIN	FLOWRATE INTO EQUILIBRATION CYLINDER
GAIN		A MULTIPLIER, HUMAN INPUT COMPENSATES FOR PRG LIMIT
GAMMA	RAD	GAMMA variable for equilibrator geometry
GAMMAE	RAD	GAMMA variable for elevation geometry
GEL	IN	SIDE 3, ELEVATION GEOMETRY (THE SLIDING LEG)
GELF	IN	GEL AT THE HIGHEST ANGLE
GELI	IN	AT THETA=0 FOR GOING UP, AT THETA=72 FOR GOING DOWN
GELO	IN	GEL AT THE LOWEST ANGLE
I	SLUG-FT^2	MASS MOMENT OF INERTIA OF THE BARREL
L1	IN	SIDE 1, EQUILIBRATION GEOMETRY
L1E	IN	SIDE 1, ELEVATION GEOMETRY
L2	IN	SIDE 2, EQUILIBRATION GEOMETRY
L2E	IN	SIDE 2, ELEVATION GEOMETRY
LCG	IN	= 13.56 FEET
MOLE	LB-mass	= VE/VOL, MASS OF GAS IN EQUILIBRATOR ACCUMULATOR
MS		
MV		
OMEGA	RAD/S	ANGULAR VELOCITY OF ELEVATION GEOMETRY
OMEGA1		
OMEGA1S		INITIAL CONDITIONS GIVEN TO THE ITERATION MODULE
OMEGA2		
OMEGA2S		



# VARIABLE NAMES FOR PROGRAM ELEVATION.BAS

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VARIABLE	COMPUTATION UNITS	DESCRIPTION
OPT\$	string	OPTION STRING VARIABLE
PAI	LB/IN <sup>2</sup>	INITIAL ENERGY STORAGE ACCUMULATOR GAS PRESSURE
PAMB	LB/IN <sup>2</sup>	AMBIENT PRESSURE
PCHARGE	LB/IN <sup>2</sup>	CHARGE PRESSURE
PCYL	LB/IN <sup>2</sup>	CURRENT PRESSURE IN ELEVATION CYLINDER
PCYL1	LB/IN <sup>2</sup>	
PCYL2	LB/IN <sup>2</sup>	
PCYLMAX	LB/IN <sup>2</sup>	MAX PRESSURE POSSIBLE DURING MANUAL OPERATION
PH		
PHI	RAD	ANGLE BETWEEN CYLINDER & BARREL
PISDIA	IN	ELEVATION CYLINDER PISTON DIAMETER
PL		
PO	LB/IN <sup>2</sup>	EQUILIBRATION GAS PRESSURE AT THETA = 0
POWER		POWER BEING EXERTED BY ELEVATION CYLINDER
POWMAX	HP	MAXIMUM MANUAL POWER INPUT: 1/3 HP
PRESS	LB/IN <sup>2</sup>	CURRENT PRESSURE OF EQUILIBRATION PISTON
PRESS	LB/IN <sup>2</sup>	PRESSURE AFTER EXTENDED TIME
PRESSO	LB/IN <sup>2</sup>	INITIAL EQUILIBRATION GAS PRESSURE
PSTART	LB/IN <sup>2</sup>	STARTING DECELERATION PRESSURE
PSTOP	LB/IN <sup>2</sup>	OPTIMUM PRESSURE REQ'D TO STOP BARREL BEFORE THETA F
PSTOPMAX	LB/IN <sup>2</sup>	=PSTART/GAIN, MAXIMUM ALLOWABLE STOPPING PRESSURE
RADTODEG		CONVERSION CONSTANT
RODDIA	IN	ROD DIAMETER, ELEVATION CYLINDER
RP	IN	PERPENDICULAR BISECTOR, EQUILIBRATION GEOMETRY
RPE	IN	PERPENDICULAR BISECTOR, ELEVATION GEOMETRY
SLH		variable used for interpolation
SLL		variable used for interpolation
S2H		variable used for interpolation
S2L		variable used for interpolation
SCYL	IN/S	SPEED (VELOCITY) OF THE ELEVATION CYLINDER
SH		
SH		
SINB		SIN OF THE BETA ANGLE, EQUILIBRATION GEOMETRY
SINBE		SIN OF THE BETA ANGLE, ELEVATION GEOMETRY
SL		
SL		
STME		CURRENT TIME GIVEN TO THE ITERATION MODULE
SWITCH		=0 FOR ELEVATING, =1 FOR DEPRESSING (ELEVATION CYL)
T		TIME INCREMENT TO BE GIVEN TO THE ITERATION MODULE
T1		TORQUE AT BEGINNING OF TIME STEP
T2		TORQUE AT END OF THE TIME STEP
TAMB	deg-F	OUTSIDE AMBIENT TEMP
TELEV	IN-LB	TORQUE EXERTED BY THE ELEVATION CYLINDER
TEMP	deg-F	=72 CURRENT TEMP
TEMPO	deg-F	INITIAL EQUILIBRATION GAS TEMP
TEQUIL	IN-LB	TORQUE EXERTED BY THE EQUILIBRATION CYLINDER
TGRAV	IN-LB	TORQUE EXERTED GRAVITY
TH		
THETA	RAD	INPUT ANGLE: ELEVATION OF THE BARREL
THETA1		
THETA1S		INITIAL CONDITIONS GIVEN TO THE ITERATION MODULE
THETA2		
THETA2S		

15

VARIABLE NAMES FOR PROGRAM ELEVATION.BAS

17

VARIABLE	COMPUTATION UNITS	DESCRIPTION
THETAF	RAD	HIGHEST ENDING ELEVATION (MAY BE 72 DEGREES)
THETAO	RAD	LOWEST STARTING ELEVATION (MAY BE 0 DEGREES)
THETAS	RAD	=THETAF FOR ELEVATING, =THETAO FOR DEPRESSING
TIMENOW\$	string	CURRENT TIME
TL		
TM1	IN-LB	INITIAL MEAN FORCE GUESS
TM2	IN-LB	=(T2+T1)/2.0 , NEXT MEAN TORQUE GUESS
TME	SEC	TIME
TODAY\$	string	TODAY'S DATE
TORQUE	IN-LB	=TELEV+TEQUIL-TGRAV, TOTAL TORQUE DETERMINED
TS1		
TS2		
TSTOP	IN-LB	OPTIMUM TORQUE REQ'D TO STOP BARREL BEFORE THETAF
TSTOPMAX	IN-LB	MAXIMUM DECELERATION/ALLOWABLE STOPPING TORQUE
TV1		variable used for interpolation
TV2		variable used for interpolation
V1H		variable used for interpolation
V1H		variable used for interpolation
V1L		variable used for interpolation
V1L		variable used for interpolation
V2H		variable used for interpolation
V2H		variable used for interpolation
V2L		variable used for interpolation
V2L		variable used for interpolation
VAI	IN^3	INITIAL ENERGY STORAGE ACCUMULATOR GAS VOLUME
VCOMP	IN^3	VOLUME OF FLUID USED TO COMPENSATE FOR TEMP CHANGE
VE	IN^3	VOLUME OF THE EQUILIBRATOR ACCUMULATOR
VELD	IN/S	VELOCITY ALONG D
VF	IN^3	FINAL VOLUME OF THE EQUILIBRATION GAS
VH		
VL		
VMIN	RAD/S	=.01 RAD/S, ANGULAR CREEP VELOCITY
VOL	IN^3/LBm	SPECIFIC VOLUME OF THE EQUILIBRATION GAS
VOLO	IN^3/LBm	INITIAL EQUILIBRATION GAS SPECIFIC VOLUME
VOLUME	IN^3	VOLUME OF FLUID USED SINCE START OF SIMULATION
VOLUME1	IN^3	AMT OF FLUID PUMPED INTO CYL AT END OF ELEVATING
WT	LBS	WEIGHT OF COMPONENTS TO BE ELEVATED/DEPRESSED

16

# Program module descriptions

Line	Description
100	Main operating menu
185	Equilibration Modification Menu
370	Elevation modification menu
605	Simulation control menu
1000	Simulation controller
2000	Force, velocity, position, and acceleration iteration module
3000	Torque Summing module
4000	Geometry determination module
5000	Equilibration torque module
6000	Elevation torque module
7000	initial conditions module
8000	Real gas data input module
9000	Gas table interpolation by pressure and temperature
10000	Gas table interpolation by specific volume and entropy
11000	Gas table interpolation by temperature and specific volume
12000	Static Simulation module
13000	Data output module
14000	Output file initialization module
15000	Overturning Torque calculation module

# VARIABLE NAMES FOR PROGRAM ELEVATION.BAS

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VARIABLE	COMPUTATION UNITS	DESCRIPTION
A		COUNTER
ACC		NUMBER USED TO CHECK PRECISION OF ITERATION
ALPHA	RAD	ALPHA variable for equilibrator geometry
ALPHAE	RAD	ALPHA variable for elevation geometry
ANGACCEL	RAD/SEC^2	ANGULAR ACCELERATION OF THE BARREL
AREA1	IN^2	PISTON AREA - EQUILIBRATION CYLINDER
AREA2	IN^2	PISTON AREA - ELEVATION (SMALLER SIDE) * 2 CYLINDERS
AREA3	IN^2	PISTON AREA - ELEVATION (LARGER SIDE) * 2 CYLINDERS
B		COUNTER
BETA		BETA variable for geometry
BSS		
BV		
C		COUNTER
CNT		A COUNTER TO PRINT EVERY 100 DATA POINTS
D		COUNTER
D	IN	SIDE 3, EQUILIBRATION GEOMETRY (THE SLIDING LEG)
DATAOUT\$	string	OUTPUT FILE NAME
DEGTORAD		CONVERSION CONSTANT
DF	IN	D AT THETA = 72 DEGREES
DO	IN	D AT THETA = 0 DEGREES
DRIVER\$	string	DRIVING FUNCTION OPTION VARIABLE
DS	IN	D AT THETA = THETA0
DT	SEC	TIME STEP
ENERGY	FT-LB	= .5*I*OMEGA^2, CURRENT KINETIC ENERGY OF BARREL ASSY
ENT		CURRENT ENTROPY OF THE EQUILIBRATION GAS
ENTO		INITIAL ENTROPY OF EQUIL GAS AT SIMULATION START
EPS		
EPSF		= EPS/8.0
FLAG1		
FLAG2		
FLOWELEV	GAL/MIN	FLOWRATE INTO ELEVATION CYLINDER
FLOWEQUIL	GAL/MIN	FLOWRATE INTO EQUILIBRATION CYLINDER
GAIN		A MULTIPLIER, HUMAN INPUT COMPENSATES FOR PRG LIMIT
GAMMA	RAD	GAMMA variable for equilibrator geometry
GAMMAE	RAD	GAMMA variable for elevation geometry
GEL	IN	SIDE 3, ELEVATION GEOMETRY (THE SLIDING LEG)
GELF	IN	GEL AT THE HIGHEST ANGLE
GELI	IN	AT THETA=0 FOR GOING UP, AT THETA=72 FOR GOING DOWN
GELO	IN	GEL AT THE LOWEST ANGLE
I	SLUG-FT^2	MASS MOMENT OF INERTIA OF THE BARREL
L1	IN	SIDE 1, EQUILIBRATION GEOMETRY
L1E	IN	SIDE 1, ELEVATION GEOMETRY
L2	IN	SIDE 2, EQUILIBRATION GEOMETRY
L2E	IN	SIDE 2, ELEVATION GEOMETRY
LCG	IN	= 13.56 FEET
MOLE	LB-mass	= VE/VOL, MASS OF GAS IN EQUILIBRATOR ACCUMULATOR
MS		
MV		
OMEGA	RAD/S	ANGULAR VELOCITY OF ELEVATION GEOMETRY
OMEGA1		
OMEGA1S		INITIAL CONDITIONS GIVEN TO THE ITERATION MODULE
OMEGA2		
OMEGA2S		

# VARIABLE NAMES FOR PROGRAM ELEVATION.BAS

20

VARIABLE	COMPUTATION UNITS	DESCRIPTION
OPT#	string	OPTION STRING VARIABLE
FAI	LB/IN <sup>2</sup>	INITIAL ENERGY STORAGE ACCUMULATOR GAS PRESSURE
FAMB	LB/IN <sup>2</sup>	AMBIENT PRESSURE
FCHARGE	LB/IN <sup>2</sup>	CHARGE PRESSURE
FCYL	LB/IN <sup>2</sup>	CURRENT PRESSURE IN ELEVATION CYLINDER
FCYL1	LB/IN <sup>2</sup>	
FCYL2	LB/IN <sup>2</sup>	
FCYLMAX	LB/IN <sup>2</sup>	MAX PRESSURE POSSIBLE DURING MANUAL OPERATION
FH		
FHI	RAD	ANGLE BETWEEN CYLINDER & BARREL
FISDIA	IN	ELEVATION CYLINDER PISTON DIAMETER
FL		
FO	LB/IN <sup>2</sup>	EQUILIBRATION GAS PRESSURE AT THETA = 0
POWER		POWER BEING EXERTED BY ELEVATION CYLINDER
POWMAX	HP	MAXIMUM MANUAL POWER INPUT: 1/3 HP
PRESS	LB/IN <sup>2</sup>	CURRENT PRESSURE OF EQUILIBRATION PISTON
PRESS	LB/IN <sup>2</sup>	PRESSURE AFTER EXTENDED TIME
PRESS0	LB/IN <sup>2</sup>	INITIAL EQUILIBRATION GAS PRESSURE
PSTART	LB/IN <sup>2</sup>	STARTING DECELERATION PRESSURE
PSTOP	LB/IN <sup>2</sup>	OPTIMUM PRESSURE REQ'D TO STOP BARREL BEFORE THETA F
PSTOPMAX	LB/IN <sup>2</sup>	=PSTART/GAIN, MAXIMUM ALLOWABLE STOPPING PRESSURE
RADTODEG		CONVERSION CONSTANT
RODDIA	IN	ROD DIAMETER, ELEVATION CYLINDER
RF	IN	PERPENDICULAR BISECTOR, EQUILIBRATION GEOMETRY
RFE	IN	PERPENDICULAR BISECTOR, ELEVATION GEOMETRY
S1H		variable used for interpolation
S1L		variable used for interpolation
S2H		variable used for interpolation
S2L		variable used for interpolation
SCYL	IN/S	SPEED (VELOCITY) OF THE ELEVATION CYLINDER
SH		
SH		
SINB		SIN OF THE BETA ANGLE, EQUILIBRATION GEOMETRY
SINBE		SIN OF THE BETA ANGLE, ELEVATION GEOMETRY
SL		
SL		
STME		CURRENT TIME GIVEN TO THE ITERATION MODULE
SWITCH		=0 FOR ELEVATING, =1 FOR DEPRESSING (ELEVATION CYL)
T		TIME INCREMENT TO BE GIVEN TO THE ITERATION MODULE
T1		TORQUE AT BEGINNING OF TIME STEP
T2		TORQUE AT END OF THE TIME STEP
TAMB	deg-F	OUTSIDE AMBIENT TEMP
TELEV	IN-LB	TORQUE EXERTED BY THE ELEVATION CYLINDER
TEMP	deg-F	=72 CURRENT TEMP
TEMPO	deg-F	INITIAL EQUILIBRATION GAS TEMP
TEQUIL	IN-LB	TORQUE EXERTED BY THE EQUILIBRATION CYLINDER
TGRAV	IN-LB	TORQUE EXERTED GRAVITY
TH		
THETA	RAD	INPUT ANGLE: ELEVATION OF THE BARREL
THETA1		
THETA1S		INITIAL CONDITIONS GIVEN TO THE ITERATION MODULE
THETA2		
THETA2S		

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21

	SSSS	AAA	V	V	;;	1		
S		A	A	V	V	;;	11	
S		A	A	V	V		1	
	SSS	A	A	V	V	;;	1	
		S	AAAAA	V	V	;;	1	
..		S	A	A	V	V	;	1
..	SSSS	A	A	V		;	111	

LLLLLLLLLL  
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10 rem PROGRAM TO SIMULATE THE ELEVATION OF THE LTHD
12 rem October/November 1986 John E. Green/Leanna K. Peterson
14 DIM T(14),P(50),S(50,14),V(50,14)
16 TODAY$ = DATE$(0)
18 DATAOUT$ = "NONE"
20 RAD_TO_DEG = 180.0 / PI
22 DEG_TO_RAD = PI / 180.0
24 PAMB = 14.7
26 THETA0 = 0.0
28 THETA_F = 72.0 * DEG_TO_RAD
30 DT = 0.001
31 CNTMAX% = 500
32 I = 41230.
34 AREA1 = 5.7
36 PISDIA = 3.25
38 PAI = 3000.0 + PAMB
40 VAI = 2500.0
42 TSTOPMAX = 10000*12
44 PSTART = 3000.0 + PAMB
46 PCYLMAX = 3000.0 + PAMB
48 POWMAX = 0.3
50 TAMB = 70.0
52 PO = 5000.0 + PAMB
54 VE = 1200.0
56 EPS = 1.0
58 EPSP = EPS/8.0
60 DRIVER$ = "ENERGY RECOVERY"
62 WT = 6077.0
64 GAIN = 0.65
66 PCHARGE = 2700.0 + 14.7
68 RODDIA = 1.5
70 X = -2.0
72 Y = 35.5
74 L1 = 247.4
76 L2 = SQR(X^2+Y^2)
78 LCG = 161.748
80 L1E = 10.258
82 L2E = 33.09
84 GAMMA = ATN(-X/Y) + PI/2.0
86 GAMMAE = 109.4029 * DEG_TO_RAD
87 DRAG = .8
88 ORIFICE = .1
89 L3=57.002
90 L4=233.6862
91 LAMC=1.2747
92 LAMS=.2864
93 L3E=51.8913
94 L4E=240.3595
95 LAMEC=1.0552
96 LAMES=.4003
97 ACCMAX=1
99 GOSUB 8000
100 rem MAIN MENU
105 PRINT "WOULD YOU LIKE TO:"
110 PRINT "1. VIEW/MODIFY EQUILIBRATION PARAMETERS"
115 PRINT "2. VIEW/MODIFY ELEVATION CYLINDER PARAMETERS"
120 PRINT "3. VIEW/MODIFY OVERALL SYSTEM PARAMETERS"
125 PRINT "4. RUN DYNAMIC SIMULATION"
130 PRINT "5. RUN STATIC SIMULATION"
135 PRINT "6. END SESSION"
140 PRINT "(ENTER NUMBER)"
145 INPUT OPT1

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150 IF OPT1 = 1 THEN GOSUB 185
155 IF OPT1 = 2 THEN GOSUB 370
160 IF OPT1 = 3 THEN GOSUB 605
165 IF OPT1 = 4 THEN GOSUB 1000
170 IF OPT1 = 5 THEN GOSUB 12000
175 IF OPT1 = 6 THEN GOTO 16000
180 GOTO 100
185 rem EQUILIBRATION PARAMETER MODIFICATION MODULE
190 PRINT "WOULD YOU LIKE TO:"
195 PRINT "1. CHANGE PISTON AREA, CURRENT = ";A
200 PRINT "2. CHANGE EQUILIBRATOR VOLUME, CURRENT = ";V
205 PRINT "3. CHANGE AMBIENT TEMPERATURE, CURRENT = ";T
210 PRINT "4. CHANGE AMBIENT PRESSURE, CURRENT = ";P
215 PRINT "5. CHANGE STARTING PRESSURE AT 0 Q.E., CURRENT = ";P
220 PRINT "6. CHANGE CHARGE PRESSURE AT 72 DEG. F AND 14.7 PSI, CURRENT = ";P
225 PRINT "7. CHANGE X LOCATION OF WIRE ROPE, CURRENT = ";X
230 PRINT "8. CHANGE Y LOCATION OF WIRE ROPE, CURRENT = ";Y
235 PRINT "9. RETURN TO MAIN MENU"
240 PRINT "(ENTER NUMBER)"
245 INPUT OPT2
250 IF OPT2 <> 1 THEN GOTO 260
255 INPUT "ENTER PISTON AREA (INCH^2) ";AREA1
260 IF OPT2 <> 2 THEN GOTO 270
265 INPUT "ENTER EQUILIBRATOR VOLUME (INCH^3) ";VE
270 IF OPT2 <> 3 THEN GOTO 280
275 INPUT "ENTER AMBIENT TEMPERATURE (deg-F) ";TAMB
280 IF OPT2 <> 4 THEN GOTO 290
285 INPUT "ENTER AMBIENT PRESSURE (PSI) ";PAMB
290 IF OPT2 <> 5 THEN GOTO 305
295 INPUT "ENTER STARTING PRESSURE (PSI) ";PO
300 PO=PO+PAMB
305 IF OPT2 <> 6 THEN GOTO 320
310 INPUT "ENTER CHARGE PRESSURE (PSI) ";PCHARGE
315 PCHARGE=PCHARGE+14.7
320 IF OPT2 <> 7 THEN GOTO 340
325 INPUT "ENTER X LOCATION (IN) ";X
330 L2 = SQR(X^2+Y^2)
335 GAMMA = ATN(-X/Y) + PI/2.0
340 IF OPT2 <> 8 THEN GOTO 360
345 INPUT "ENTER Y LOCATION (IN) ";Y
350 L2 = SQR(X^2+Y^2)
355 GAMMA = ATN(-X/Y) + PI/2.0
360 IF OPT2 = 9 THEN RETURN
365 GOTO 185
370 rem CHANGE ELEVATION CYLINDER PARAMETERS MODULE
375 PRINT "WOULD YOU LIKE TO:"
380 PRINT " 1. CHANGE DRIVING FUNCTION, CURRENT = ";DR
385 PRINT " 2. CHANGE MAXIMUM MANUAL PRESSURE, CURRENT = ";PC
390 PRINT " 3. CHANGE CONTROL ORIFICE SIZE, CURRENT = ";OR
395 PRINT " 4. CHANGE STARTING DECELERATION PRESSURE, CURRENT = ";PS
400 PRINT " 5. CHANGE MAXIMUM DECELERATION TORQUE, CURRENT = ";TS
405 PRINT " 6. CHANGE ENERGY STORAGE ACCUMULATOR GAS VOLUME, CURRENT = ";VA
410 PRINT " 7. CHANGE ENERGY STORAGE ACCUMULATOR GAS PRESSURE, CURRENT = ";PA
415 PRINT " 8. CHANGE ELEVATION CYLINDER PISTON DIAMETER, CURRENT = ";PI
420 PRINT " 9. CHANGE GAIN VALUE, CURRENT = ";GA
425 PRINT "10. CHANGE ROD DIAMETER, CURRENT = ";RO
430 PRINT "11. RETURN TO MAIN MENU"
435 PRINT "(ENTER NUMBER) "
440 INPUT OPT3
445 IF OPT3 <> 1 THEN GOTO 485
450 PRINT "WOULD YOU LIKE TO USE:"
455 PRINT "1. MANUAL ELEVATION"

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460 PRINT "2. ENERGY RECOVERY ELEVATION"
465 PRINT "(ENTER NUMBER) "
470 INPUT OPT4
475 IF OPT4 = 1 THEN DRIVER$="MANUAL"
480 IF OPT4 = 2 THEN DRIVER$="ENERGY RECOVERY"
485 IF OPT3 <> 2 THEN GOTO 500
490 INPUT "ENTER PEAK MANUAL PRESSURE (PSI) ",PCYLMAX
495 PCYLMAX=PCYLMAX+PAMB
500 IF OPT3 <> 3 THEN GOTO 510
505 INPUT "ENTER CONTROL ORIFICE SIZE (IN) ",ORIFICE
510 IF OPT3 <> 4 THEN GOTO 525
515 INPUT "ENTER STARTING DECELERATION PRESSURE (PSI) ",PSTART
520 PSTART=PSTART+PAMB
525 IF OPT3 <> 5 THEN GOTO 540
530 INPUT "ENTER MAXIMUM DECELERATION TORQUE (FT-LB) ",TSTOPMAX
535 TSTOPMAX = TSTOPMAX * 12.0
540 IF OPT3 <> 6 THEN GOTO 550
545 INPUT "ENTER ACCUMULATOR GAS VOLUME (CU-IN) ",VAI
550 IF OPT3 <> 7 THEN GOTO 565
555 INPUT "ENTER ACCUMULATOR GAS PRESSURE (PSI) ",PAI
560 PAI=PAI+PAMB
565 IF OPT3 <> 8 THEN GOTO 575
570 INPUT "ENTER PISTON DIAMETER (IN) ",PISDIA
575 IF OPT3 <> 9 THEN GOTO 585
580 INPUT "ENTER GAIN ",GAIN
585 IF OPT3 <> 10 THEN GOTO 595
590 INPUT "ENTER ROD DIAMETER (IN) ",RODDIA
595 IF OPT3 = 11 THEN GOTO 100
600 GOTO 370
605 rem CHANGE SYSTEM PARAMETERS MODULE
610 PRINT "WOULD YOU LIKE TO:"
615 PRINT "1. CHANGE STARTING ELEVATION, CURRENT = ";THETA0*RAD_TO_DEG
620 PRINT "2. CHANGE ENDING ELEVATION, CURRENT = ";THETA0*RAD_TO_DEG
625 PRINT "3. CHANGE DATA SAMPLING INTERVAL, CURRENT = ";CNTMAX%
630 PRINT "4. CHANGE CONVERGENCE TOLERANCE, CURRENT = ";ACCMAX
635 PRINT "5. CHANGE DATA CAPTURE FILE NAME, CURRENT = ";DATAOUT$
640 PRINT "6. RETURN TO MAIN MENU"
645 PRINT "(ENTER NUMBER)"
650 INPUT OPT5
655 IF OPT5 <> 1 THEN GOTO 670
660 INPUT "ENTER STARTING ELEVATION (DEGREES) ",THETA0
665 THETA0=THETA0*DEG_TO_RAD
670 IF OPT5 <> 2 THEN GOTO 685
675 INPUT "ENTER ENDING ELEVATION (DEGREES) ",THETA0
680 THETA0=THETA0*DEG_TO_RAD
685 IF OPT5 <> 3 THEN GOTO 695
690 INPUT "ENTER DATA SAMPLING INTERVAL ",CNTMAX%
695 IF OPT5 <> 4 THEN GOTO 705
700 INPUT "ENTER CONVERGENCE TOLERANCE (FT-LB) ",ACCMAX
705 IF OPT5 <> 5 THEN GOTO 715
710 INPUT "ENTER NEW OUTPUT FILE NAME (INCLUDE EXTENSION) ",DATAOUT$
715 IF OPT5 = 6 THEN RETURN
720 GOTO 605
1000 rem PERFORM SIMULATION MODULE
1005 rem
1006 SWITCH1=0
1007 TEMPP=0
1008 ALAST=1
1009 BLAST=13
1010 IF DATAOUT$ <> "NONE" THEN GOSUB 13000
1015 rem
1020 CNT% = 0

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1025 PSTOPMAX = PSTART/GAIN
1030 TSTOPP = TSTOPMAX/GAIN
1035 rem SINCE THERE ARE 2 CYLINDERS, MULTIPLY THE AREA BY 2:
1040 AREA2 = 2.0 * PI * ((PISDIA^2/4.0) - (RODDIA^2/4.0))
1045 AREA3 = 2.0 * PI * PISDIA^2/4.0
1050 INPUT "DO YOU WISH TO SIMULATE DEPRESSION ALSO (Y/N) ", OPT$
1055 VOLUME1 = 0
1060 FLAG1 = 0
1065 FLAG2 = 0
1070 THETAS = THETAF
1075 VMIN = 0.034907
1080 GOSUB 7000
1085 rem GOTO 1170
1090 GELI=GELO
1095 PRINT ""
1100 PRINT "ELEVATION CYCLE"
1105 PRINT "TIME","ELEVATION","ELEVATION","EQUILIBRATOR","ANGULAR","OVERTURN"
1110 PRINT "","","PRESSURE","PRESSURE","VELOCITY","TORQUE"
1115 PRINT "(SEC)","(DEG)","(PSI)","(PSI)","(DEG/SEC)","(FT-LB)"
1120 IF DATAOUT$ <> "NONE" THEN PRINT #5; ""
1125 IF DATAOUT$ <> "NONE" THEN PRINT #5; "ELEVATION CYCLE"
1130 IF DATAOUT$ <> "NONE" THEN PRINT #5; "TIME","ELEVATION","ELEVATION","EQU
1135 IF DATAOUT$ <> "NONE" THEN PRINT #5; "","","PRESSURE","PRESSURE","VELOCI
1140 IF DATAOUT$ <> "NONE" THEN PRINT #5; "(SEC)","(DEG)","(PSI)","(PSI)","(D
1145 IF DATAOUT$ <> "NONE" THEN PRINT #5; ""
1150 rem
1155 rem OPEN & INITIALIZE THE OUTPUT FILES:
1160 GOSUB 14000
1165 rem
1170 PRINT ""
1175 rem TME=CURRENT TIME
1180 TME = 0
1185 rem THETA1 AND OMEGA1 = CONDITIONS AT BEGINNING OF TIME STEP
1190 SWITCH% = 0
1195 THETA1 = THETA0
1200 OMEGA1 = 0
1205 rem T= TIME INCREMENT TO BE GIVEN TO ITERATION MODULE
1210 rem DT=CURRENT TIME STEP
1215 T = DT
1220 rem THETA1S AND OMEGA1S = INITIAL CONDITIONS GIVEN TO ITERATION MODULE
1225 THETA1S = THETA1
1230 OMEGA1S = OMEGA1
1235 rem STME= CURRENT TIME GIVEN TO ITERATION MODULE
1240 STME = TME
1245 rem GO TO FORCE ITERATION MODULE:
1250 GOSUB 2000
1255 THETA2 = THETA2S
1260 OMEGA2 = OMEGA2S
1265 rem GO TO NEXT TIME STEP
1270 CNT% = CNT% +1
1275 IF CNT% <> CNTMAX% THEN GOTO 1330
1280 CNT% = 0
1285 PRINT TME,THETA*RAD TO DEG,PCYL-PAMB,PRESS-PAMB,OMEGA2*RAD TO DEG,OVERTU
1290 IF DATAOUT$ <> "NONE" THEN PRINT #5; TME,THETA*RAD_TO_DEG,PCYL-PAMB,PRES
1295 rem
1310 PRINT #6 USING "#####", TME;
1312 PRINT #6 USING "#####", THETA*RAD_TO_DEG
1315 PRINT #7, TME, PCYL-PAMB, PRESS-PAMB
1320 PRINT #8, TME, FLOWELEV, FLOWEQUIL
1325 rem
1330 IF THETA2 >= THETAF THEN GOTO 1360
1335 IF OMEGA2 <= 0 THEN GOTO 1360

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1340 THETA1 = THETA2
1345 OMEGA1 = OMEGA2
1350 TME = TME + DT
1355 GOTO 1215
1360 rem GUN DEPRESSION ROUTINE
1361 SWITCH1=0
1362 TEMPP=0
1365 IF (OPT$ = "N") or (OPT$ = "n") THEN GOTO 1575
1370 IF SWITCH% = 1 THEN GOTO 1560
1375 FLAG1 = 0
1380 FLAG2 = 0
1385 TEMP = TAMB
1390 OMEGA2 = 0
1395 THETA2 = THETA1
1400 rem GO TO DATA BASED ON TEMP & SPECIFIC VOLUME MODULE:
1405 GOSUB 11000
1406 GOSUB 9000
1410 ENTO = ENT
1415 PRINT ""
1420 PRINT "PRESSURE AFTER EXTENDED TIME = ";PRESS
1421 PRINT "ELEVATION CYLINDER STROKE = ";ABS(GELF-GELO)
1422 PRINT "TEMPERATURE COMPENSATION VOLUME = ";VCOMP
1425 PRINT ""
1430 INPUT DUMMY
1435 PRINT "DEPRESSION CYCLE"
1440 PRINT "TIME","ELEVATION","ELEVATION","EQUILIBRATOR","ANGULAR","OVERTURN"
1445 PRINT "","","PRESSURE","PRESSURE","VELOCITY","TORQUE"
1450 PRINT "(SEC)","(DEG)","(PSI)","(PSI)","(DEG/SEC)","(FT-LBS)"
1455 PRINT ""
1460 IF DATAOUT$ <> "NONE" THEN PRINT #5; "PRESSURE AFTER EXTENDED TIME = ";P
1461 IF DATAOUT$ <> "NONE" THEN PRINT #5; "ELEVATION CYLINDER STROKE = ";ABS(
1462 IF DATAOUT$ <> "NONE" THEN PRINT #5; "TEMPERATURE COMPENSATION VOLUME =
1465 IF DATAOUT$ <> "NONE" THEN PRINT #5; ""
1470 IF DATAOUT$ <> "NONE" THEN PRINT #5; "DEPRESSION CYCLE"
1475 IF DATAOUT$ <> "NONE" THEN PRINT #5; "TIME","ELEVATION","ELEVATION","EQU
1480 IF DATAOUT$ <> "NONE" THEN PRINT #5; "","","PRESSURE","PRESSURE","VELOC
1485 IF DATAOUT$ <> "NONE" THEN PRINT #5; "(SEC)","(DEG)","(PSI)","(PSI)","(D
1490 IF DATAOUT$ <> "NONE" THEN PRINT #5; ""
1495 rem
1500 rem REINITIALIZE:
1505 VOLUME1 = VOLUME
1510 THETA1 = THETA1
1515 OMEGA1 = 0
1520 REM TME = 0
1525 THETA1 = THETA0
1530 VMIN = -VMIN
1535 GELI = GELF
1540 SWITCH% = 1
1545 rem USING "NEGATIVE" AREAS TO REVERSE THE SIGN OF THE TORQUE:
1550 AREA2 = -2.0 * PI * PISDIA^2/4.0
1555 AREA3 = -2.0 * PI * ((PISDIA^2/4.0) - (RODDIA^2/4.0))
1560 IF THETA2 <= THETA0 THEN GOTO 1575
1565 GOTO 1340
1570 rem
1575 CLOSE #5, #6, #7, #8
1580 RETURN
2000 rem FORCE ITERATION MODULE
2001 LOOP%=1
2005 rem THETA AND OMEGA = CONDITIONS SENT TO FORCE DETERMINATION MODULES
2010 THETA = THETA1S
2015 OMEGA = OMEGA1S
2020 rem GO TO FORCE DETERMINATION MODULE:

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2025 GOSUB 3000
2030 PCYL1 = PCYL
2035 rem T1 = TORQUE AT BEGINNING OF TIME STEP
2040 rem TORQUE = TOTAL TORQUE DETERMINED BY FORCE MODULES
2045 T1 = TORQUE
2050 rem TM1=INITIAL MEAN FORCE GUESS
2055 TM1 = T1
2060 rem ANGACCEL = ANGULAR ACCELERATION OF THE BARREL (RAD/SEC^2)
2065 rem I = MASS MOMENT OF INERTIA OF BARREL (SLUG-FT^2)
2070 rem NOTE: TM1 MUST BE IN FT-LB UNITS:
2075 ANGACCEL = (TM1 / 12.0) / I
2080 OMEGA2S= OMEGA1S + ANGACCEL * T
2085 THETA2S= THETA1S + OMEGA1S * T + 0.5 * ANGACCEL * T^2
2090 THETA = THETA2S
2095 OMEGA = OMEGA2S
2100 rem GO TO FORCE DETERMINATION MODULE:
2105 GOSUB 3000
2110 PCYL2 = PCYL
2115 IF PCYL2 < 0 THEN GOTO 2125
2120 GOTO 2130
2125 IF PCYL1 > 0 THEN GOTO 2190
2130 IF PCYL2 > 0 THEN GOTO 2140
2135 GOTO 2145
2140 IF PCYL1 < 0 THEN GOTO 2190
2145 rem T2 = TORQUE AT THE END OF THE TIME STEP
2150 T2 = TORQUE
2155 rem TM2= NEXT MEAN TORQUE GUESS
2160 TM2 = (T2+T1)/2
2165 rem ACC= NUMBER USED TO CHECK PRECISION OF ITERATION
2170 ACC = ABS(TM2-TM1)
2175 IF ACC <= ACCMAX THEN GOTO 2190
2180 TM1 = TM2
2181 IF LOOP% >= 1000 THEN PRINT "CONVERGENCE FAILURE, ACCMAX = ";ACCMAX
2182 IF LOOP% >= 1000 THEN GOTO 100
2183 LOOP%=LOOP%+1
2185 GOTO 2075
2190 RETURN
3000 rem FORCE DETERMINATION MODULE
3005 rem GO TO GEOMETRY DETERMINATION MODULE:
3010 GOSUB 4000
3015 rem GO TO EQUILIBRATOR FORCE DETERMINATION MODULE:
3020 GOSUB 5000
3025 rem GO TO ELEVATION CYLINDER FORCE DETERMINATION MODULE:
3030 GOSUB 6000
3035 rem TELEV = TORQUE EXERTED BY THE ELEVATION CYLINDER
3040 rem TEQUIL= TORQUE EXERTED BY THE EQUILIBRATION CYLINDER
3045 rem TGRAV = TORQUE EXERTED BY GRAVITY
3046 REM GOTO OVERTURNING TORQUE MODULE
3047 GOSUB 15000
3049 TORQUE = TELEV + TEQUIL - TGRAV
3065 RETURN
4000 rem GEOMETRY DETERMINATION MODULE
4010 rem WT = WEIGHT OF COMPONENTS TO BE ELEVATED/DEPRESSED, LBS
4020 rem SEE SKETCHES FOR DEFINITIONS OF THE FOLLOWING PARAMETERS.
4030 rem D, RP, GEL, RPE ARE IN INCHES NOW (5 NOV 86 LKLP).
4040 rem
4050 rem THE FOLLOWING VARIABLES DEFINE THE EQUILIBRATION
4060 rem CYLINDER POSITION/PARAMETERS
4070 ALPHA = GAMMA - THETA + .0344
4080 DEQ = (SQRT(L1^2 + L2^2 - 2 * L1*L2 * COS(ALPHA)))
4090 SINB = L1 * SIN(ALPHA) / DEQ
4100 IF SINB -> 1 THEN BETA=1.5708

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4110 IF SINB => 1 THEN GOTO 4130
4120 BETA=ATN(SINB/SQR(1-SINB*SINB))
4130 RP      = L2 * SINB
4140 TGRAV   = LCG * COS(THETA) * WT
4145 DELT=PI-ALPHA-BETA
4150 rem
4160 rem THE FOLLOWING VARIABLES DEFINE ELEVATION / DEPRESSION
4170 rem      CYLINDER LOCATION
4180 ALPHAE = GAMMAE - THETA
4190 GEL     = (SQR(L1E^2 + L2E^2 - 2.0 * L1E * L2E * COS(ALPHAE)))
4200 SINBE   = L1E * SIN(ALPHAE) / GEL
4210 IF SINBE => 1 THEN BETAE=1.5708
4220 IF SINBE => 1 THEN GOTO 4230
4221 BETAE=ATN(SINBE/SQR(1-SINBE*SINBE))
4230 RPE     = L2E * SINBE
4235 DELTE=PI-ALPHAE-BETAE
4240 BETA    = ATN(SINBE / SQR(1 - SINBE*SINBE))
4250 PHI     = PI - BETA - ALPHAE
4260 RETURN
5000 rem EQUILIBRATOR FORCE MODULE
5005 rem VOL = CURRENT SPECIFIC VOLUME OF THE EQUILIBRATION GAS
5010 rem VF  = FINAL VOLUME OF EQUILIBRATION GAS
5015 VOL     = (VE - ((DEQ-DF) * AREA1) - VCOMP) / MOLE
5020 rem ENT = CURRENT ENTROPY OF EQUILIBRATION GAS
5025 rem ENTO= INITIAL ENTROPY OF EQUILIBRATION GAS AT START OF SIMULATION
5030 ENT     = ENTO
5035 rem GO TO DATA BASED ON SPECIFIC VOLUME & ENTROPY MODULE:
5040 GOSUB 10000
5045 rem PRESS = CURRENT PRESSURE OF EQUILIBRATION GAS
5050 rem AREA1 = AREA OF EQUILIBRATION PISTON
5051 IF OMEGA = 0 THEN GOTO 5055
5052 TEQUIL=(PRESS-PAMB)*AREA1*RP-(OMEGA/ABS(OMEGA))*2500*RP
5053 GOTO 5060
5055 TEQUIL   = (PRESS-PAMB) * AREA1 * RP
5060 rem
5065 rem FLOWEQUIL = FLOWRATE THRU EQUILIBRATION CYLINDER (GAL/MIN)
5070 rem VELD      = VELOCITY ALONG D (IN/S). FROM THE GEOMETRY:
5075 VELD         = L1 * OMEGA * (SIN(ALPHA) * L2)/DEQ
5080 FLOWEQUIL    = (VELD * AREA1 * 60.0 / 231.0)
5085 RETURN
6000 rem ELEVATION CYLINDER FORCE MODULE
6005 rem PRINT "ELEVATION MODULE"
6010 REM IF DRIVER$ = "MANUAL" THEN GOTO 6210
6020 IF SWITCH% = 1 THEN GOTO 6055
6025 IF OMEGA <= VMIN THEN GOTO 6035
6030 GOTO 6070
6035 IF FLAG1 = 1 THEN GOTO 6380
6040 GOTO 6070
6055 IF OMEGA >= VMIN THEN GOTO 6065
6060 GOTO 6070
6065 IF FLAG1 = 1 THEN GOTO 6380
6070 IF DRIVER$ = "MANUAL" THEN GOTO 6210
6071 rem VOLUME=VOLUME OF FLUID USED SINCE START OF SIMULATION
6075 rem ENERGY RECOVERY ROUTINE
6080 rem FOR ELEVATION (& STATIC ANALYSIS), VOLUME1 = 0.0
6084 rem FOR DEPRESSION, VOLUME1 = volume from elevating
6085 SCYL   = L1E * OMEGA * COS((PI/2)-PHI)
6086 FLOWELEV = (SCYL * AREA2 * 60.0 / 231.0)
6090 VOLUME  = ABS((GELI-GEL) * AREA2) + VOLUME1
6095 rem PCYL = CURRENT PRESSURE IN ELEVATION CYLINDER
6100 rem PAI  = INITIAL GAS PRESSURE IN STORAGE ACCUMULATOR
6105 rem VAI  = INITIAL GAS VOLUME IN STORAGE ACCUMULATOR

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6110 PCYL      = (((PAI)*VAI^1.4) / (VAI+VOLUME)^1.4) - .8*(FLOWELEV/(29.81*DRAG
6111 IF PCYL < 0 THEN PCYL=0
6115 rem ENERGY=CURRENT KINETIC ENERGY OF THE BARREL ASSEMBLY
6120 ENERGY   = 0.5 * I * OMEGA^2
6135 rem TSTOP= OPTIMUM TORQUE REQUIRED TO STOP THE BARREL BEFORE THETA F
6140 rem IF THETA >= THETA F THEN RETURN
6145 TSTOP     = (ENERGY/(ABS(THETA S-THETA)-.008))*12
6150 rem PSTOP= OPTIMUM PRESSURE REQUIRED TO STOP THE BARREL
6155 PSTOP     = ABS(TSTOP / (AREA3 * RPE)) + PAMB
6160 rem TSTOPMAX=MAXIMUM ALLOWABLE STOPPING TORQUE
6165 rem PSTOPMAX=MAXIMUM ALLOWABLE STOPPING PRESSURE
6170 IF TSTOP >= TSTOPP THEN FLAG1=1
6175 IF PSTOP >= PSTOPMAX THEN FLAG1=1
6180 IF FLAG1 = 1 THEN GOTO 6355
6185 rem IF TSTOP >= TSTOPMAX THEN GOTO 6340
6190 rem IF PSTOP >= PSTOPMAX THEN GOTO 6340
6195 TELEV     = (PCYL-PAMB) * AREA2 * RPE
6200 rem PRINT TELEV/12.0,PCYL,"NORM",AREA2,RPE
6205 GOTO 6410
6210 rem MANUAL POWER ROUTINE
6215 rem PHI   = ANGLE BETWEEN CYLINDER AND BARREL
6220 rem SCYL  = SPEED OF THE ELEVATION CYLINDER
6225 SCYL     = LIE * OMEGA * COS((PI/2)-PHI)
6230 rem PCYLMAX = MAXIMUM PRESSURE POSSIBLE DURING MANUAL ELEVATION
6240 rem FLOWELEV = FLOWRATE INTO ELEVATION CYLINDER
6245 rem AREA2   = AREA OF ELEVATION CYLINDER PISTON
6250 FLOWELEV   = ABS(SCYL * AREA2 * 60.0 / 231.0)
6251 PCYL      = PCYLMAX - .8*(FLOWELEV/(29.81*DRAG*ORIFICE^2))^2
6255 rem POWER  = POWER BEING EXERTED BY ELEVATION CYLINDER
6260 POWER     = ABS((FLOWELEV * (PCYL+.8*(FLOWELEV/(29.81*DRAG*ORIFICE^2))^2)
6265 VOLUME    = (GELI-GEL) * AREA2
6270 rem POWMAX = MAXIMUM POWER ALLOWABLE FOR MANUAL ELEVATION (.3 hp)
6275 IF POWER > POWMAX THEN PCYL=ABS(POWMAX*1714/FLOWELEV)+PAMB-.8*(FLOWELEV/
6280 ENERGY   = 0.5 * I * OMEGA^2
6285 rem TSTOP  = OPTIMUM TORQUE REQUIRED TO STOP THE BARREL BEFORE THETA F
6290 TSTOP     = (ENERGY/(ABS(THETA S-THETA)-.008))*12
6295 rem PSTOP  = OPTIMUM PRESSURE REQUIRED TO STOP THE BARREL
6300 PSTOP     = ABS(TSTOP/(AREA3*RPE))+PAMB
6305 rem TSTOPMAX = MAXIMUM ALLOWABLE STOPPING TORQUE
6310 rem PSTOPMAX = MAXIMUM ALLOWABLE STOPPING PRESSURE
6315 IF TSTOP >= TSTOPP THEN FLAG1=1
6320 IF PSTOP >= PSTOPMAX THEN FLAG1=1
6325 IF FLAG1 = 1 THEN GOTO 6355
6330 rem IF TSTOP >= TSTOPMAX THEN GOTO 6340
6335 rem IF PSTOP >= PSTOPMAX THEN GOTO 6340
6336 IF PCYL < 0 THEN PCYL=0
6341 TELEV     = (PCYL-PAMB) * AREA2 * RPE
6345 rem
6350 GOTO 6410
6355 rem DECELERATION ROUTINE
6360 PCYL      = -PSTOP * GAIN
6365 TELEV     = (PCYL+PAMB) * AREA3 * RPE
6370 rem PRINT TELEV/12.0,PCYL,"DECEL",AREA3,RPE
6375 GOTO 6410
6380 rem CREEP ROUTINE
6385 TELEV     = TGRAV - TEQUIL
6390 PCYL      = ((TELEV/RPE) / (AREA2)) + PAMB
6395 rem PRINT TELEV/12.0,PCYL,"CREEP",AREA2,RPE
6400 GOTO 6410
6410 RETURN
7000 rem INITIAL GAS AND GEOMETRIC DATA MODULE
7005 TEMP      = 72.0

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7010 PRESS = PCHARGE
7015 GOSUB 9000
7020 MOLE = VE / VOL
7025 rem THETAO= INITIAL POSITION
7030 THETA = 0.0
7035 GOSUB 4000
7040 rem DO = INITIAL ROPE LENGTH
7045 DO = DEQ
7050 rem THETA=FINAL POSITION
7055 THETA = 72.0 * DEG_TO_RAD
7060 GOSUB 4000
7065 DF = DEQ
7070 rem DF = FINAL ROPE LENGTH
7075 THETA = THETAO
7080 GOSUB 4000
7085 DS = DEQ
7090 GELO = GEL
7095 THETA = THETA
7100 GOSUB 4000
7105 GELF = GEL
7110 rem TEMP = CURRENT TEMPERATURE
7115 TEMP = TAMB
7120 rem TAMB = OUTSIDE AMBIENT TEMPERATURE
7125 rem PO = INITIAL EQUILIBRATION GAS PRESSURE
7130 PRESS = PO
7135 GOSUB 9000
7140 rem TEMPO = INITIAL EQUILIBRATION GAS TEMPERATURE
7145 rem PRESSO = INITIAL EQUILIBRATION GAS PRESSURE
7150 rem VOLO = INITIAL EQUILIBRATION GAS SPECIFIC VOLUME
7155 rem VOL = CURRENT EQUILIBRATION GAS SPECIFIC VOLUME
7160 rem ENTO = INITIAL EQUILIBRATION GAS ENTROPY
7165 rem ENT = CURRENT EQUILIBRATION GAS ENTROPY
7170 VCOMP = VE - VOL*MOLE - ((DO-DF) * AREA1)
7175 VOLO = (VE - VCOMP - ((DS-DF) * AREA1)) / MOLE
7180 TEMPO = TAMB
7185 VOL = VOLO
7190 TEMP = TEMPO
7195 GOSUB 11000
7200 PRESSO = PRESS
7205 ENTO = ENT
7210 RETURN
8000 rem DATA INPUT MODULE
8005 OPEN "NITROGEN.DAT" FOR INPUT AS FILE #1
8010 rem OPEN "nitrogen.eng" FOR INPUT AS FILE #1
8015 INPUT #1,TITLE$
8020 INPUT #1,BLANK$
8025 INPUT #1,TEMP$,T(1),T(2),T(3),T(4),T(5),T(6),T(7),T(8),T(9),T(10),T(11),
8030 rem INPUT #1,TEMP$,T(1),T(2),T(3),T(4),T(5),T(6),T(7),T(8)
8035 INPUT #1,BLANK$
8040 INPUT #1,PRESS$
8045 A=1
8050 INPUT #1,P(A),V(A,1),V(A,2),V(A,3),V(A,4),V(A,5),V(A,6),V(A,7),V(A,8),V(
8055 rem INPUT #1,P(A),V(A,1),V(A,2),V(A,3),V(A,4),V(A,5),V(A,6),V(A,7),V(
8060 INPUT #1,S(A,1),S(A,2),S(A,3),S(A,4),S(A,5),S(A,6),S(A,7),S(A,8),S(A,9),
8065 rem INPUT #1,S(A,1),S(A,2),S(A,3),S(A,4),S(A,5),S(A,6),S(A,7),S(A,8)
8070 IF A = 45 THEN GOTO 8095
8075 rem IF A = 9 THEN GOTO 8095
8080 A=A+1
8085 INPUT #1,BLANK$
8090 GOTO 8050
8095 CLOSE #1
8100 RETURN

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9000 rem DATA BASED ON TEMPERATURE AND PRESSURE MODULE
9005 PRESS=PRESS/100
9010 A=1
9015 IF P(A) >= PRESS THEN GOTO 9035
9020 A=A+1
9025 IF A > 45 THEN GOTO 9155
9030 GOTO 9015
9035 PH=P(A)
9040 PL=P(A-1)
9045 B=1
9050 IF T(B) >= TEMP THEN GOTO 9070
9055 B=B+1
9060 IF B > 14 THEN GOTO 9155
9065 GOTO 9050
9070 TH=T(B)
9075 TL=T(B-1)
9080 S1L=S(A-1,B-1)
9085 S1H=S(A-1,B)
9090 S2L=S(A,B-1)
9095 S2H=S(A,B)
9100 SL=S1L+((PRESS-PL)/(PH-PL))*((S2L-S1L))
9105 SH=S1H+((PRESS-PL)/(PH-PL))*((S2H-S1H))
9110 ENT=SL+(ABS(TEMP-TL)/ABS(TH-TL))*ABS(SH-SL)
9115 V1L=V(A-1,B-1)
9120 V1H=V(A-1,B)
9125 V2L=V(A,B-1)
9130 V2H=V(A,B)
9135 VL=V1L+((PRESS-PL)/(PH-PL))*((V2L-V1L))
9140 VH=V1H+((PRESS-PL)/(PH-PL))*((V2H-V1H))
9145 VOL=VL+(ABS(TEMP-TL)/ABS(TH-TL))*ABS(VH-VL)
9150 GOTO 9160
9155 PRINT "DATA POINT OUT OF RANGE, PRESS = ";PRESS,"TEMP = ";TEMP
9160 PRESS=PRESS*100
9165 RETURN
10000 rem DATA BASED ON SPECIFIC VOLUME AND ENTROPY MODULE
10001 IF TEMPP > -100 THEN GOTO 10010
10002 PRESS=PAMB
10003 GOTO 10480
10010 SWITCH1=0
10020 DIFFP=100000
10030 A=1
10040 B=13
10050 REM      B= 8
10060 IF V(A,B) <= VOL THEN GOTO 10080
10070 GOTO 10090
10080 IF V(A,B+1) > VOL THEN GOTO 10180
10090 B=B-1
10100 IF B <= 0 THEN GOTO 10120
10110 GOTO 10060
10120 B=13
10130 REM      B= 8
10140 A=A+1
10150 IF A >= 45 THEN GOTO 10300
10160 REM      IF A >= 9 THEN GOTO 10140
10170 GOTO 10060
10180 IF S(A,B) <= ENT THEN GOTO 10200
10190 GOTO 10090
10200 REM IF S(A-1,B+1) > ENT THEN GOTO 10071
10210 REM GOTO 10020
10220 DIFF=ABS((VOL-V(A,B))/(V(A,B+1)-V(A,B))-(ENT-S(A,B))/(S(A,B+1)-S(A,B)))
10230 IF DIFF < DIFFP THEN GOTO 10250
10240 GOTO 10090

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10250 DIFFP=DIFF
10260 AA=A
10270 BB=B
10280 SWITCH1=1
10290 GOTO 10090
10300 IF SWITCH1 = 0 THEN GOTO 10460
10310 A=AA
10320 B=BB
10330 C=A+1
10340 D=B+1
10350 TV1=T(B)+((VOL-V(A,B))*(T(B+1)-T(B))/(V(A,B+1)-V(A,B)))
10360 TV2=T(D)+((VOL-V(C,D))*(T(D+1)-T(D))/(V(C,D+1)-V(C,D)))
10370 TS1=T(B)+((ENT-S(A,B))*(T(B+1)-T(B))/(S(A,B+1)-S(A,B)))
10380 TS2=T(D)+((ENT-S(C,D))*(T(D+1)-T(D))/(S(C,D+1)-S(C,D)))
10390 MV=(TV2-TV1)/(P(C)-P(A))
10400 BV=TV1-(MV*P(A))
10410 MS=(TS2-TS1)/(P(C)-P(A))
10420 BSS=TS1-(MS*P(A))
10430 TEMP=(BV-((MV*BSS)/MS))/(1-(MV/MS))
10440 PRESS=(TEMP-BSS)/MS
10450 GOTO 10470
10460 PRINT "DATA POINT OUT OF RANGE, VOL = ";VOL,"ENT = ";ENT
10461 GOTO 10002
10470 PRESS=PRESS*100
10480 PRESSP=PRESS
10481 VOLP=VOL
10482 IF TEMP < TEMPP THEN TEMPP=TEMP
10483 ENTP=ENT
10484 ALAST=A
10485 BLAST=B
10486 RETURN
11000 rem DATA BASED ON TEMPERATURE AND SPECIFIC VOLUME MODULE
11005 B=14
11015 A=1
11020 IF T(B) < TEMP THEN GOTO 11040
11025 B=B-1
11030 IF B <= 0 THEN GOTO 11160
11035 GOTO 11020
11040 IF V(A,B) < VOL THEN GOTO 11065
11045 A=A+1
11050 IF A > 45 THEN GOTO 11160
11060 GOTO 11040
11065 C=A+1
11070 D=B+1
11075 TV1=T(B)+((VOL-V(A,B))*(T(B+1)-T(B))/(V(A,B+1)-V(A,B)))
11080 TV2=T(D)+((VOL-V(C,D))*(T(D+1)-T(D))/(V(C,D+1)-V(C,D)))
11085 MV=(TV2-TV1)/(P(C)-P(A))
11090 BV=TV1-(MV*P(A))
11095 PRESS=(TEMP-BV)/MV
11100 PH=P(A+1)
11105 PL=P(A)
11110 TH=T(B+1)
11115 TL=T(B)
11120 S1L=S(A,B)
11125 S1H=S(A,B+1)
11130 S2L=S(A+1,B)
11135 S2H=S(A+1,B+1)
11140 SL=S1L-(ABS(PRESS-PL)/ABS(PH-PL))*(ABS(S2L-S1L))
11145 SH=S1H-(ABS(PRESS-PL)/ABS(PH-PL))*(ABS(S2H-S1H))
11150 ENT=SL+(ABS(TEMP-TL)/ABS(TH-TL))*ABS(SH-SL)
11155 GOTO 11165
11160 PRINT "DATA POINT OUT OF RANGE, TEMP = ";TEMP,"VOL = ";VOL

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11165 PRESS=PRESS*100
11170 RETURN
12000 rem STATIC ANALYSIS MODULE
12001 TEMPP=0
12002 rem
12004 IF DATAOUT$ <> "NONE" THEN GOSUB 13000
12006 FLAG1 = 0
12007 ALAST=1
12008 BLAST=13
12010 FLAG2 = 0
12011 MATCHTOT = 0
12012 MATCHMAX = 0
12015 PSTOPMAX = PSTART/GAIN
12020 rem SINCE THERE ARE 2 CYLINDERS, MULTIPLY THE AREA BY 2:
12025 AREA2 = 2.0 * PI * ((PISDIA^2/4.0) - (RODDIA^2/4.0))
12030 AREA3 = 2.0 * PI * PISDIA^2/4.0
12035 OMEGA = 0
12040 PRINT "THETA","TGRAV","TEQUIL","TELEV","PRESS","TEQUILA"
12042 PRINT " "
12044 IF DATAOUT$ <> "NONE" THEN PRINT #5; "THETA","TGRAV","TEQUIL","TELEV"," "
12045 IF DATAOUT$ <> "NONE" THEN PRINT #5; " "
12050 rem
12055 OPEN "STATIC.GRL" FOR OUTPUT AS FILE #2
12065 PRINT #2,"TITLE STATIC ANALYSIS RESULTS - Nitrogen"
12070 TIMENOW$ = TIMES(0)
12075 PRINT #2,"SUBTITLE ";DRIVERS$;" ";TODAYS$;" ";TIMENOW$
12080 PRINT #2,"HORIZONTAL LABEL THETA (degrees)"
12085 PRINT #2,"VERTICAL LABEL TORQUE (ft-lb)"
12090 PRINT #2,"Y_LEGEND-gravity"
12095 PRINT #2,"Y_LEGEND equilibration"
12100 PRINT #2,"Y_LEGEND elevation"
12101 PRINT #2,"Y_LEGEND dyn equil"
12105 PRINT #2," "
12110 PRINT #2, "C THETA";" TGRAV";" TEQUIL";" TELEV";" DYNELEV"
12115 rem GO TO INITIAL GAS & GEOMETRIC DATA MODULE:
12120 GOSUB 7000
12125 THETA = -5.0 * DEG_TO_RAD
12130 GOSUB 4000
12135 VOL = (VE - ((DEQ-DF) * AREA1) - VCOMP) / MOLE
12136 ENT=ENTO
12137 GOSUB 10000
12138 TEQUILA=(PRESS-PAMB)*AREA1*RP
12139 P1=PRESS
12140 T1=TEMP
12141 V1=VOL
12142 S1=ENT
12143 TEMP = TAMB
12145 GOSUB 11000
12150 TEQUIL= (PRESS-PAMB)*AREA1*RP
12155 rem FOR ELEVATING ONLY:
12160 VOLUME = ABS(GELI - GEL) * AREA2
12165 rem ASSUME STATIC ANALYSIS IS ISOTHERMAL:
12170 PCYL = (PAI * VAI) / (VAI + VOLUME)
12175 TELEV= (PCYL-PAMB) * AREA2 * RPE
12176 MATCH=ABS(TGRAV-TEQUIL)
12177 MATCHTOT=MATCHTOT+MATCH
12178 IF MATCH > MATCHMAX THEN MATCHMAX=MATCH
12180 PRINT THETA*RAD TO DEG,TGRAV/12.0,TEQUIL/12.0,TELEV/12.0,PRESS-PAMB,TEQ
12182 IF DATAOUT$ <> "NONE" THEN PRINT #5; THETA*RAD_TO_DEG,TGRAV/12.0,TEQUIL
12183 rem
12185 PRINT #2 USING "####.##",THETA*RAD_TO_DEG;
12190 PRINT #2," ";

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12195 PRINT #2 USING "#####.-",TGRAV/12.0;
12200 PRINT #2 USING "#####.-",TEQUIL/12.0;
12205 PRINT #2 USING "#####.-",TELEV/12.0;
12206 PRINT #2 USING "#####.-",TEQUILA/12.0
12207 rem
12215 IF THETA >= 72.0 * DEG TO RAD THEN GOTO 12230
12220 THETA = THETA + 1.0 * DEG TO RAD
12225 GOTO 12130
12230 CLOSE #2, #5
12231 PRINT "AVERAGE EQUILIBRATION MISMATCH = ";MATCHTOT/(78*12)
12232 PRINT "MAXIMUM EQUILIBRATION MISMATCH = ";MATCHMAX/12
12233 PRINT "ELEVATION CYLINDER STROKE = ";ABS(GELF-GELO)
12240 RETURN
13000 rem WRITING DESIGN PARAMETERS TO OUTPUT FILE DATAOUT$:
13005 rem Module added 3 November 1986. LKLP
13010 rem
13015 OPEN DATAOUT$ FOR OUTPUT AS FILE #5
13020 IF OPT1 = 4 THEN PRINT #5;"DYNAMIC ANALYSIS"
13025 IF OPT1 = 5 THEN PRINT #5;"STATIC ANALYSIS"
13030 rem
13035 TIMENOW$ = TIME$(0)
13040 PRINT #5; DRIVER$;" ELEVATION      :      ";TODAY$;"      ";TIMENOW$
13045 PRINT #5; " "
13050 PRINT #5; "EQUILIBRATION CYLINDER PARAMETERS: "
13055 PRINT #5; "-----"
13060 PRINT #5; "PISTON AREA                                IN^2      ";
13063 PRINT #5 USING "#####.##", AREAL
13065 PRINT #5; "EQUILIBRATOR VOLUME                          IN^3      ";
13067 PRINT #5 USING "#####.##", VE
13070 PRINT #5; "AMBIENT TEMPERATURE                          deg-F     ";
13072 PRINT #5 USING "#####.##", TAMB
13075 PRINT #5; "AMBIENT PRESSURE                              LB/IN^2   ";
13077 PRINT #5 USING "#####.##", PAMB
13080 PRINT #5; "STARTING PRESSURE AT 0 Q.E.                  LB/IN^2   ";
13082 PRINT #5 USING "#####.##", PO-PAMB
13085 PRINT #5; "CHARGE PRESSURE AT 72 deg-F & 14.7 PSI      LB/IN^2   ";
13087 PRINT #5 USING "#####.##", PCHARGE-14.7
13090 PRINT #5; "X LOCATION OF WIRE ROPE                      INCH      ";
13092 PRINT #5 USING "#####.##", X
13095 PRINT #5; "Y LOCATION OF WIRE ROPE                      INCH      ";
13097 PRINT #5 USING "#####.##", Y
13100 PRINT #5; " "
13105 PRINT #5; "ELEVATION CYLINDER PARAMETERS: "
13110 PRINT #5; "-----"
13115 PRINT #5; "MAXIMUM MANUAL PRESSURE                      LB/IN^2   ";
13117 PRINT #5 USING "#####.##", PCYLMAX-PAMB
13120 PRINT #5; "MAXIMUM MANUAL POWER INPUT                   HP        ";
13122 PRINT #5 USING "#####.##", POWMAX;
13125 PRINT #5; "STARTING DECELERATION PRESS                  LB/IN^2   ";
13127 PRINT #5 USING "#####.##", PSTART-PAMB
13130 PRINT #5; "MAXIMUM DECELERATION TORQUE                  FT-LB     ";
13132 PRINT #5 USING "#####.##", TSTOPMAX/12.0
13135 PRINT #5; "ENERGY STORAGE ACCUMULATOR GAS VOLUME      IN^3      ";
13137 PRINT #5 USING "#####.##", VAI
13140 PRINT #5; "ENERGY STORAGE ACCUMULATOR GAS PRESSURE    LB/IN^2   ";
13142 PRINT #5 USING "#####.##", PAI-PAMB
13145 PRINT #5; "PISTON DIAMETER                             INCH      ";
13147 PRINT #5 USING "#####.##", PISDIA
13150 PRINT #5; "ROD DIAMETER                                INCH      ";
13152 PRINT #5 USING "#####.##", RODDIA
13155 PRINT #5; "GAIN VALUE                                   ";
13157 PRINT #5 USING "#####.##", GAIN

```

```

13160 PRINT #5; " "
13165 PRINT #5; "SYSTEM PARAMETERS: "
13170 PRINT #5; "-----"
13175 PRINT #5; "STARTING ELEVATION (THETAo)          DEGREES ";
13177 PRINT #5 USING "#####.###", THETAo*180.0/PI
13180 PRINT #5; "ENDING ELEVATION          (THETAf)    DEGREES ";
13182 PRINT #5 USING "#####.###", THETAf*180.0/PI
13185 PRINT #5; "ELEVATING WEIGHT          LBS ";
13187 PRINT #5 USING "#####.###", WT
13190 PRINT #5; "MASS MOMENT OF INERTIA (I)          SLUG-FT^2 ";
13192 PRINT #5 USING "#####.###", I
13195 PRINT #5; " "
13200 rem
13205 RETURN
14000 rem MODULE TO OPEN & INITIALIZE OUTPUT FILES:
14005 rem
14010 TIMENOW$ = TIME$(0)
14015 rem
14030 rem FILE FOR THETA -vs- TIME:
14035 OPEN "DYNTHETA.GRL" FOR OUTPUT AS FILE #6
14040 rem
14045 PRINT #6,"TITLE DYNAMIC ANALYSIS RESULTS - Nitrogen"
14050 PRINT #6,"SUBTITLE ";DRIVERS$;" ";TODAYS$;" ";TIMENOW$
14055 PRINT #6,"HORIZONTAL LABEL TIME (seconds)"
14060 PRINT #6,"VERTICAL LABEL THETA (degrees)"
14065 PRINT #6,"Y_LEGEND Elevation Angle"
14070 PRINT #6,""
14075 PRINT #6,"C TIME","ELEVATION"
14080 PRINT #6,"C (sec)","(degrees)"
14085 PRINT #6,""
14090 rem
14095 rem FILE FOR PCYL & PRESS -vs- TIME:
14100 OPEN "DYNPRESS.GRL" FOR OUTPUT AS FILE #7
14105 rem
14110 PRINT #7,"TITLE DYNAMIC ANALYSIS RESULTS - Nitrogen"
14115 PRINT #7,"SUBTITLE ";DRIVERS$;" ";TODAYS$;" ";TIMENOW$
14120 PRINT #7,"HORIZONTAL LABEL TIME (seconds)"
14125 PRINT #7,"VERTICAL LABEL PRESSURES (PSI)"
14130 PRINT #7,""
14135 PRINT #7,"Y_LEGEND PCYL : Elev"
14140 PRINT #7,"Y_LEGEND PRESS : Equil"
14145 PRINT #7,""
14150 PRINT #7,"C ", "ELEVATION","EQUILIBRATOR"
14155 PRINT #7,"C TIME", "PRESSURE", "PRESSURE"
14160 PRINT #7,"C (SEC)","(PSI)"," (PSI)"
14165 PRINT #7,""
14170 rem
14175 rem FILE FOR FLOWRATE -vs- TIME:
14180 OPEN "DYNFLOW.GRL" FOR OUTPUT AS FILE #8
14185 rem
14190 PRINT #8,"TITLE DYNAMIC ANALYSIS RESULTS - Nitrogen"
14195 PRINT #8,"SUBTITLE ";DRIVERS$;" ";TODAYS$;" ";TIMENOW$
14200 PRINT #8,"HORIZONTAL LABEL TIME (seconds)"
14205 PRINT #8,"VERTICAL LABEL FLOWRATE (gal/min)"
14210 PRINT #8,""
14215 PRINT #8,"Y_LEGEND Elevation"
14220 PRINT #8,"Y_LEGEND Equilibration"
14225 PRINT #8,""
14230 PRINT #8,"C TIME", "FLOWELEV", "FLOWEQUIL"
14235 PRINT #8,"C (SEC)","(GPM)"," (GPM)"
14240 PRINT #8,""
14245 rem

```

```
14250 RETURN
15000 REM OVERTURNING TORQUE CALCULATION MODULE
15020 OTEQUIL=(TEQUIL/RP)*L3*SIN(BETA+LAMS)
15060 OTELEV=(TELEV/RPE)*L3E*SIN(BETA+LAMES)
15070 FTX=(TEQUIL/RP)*COS(DELTA-THETA)+(TELEV/RPE)*COS(DELTA-THETA)
15080 FTY=(TEQUIL/RP)*SIN(THETA-DELTA)-(TELEV/RPE)*SIN(DELTA-THETA)+WT
15090 OTRUN=FTY*15-FTX*20
15100 OTGRAV=111485
15110 OVERTURN=OTGRAV+OTELEV+OTEQUIL+OTRUN
15900 RETURN
16000 END
```



when acceleration is 0 then

$$\text{overturning torque} = -\sin \lambda_E L_E \sin(\lambda_E - \beta)$$

when acceleration is 0 then

$$\text{overturning torque} = F_{EL} L_E \sin(\beta - \lambda_E)$$

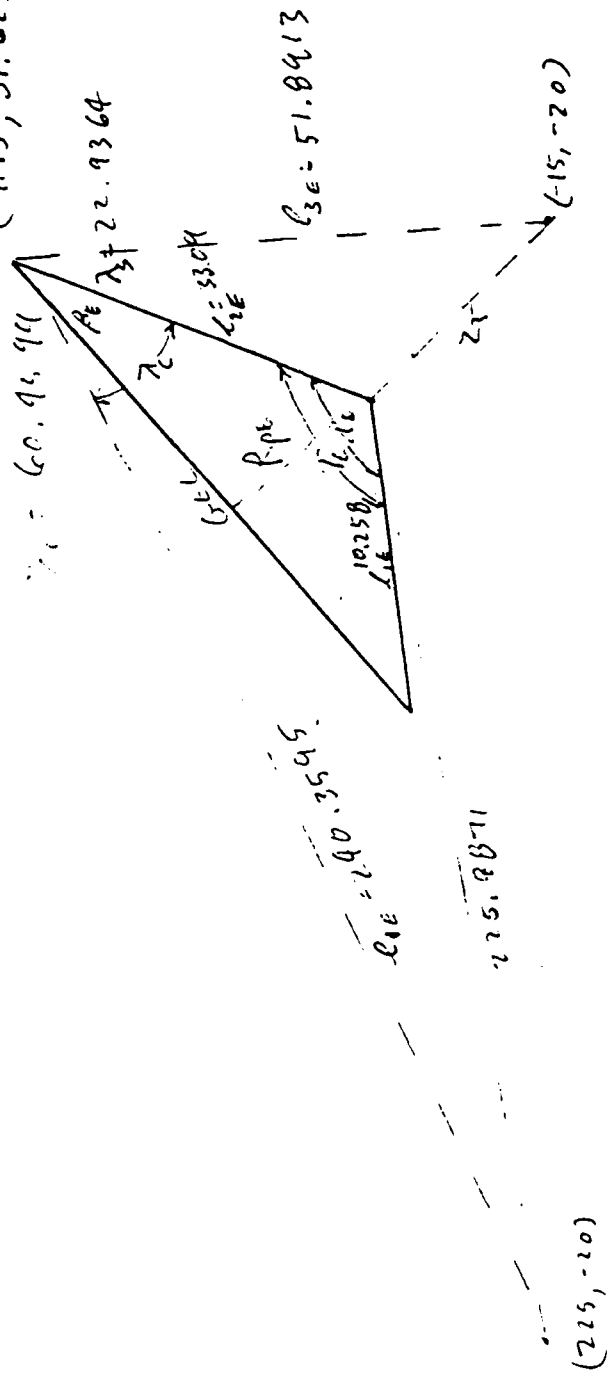
$$a_i = \gamma_E - 0$$

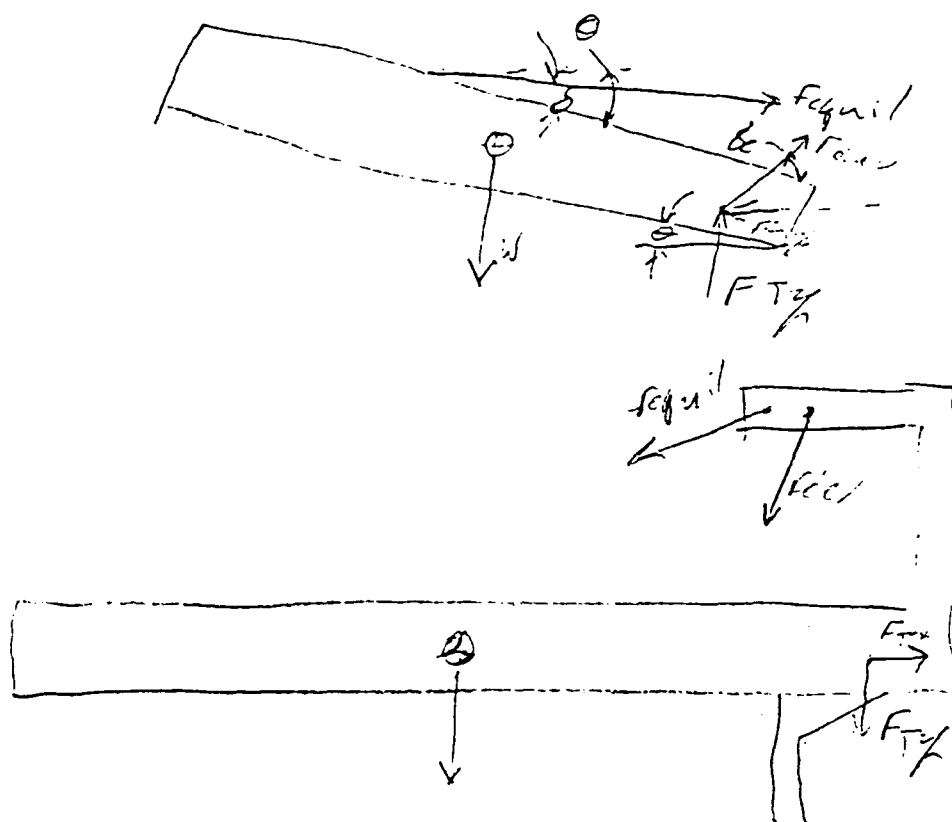
$$GEL = \sqrt{L_{1E}^2 + L_{2E}^2} - 2 L_{1E} L_{2E} \cos \lambda_E$$

$$\sin \beta_E = \frac{L_{1E} \sin \lambda_E}{GEL}$$

$$RP_E = L_{2E} \sin \beta_E$$

$$(-9.75, 31.625)$$





$$\delta = 180 - \alpha - \beta$$

$$\delta_e = 180 - \alpha_e - \beta_e$$

$$F_{T2} = F_{T1} \cos \delta + F_{T1} \sin \delta$$

$$F_{Tx} = W - F_{T1} \cos \delta - F_{T1} \sin \delta$$

$$F_{T1x} = F_{T1} \cos (\theta - \delta)$$

$$F_{T1y} = F_{T1} \sin (\theta - \delta)$$

$$F_{T2x} = F_{T2} \cos (\delta_e - \theta)$$

$$F_{T2y} = F_{T2} \sin (\delta_e - \theta)$$



S. DACKO - 3/13/87 40  
FOR J. GREEN

## FINAL EQUILIBRATION + ELEVATION RESULTS

1. ACCUMULATOR VOLUME : 1200 CU. IN.  
CHARGE PRESS. = 2690 PSI  
CALIB PRESS. = 5414 PSI (0° QE)

2. EQUIL. PISTON DIA. =  $3\frac{1}{8}$ "  
ROD DIA. =  $2\frac{1}{2}$ "

3. ELEV. PISTON DIA. = 3"  
ROD DIA. =  $1\frac{1}{2}$ "

MAX FLOW RATE : 14 GPM  
(VALVE W/ 3000 PSI DP AT 20 GPM)

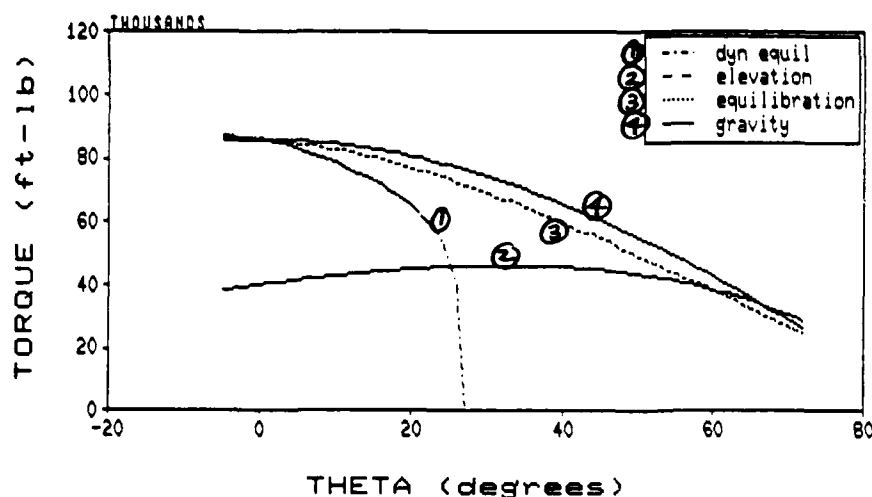
4. PEAK EQUIL PRESS = 6800 PSI (DEPR)  
NORMAL OP. PRESS = 5400 PSI (EQUIL)

### 5. OIL VOLUMES

<u>T, °F</u>	<u>VOLUME, CU. IN.</u>
-25	426.43
70	298.1
+160	179.4

# STATIC ANALYSIS RESULTS - Nitrogen

ENERGY RECOVERY 05-Mar-87 11:12 AM



## STATIC ANALYSIS

ENERGY RECOVERY ELEVATION : 05-Mar-87 11:12 AM

## EQUILIBRATION CYLINDER PARAMETERS:

PISTON AREA	IN^2	5.52
EQUILIBRATOR VOLUME	IN^3	1200.00
AMBIENT TEMPERATURE	deg-F	-25.00
AMBIENT PRESSURE	LB/IN^2	14.70
BALANCE PRESSURE	LB/IN^2	5414.00
BALANCE POSITION	DEG	0.00
CHARGE PRESSURE AT 70 deg-F & 14.7 PSI	LB/IN^2	2690.00
X LOCATION OF WIRE ROPE	INCH	-2.00
Y LOCATION OF WIRE ROPE	INCH	35.50

## ELEVATION CYLINDER PARAMETERS:

MAXIMUM MANUAL PRESSURE	LB/IN^2	3000.000
MAXIMUM MANUAL POWER INPUT	HP	0.300
STARTING DECELERATION PRESS	LB/IN^2	3000.000
MAXIMUM DECELERATION TORQUE	FT-LB	10000.000
ENERGY STORAGE ACCUMULATOR GAS VOLUME	IN^3	2500.000
ENERGY STORAGE ACCUMULATOR GAS PRESSURE	LB/IN^2	3000.000
PISTON DIAMETER	INCH	3.000
ROD DIAMETER	INCH	1.500
GAIN VALUE		0.650

## SYSTEM PARAMETERS:

STARTING ELEVATION (THETAo)	DEGREES	0.000
ENDING ELEVATION (THETAf)	DEGREES	72.000
ELEVATING WEIGHT	LBS	6348.450
MASS MOMENT OF INERTIA (I)	SLUG-FT^2	40176.600

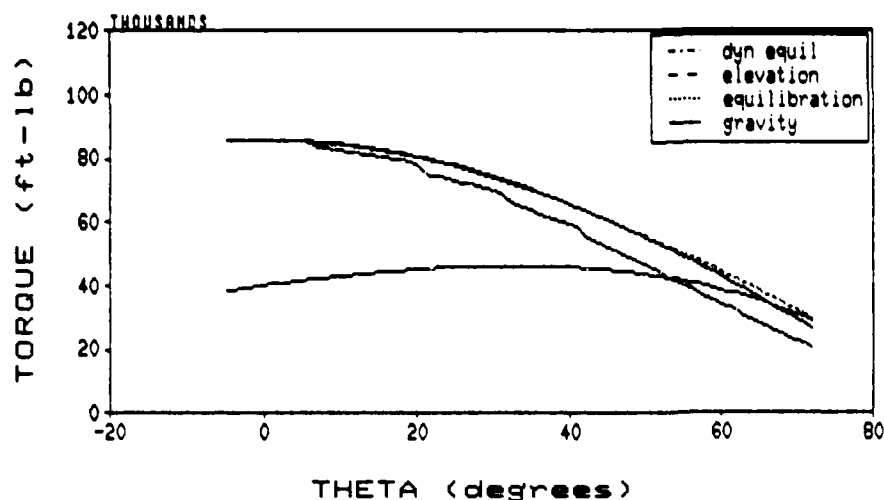
THETA	TGRAV	TEQUIL	TELEV	PRESS
-5	85740.5	86374.4	38449.8	5558.42
-4	85858.4	86349.6	38809.1	5527.17
-3	85950.1	86306.1	39162.7	5496.53

-2	86015.6	86244	39510.7	5466.48
-1	86054.9	86163.4	39852.7	5437.02
-.213443E-06	86068.1	86272.6	40188.7	5421.22
1	86054.9	85996.8	40518.5	5382.93
2	86015.6	85704.6	40841.8	5345.4
3	85950.1	85396.5	41158.6	5308.61
	85858.4	85072.4	41468.6	5272.56
	85740.5	84732.7	41771.7	5237.23
6	85596.6	84377.4	42067.6	5202.62
7	85426.5	84006.6	42356.2	5168.71
8	85230.4	83620.6	42637.2	5135.49
9	85008.4	83219.5	42910.4	5102.94
10	84760.5	82803.3	43175.6	5071.07
11	84486.7	82779.1	43432.6	5064.75
12	84187.3	82183.6	43681.2	5025.01
13	83862.1	81576.1	43921	4986.1
14	83511.5	80957	44152	4948
15	83135.4	80326.3	44373.7	4910.7
16	82733.9	79684.2	44585.9	4874.18
17	82307.3	79030.7	44788.4	4838.43
18	81855.6	78366.1	44980.9	4803.44
19	81378.9	77690.5	45163.1	4769.18
20	80877.5	77003.9	45334.6	4735.66
21	80351.5	76306.4	45495.3	4702.86
22	79800.9	76139.4	45644.7	4704.2
23	79226.1	75286.9	45782.5	4664.61
24	78627.1	74427.4	45908.5	4625.88
25	78004.1	73561	46022.2	4588
26	77357.5	72687.7	46123.3	4550.94
27	76687.2	71807.7	46211.4	4514.71
28	75993.6	70921.1	46286.2	4479.27
29	75276.8	70028.1	46347.2	4444.62
30	74537.1	69128.6	46394.2	4410.75
	73774.7	68222.8	46426.5	4377.63
32	72989.9	67310.8	46443.9	4345.27
33	72182.7	67050.6	46445.9	4356.39
34	71353.6	66013	46432.1	4312.37
35	70502.8	64973.2	46401.9	4281.22
36	69630.5	63931.3	46355	4244.93
37	68737	62887.3	46290.9	4209.49
38	67822.5	61841.5	46209	4174.89
39	66887.4	60793.8	46108.9	4141.11
40	65931.9	59744.3	45990.1	4108.13
41	64956.4	58693.1	45852	4075.96
42	63961	57640.2	45694.1	4044.56
43	62946.2	56585.6	45515.9	4013.94
44	61912.2	56308.8	45316.9	4039.99
45	60859.3	55159	45096.4	4004.86
46	59787.9	54011.5	44854	3970.61
47	58698.3	52866.4	44589	3937.25
48	57590.8	51723.8	44300.9	3904.76
49	56465.7	50583.5	43989.2	3873.11
50	55323.5	49445.6	43653.1	3842.31
51	54164.4	48310.2	43292.3	3812.34
52	52988.8	47177.2	42906	3783.19
53	51797	46046.6	42493.8	3754.84
54	50589.5	44918.4	42055.1	3727.3
55	49366.6	43792.7	41589.3	3700.54
56	48128.6	42669.3	41095.9	3674.56
57	46876	41548.3	40574.3	3649.34

58	45609.1	41108.9	40024.1	3685.79
59	44328.3	39929.7	39444.7	3657.65
60	43034	38756.1	38835.7	3630.39
61	41726.6	37588.1	38196.6	3603.99
62	40406.5	36425.5	37527.2	3578.46
63	39074	35268.3	36826.9	3553.78
	37729.7	34116.3	36095.4	3529.94
	36373.9	32969.4	35332.6	3506.94
66	35007	31827.6	34538.1	3484.76
67	33629.4	30690.7	33711.7	3463.4
68	32241.6	29558.6	32853.4	3442.85
69	30844	28431.2	31963.2	3423.1
70	29437	27308.3	31040.9	3404.15
71	28021	26189.8	30086.8	3385.98
72	26596.4	25075.5	29101	3368.6

# STATIC ANALYSIS RESULTS - Nitrogen

ENERGY RECOVERY 05-Mar-87 11:13 AM



## STATIC ANALYSIS

ENERGY RECOVERY ELEVATION : 05-Mar-87 11:13 AM

## EQUILIBRATION CYLINDER PARAMETERS:

PISTON AREA	IN <sup>2</sup>	5.52
EQUILIBRATOR VOLUME	IN <sup>3</sup>	1200.00
AMBIENT TEMPERATURE	deg-F	70.00
AMBIENT PRESSURE	LB/IN <sup>2</sup>	14.70
BALANCE PRESSURE	LB/IN <sup>2</sup>	5414.00
BALANCE POSITION	DEG	0.00
CHARGE PRESSURE AT 70 deg-F & 14.7 PSI	LB/IN <sup>2</sup>	2690.00
X LOCATION OF WIRE ROPE	INCH	-2.00
Y LOCATION OF WIRE ROPE	INCH	35.50

## ELEVATION CYLINDER PARAMETERS:

MAXIMUM MANUAL PRESSURE	LB/IN <sup>2</sup>	3000.000
MAXIMUM MANUAL POWER INPUT	HP	0.300
STARTING DECELERATION PRESS	LB/IN <sup>2</sup>	3000.000
MAXIMUM DECELERATION TORQUE	FT-LB	10000.000
ENERGY STORAGE ACCUMULATOR GAS VOLUME	IN <sup>3</sup>	2500.000
ENERGY STORAGE ACCUMULATOR GAS PRESSURE	LB/IN <sup>2</sup>	3000.000
PISTON DIAMETER	INCH	3.000
ROD DIAMETER	INCH	1.500
GAIN VALUE		0.650

## SYSTEM PARAMETERS:

STARTING ELEVATION (THETA <sub>o</sub> )	DEGREES	0.000
ENDING ELEVATION (THETA <sub>f</sub> )	DEGREES	72.000
ELEVATING WEIGHT	LBS	6348.450
MASS MOMENT OF INERTIA (I)	SLUG-FT <sup>2</sup>	40176.600

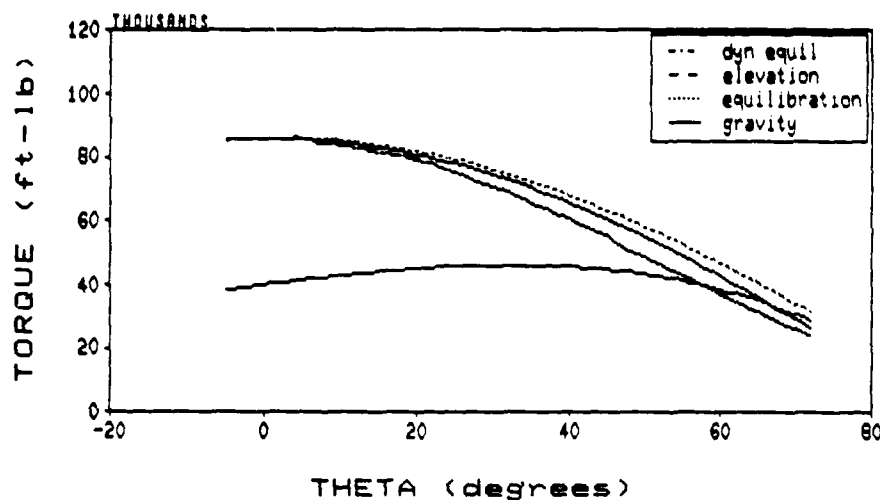
THETA	TGRAV	TEQUIL	TELEV	PRESS
-5	85740.5	85606.4	38449.8	5509
-4	85858.4	85743.1	38809.1	5488.35
-3	85950.1	85857.2	39162.7	5467.94

-2	86015.6	85948.7	39510.7	5447.77
-1	86054.9	86017.8	39852.7	5427.83
-.213443E-06	86068.1	86064.4	40188.7	5408.14
1	86054.9	86088.7	40518.5	5388.68
2	86015.6	86090.7	40841.8	5369.47
3	85950.1	86070.5	41158.6	5350.51
	85858.4	86028.1	41468.6	5331.79
	85740.5	85646	41771.7	5293.69
6	85596.6	85444.1	42067.6	5268.39
7	85426.5	85222.9	42356.2	5243.54
8	85230.4	84982.4	42637.2	5219.12
9	85008.4	84722.8	42910.4	5195.12
10	84760.5	84444.1	43175.6	5171.55
11	84486.7	84146.3	43432.6	5148.4
12	84187.3	83829.6	43681.2	5125.66
13	83862.1	83494.1	43921	5103.33
14	83511.5	83139.7	44152	5081.41
15	83135.4	82766.6	44373.7	5059.89
16	82733.9	82374.8	44585.9	5038.76
17	82307.3	81964.3	44788.4	5018.03
18	81855.6	81535.2	44980.9	4997.69
19	81378.9	81087.6	45163.1	4977.72
20	80877.5	80621.5	45334.6	4958.14
21	80351.5	80123.9	45495.3	4938.14
22	79800.9	79492.5	45644.7	4911.37
23	79226.1	78847.5	45782.5	4885.22
24	78627.1	78189	45908.5	4859.68
25	78004.1	77517	46022.2	4834.73
26	77357.5	76831.4	46123.3	4810.38
27	76687.2	76132.3	46211.4	4786.6
28	75993.6	75419.5	46286.2	4763.38
29	75276.8	74693.1	46347.2	4740.71
30	74537.1	73953.2	46394.2	4718.58
	73774.7	73199.6	46426.5	4696.98
	72989.9	72432.3	46443.9	4675.89
33	72182.7	71651.4	46445.9	4655.32
34	71353.6	70856.9	46432.1	4635.24
35	70502.8	70048.6	46401.9	4615.65
36	69630.5	69226.8	46355	4596.54
37	68737	68786.3	46290.9	4604.35
38	67822.5	67810.6	46209	4577.86
39	66887.4	66828	46108.9	4552.14
40	65931.9	65838.1	45990.1	4527.16
41	64956.4	64841	45852	4502.9
42	63961	63836.4	45694.1	4479.34
43	62946.2	62824.1	45515.9	4456.48
44	61912.2	61804.3	45316.9	4434.28
45	60859.3	60776.6	45096.4	4412.73
46	59787.9	59741	44854	4391.82
47	58698.3	58697.5	44589	4371.52
48	57590.8	57646	44300.9	4351.84
49	56465.7	56586.4	43989.2	4332.75
50	55323.5	55518.7	43653.1	4314.24
51	54164.4	54442.8	43292.3	4296.29
52	52988.8	53358.7	42906	4278.89
53	51797	52266.5	42493.8	4262.04
54	50589.5	51166	42055.1	4245.72
55	49366.6	50057.3	41589.3	4229.91
56	48128.6	48940.5	41095.9	4214.61
57	46876	48364.2	40574.3	4248.01

58	45609.1	47142.1	40024.1	4226.73
59	44328.3	45918.3	39444.7	4206.22
60	43034	44692.6	38835.7	4186.47
61	41726.6	43464.8	38196.6	4167.46
62	40406.5	42234.8	37527.2	4149.17
63	39074	41002.5	36826.9	4131.59
64	37729.7	39767.7	36095.4	4114.69
	36373.9	38530.5	35332.6	4098.46
66	35007	37290.6	34538.1	4082.89
67	33629.4	36048.1	33711.7	4067.97
68	32241.6	34802.8	32853.4	4053.67
69	30844	33554.9	31963.2	4039.99
70	29437	32304.1	31040.9	4026.91
71	28021	31050.6	30086.8	4014.43
72	26596.4	29794.4	29101	4002.53

# STATIC ANALYSIS RESULTS - Nitrogen

ENERGY RECOVERY 05-Mar-87 11:13 AM



## STATIC ANALYSIS

ENERGY RECOVERY ELEVATION : 05-Mar-87 11:13 AM

## EQUILIBRATION CYLINDER PARAMETERS:

PISTON AREA	IN^2	5.52
EQUILIBRATOR VOLUME	IN^3	1200.00
AMBIENT TEMPERATURE	deg-F	160.00
AMBIENT PRESSURE	LB/IN^2	14.70
ANCE PRESSURE	LB/IN^2	5414.00
BALANCE POSITION	DEG	0.00
CHARGE PRESSURE AT 70 deg-F & 14.7 PSI	LB/IN^2	2690.00
X LOCATION OF WIRE ROPE	INCH	-2.00
Y LOCATION OF WIRE ROPE	INCH	35.50

## ELEVATION CYLINDER PARAMETERS:

MAXIMUM MANUAL PRESSURE	LB/IN^2	3000.000
MAXIMUM MANUAL POWER INPUT	HP	0.300
STARTING DECELERATION PRESS	LB/IN^2	3000.000
MAXIMUM DECELERATION TORQUE	FT-LB	10000.000
ENERGY STORAGE ACCUMULATOR GAS VOLUME	IN^3	2500.000
ENERGY STORAGE ACCUMULATOR GAS PRESSURE	LB/IN^2	3000.000
PISTON DIAMETER	INCH	3.000
ROD DIAMETER	INCH	1.500
GAIN VALUE		0.650

## SYSTEM PARAMETERS:

STARTING ELEVATION (THETAo)	DEGREES	0.000
ENDING ELEVATION (THETAf)	DEGREES	72.000
ELEVATING WEIGHT	LBS	6348.450
MASS MOMENT OF INERTIA (I)	SLUG-FT^2	40176.600

THETA	TGRAV	TEQUIL	TELEV	PRESS
-1	85740.5	85325.7	38449.8	5490.93
-4	85858.4	85524.9	38809.1	5474.38
-3	85950.1	85700	39162.7	5457.93



-2	86015.6	85851	39510.7	5441.57
-1	86054.9	85977.9	39852.7	5425.32
-.213443E-06	86068.1	86080.8	40188.7	5409.17
1	86054.9	86159.7	40518.5	5393.13
2	86015.6	86214.6	40841.8	5377.2
3	85950.1	86245.5	41158.6	5361.39
	85858.4	86252.6	41468.6	5345.7
	85740.5	86235.7	41771.7	5330.13
6	85596.6	86195	42067.6	5314.69
7	85426.5	86130.5	42356.2	5299.38
8	85230.4	86042.2	42637.2	5284.2
9	85008.4	85930.1	42910.4	5269.16
10	84760.5	85255.9	43175.6	5221.27
11	84486.7	85027.8	43432.6	5202.33
12	84187.3	84776.9	43681.2	5183.58
13	83862.1	84503.1	43921	5165.01
14	83511.5	84206.7	44152	5146.62
15	83135.4	83887.8	44373.7	5128.43
16	82733.9	83546.4	44585.9	5110.43
17	82307.3	83182.8	44788.4	5092.63
18	81855.6	82797	44980.9	5075.02
19	81378.9	82389.1	45163.1	5057.62
20	80877.5	81959.3	45334.6	5040.42
21	80351.5	81507.6	45495.3	5023.42
22	79800.9	81034.3	45644.7	5006.63
23	79226.1	80539.4	45782.5	4990.04
24	78627.1	80023	45908.5	4973.67
25	78004.1	79485.4	46022.2	4957.5
26	77357.5	78926.5	46123.3	4941.55
27	76687.2	78346.5	46211.4	4925.82
28	75993.6	77745.6	46286.2	4910.29
29	75276.8	77123.9	46347.2	4894.99
30	74537.1	76481.6	46394.2	4879.9
31	73774.7	75465.1	46426.5	4842.35
32	72989.9	74727.8	46443.9	4824.08
33	72182.7	73971.9	46445.9	4806.08
34	71353.6	73197.6	46432.1	4788.57
35	70502.8	72405.1	46401.9	4770.93
36	69630.5	71594.6	46355	4753.76
37	68737	70766.3	46290.9	4736.88
38	67822.5	69920.3	46209	4720.28
39	66887.4	69056.8	46108.9	4703.96
40	65931.9	68176.2	45990.1	4687.92
41	64956.4	67278.4	45852	4672.17
42	63961	66363.8	45694.1	4656.7
43	62946.2	65432.6	45515.9	4641.51
44	61912.2	64484.9	45316.9	4626.6
45	60859.3	63521	45096.4	4611.99
46	59787.9	62541	44854	4597.65
47	58698.3	61545.2	44589	4583.6
48	57590.8	60533.8	44300.9	4569.84
49	56465.7	59506.9	43989.2	4556.37
50	55323.5	58464.9	43653.1	4543.18
51	54164.4	57408	43292.3	4530.28
52	52988.8	56336.3	42906	4517.67
53	51797	55250.2	42493.8	4505.34
54	50589.5	54149.8	42055.1	4493.3
55	49366.6	53035.3	41589.3	4481.55
56	48128.6	51722.1	41095.9	4454.16
57	46876	50556	40574.3	4440.52

58	45609.1	49378.5	40024.1	4427.24
59	44328.3	48190	39444.7	4414.31
60	43034	46990.6	38835.7	4401.73
61	41726.6	45780.6	38196.6	4389.51
62	40406.5	44560.3	37527.2	4377.64
63	39074	43330	36826.9	4366.11
	37729.7	42089.8	36095.4	4354.95
	36373.9	40840	35332.6	4344.13
66	35007	39581	34538.1	4333.67
67	33629.4	38312.9	33711.7	4323.55
68	32241.6	37036.1	32853.4	4313.79
69	30844	35750.9	31963.2	4304.39
70	29437	34457.4	31040.9	4295.33
71	28021	33156	30086.8	4286.63
72	26596.4	31847	29101	4278.28



ENERGY P-7 OVERVIEW ELEVATION : 05-Mar-87 12:57 PM

EQUILIBRATION CYLINDER PARAMETERS:

PISTON AREA IN'2 5.52  
EQUILIBRATOR VOLUME IN'3 1200.00  
AMBIENT TEMPERATURE deg-F -25.00  
AMBIENT PRESSURE LB/IN'2 14.70  
BALANCE PRESSURE LB/IN'2 5414.00  
BALANCE POSITION DEG 0.00  
CHARGE PRESSURE AT 70 deg-F & 14.7 PSI LB/IN'2 2690.00  
X LOCATION OF WIRE ROPE INCH -2.00  
Y LOCATION OF WIRE ROPE INCH 35.50

ELEVATION CYLINDER PARAMETERS:

MAXIMUM MANUAL PRESSURE LB/IN'2 3000.000  
MAXIMUM MANUAL POWER INPUT HP 0.300  
STARTING DECELERATION PRESS LB/IN'2 3000.000  
MAXIMUM DECELERATION TORQUE FT-LB 10000.000  
ENERGY STORAGE ACCUMULATOR GAS VOLUME IN'3 2500.000  
ENERGY STORAGE ACCUMULATOR GAS PRESSURE LB/IN'2 3000.000  
PISTON DIAMETER INCH 3.000  
ROD DIAMETER INCH 1.500  
GAIN VALUE 0.650

SYSTEM PARAMETERS:

STARTING ELEVATION (THETA0) DEGREES 33.750  
ENDING ELEVATION (THETAf) DEGREES 45.000  
ELEVATING WEIGHT LBS 6348.450  
MASS MOMENT OF INERTIA (I) SLUG-FT'2 40176.600

ELEVATION CYCLE

TIME (SEC)	ELEVATION (DEG)	ELEVATION PRESSURE (PSI)	EQUILIBRATOR PRESSURE (PSI)	ELEVATION FLOWRATE (GPM)	EQUILIBRATOR FLOWRATE (GPM)	ANGULAR VELOCITY (DEG/SEC)
.049	33.7994	2943.12	4251.72	2.73935	1.61458	1.93884
.099	33.94	2796.95	4239.88	5.17463	3.02491	3.63598
.149	34.1578	2604.26	4222.68	7.22182	4.16859	5.0184
.199	34.4362	2405.37	4202.32	8.84889	5.02698	6.06385
.249	34.7589	2228	4180.5	10.0777	5.6219	6.79743
.299	35.1116	2085.31	4158.35	10.963	5.99767	7.27077
.348999	35.4827	1979.33	4136.48	11.5728	6.20507	7.54334
.398998	35.8635	1905.78	4115.19	11.9734	6.29108	7.67044
.448998	36.248	1857.94	4094.57	12.2221	6.2942	7.69755
.498997	36.6322	1829.09	4074.65	12.3645	6.24353	7.65925
.548997	37.0133	1813.52	4055.4	12.4347	6.15989	7.58035
.598996	37.3899	1806.86	4036.78	12.4573	6.05753	7.47796
.648995	37.761	1805.96	4018.75	12.4495	5.94584	7.36341
.698995	38.1263	1808.61	4001.28	12.423	5.83084	7.24401
.748994	38.4855	1813.33	3984.34	12.3855	5.71623	7.1243
.798993	38.8385	1828.99	3962.73	12.2893	5.5803	6.9771
.848993	39.1831	1853.49	3868.69	12.1444	5.42896	6.80941
.898992	39.5199	1873.5	3845.45	12.0229	5.29434	6.6615
.948991	39.8496	1890.39	3822.95	11.9178	5.17236	6.52846
.998991	40.173	1905.05	3801.15	11.8245	5.06027	6.40696
1.04899	40.4906	1918.08	3780.01	11.7399	4.95617	6.29474
1.099	40.8028	1929.86	3759.47	11.6621	4.85874	6.1902
1.149	41.1098	1940.66	3739.51	11.5895	4.76701	6.09221
1.199	41.4122	1950.66	3720.08	11.5214	4.68026	5.99992
1.249	41.71	1959.99	3701.18	11.4569	4.59794	5.91267

1.299 42.0036 1968.73 3682.76 11.3956 4.51962 5.82998  
 1.349 42.2931 1976.96 3664.8 11.3371 4.44494 5.75141  
 1.399 42.5789 1984.73 3647.28 11.2812 4.37359 5.67664  
 1.449 42.8609 1992.08 3630.18 11.2277 4.30534 5.60537  
 1.499 43.1395 1999.05 3613.48 11.1763 4.23994 5.53736  
 1.549 43.4148 2005.67 3597.16 11.1269 4.17721 5.47237  
 1.599 43.6869 2011.95 3581.21 11.0795 4.11698 5.41021  
 1.649 43.9553 2032.31 3482.82 10.947 4.02725 5.30871  
 1.699 44.2179 2055.76 3459.06 10.7942 3.93271 5.20001  
 1.749 44.4756 2074.19 3436.01 10.6706 3.85124 5.10781  
 1.799 44.729 2089.4 3413.61 10.566 3.77866 5.02675  
 1.849 44.9785 2102.48 3391.8 10.4741 3.71239 4.95351

PRESSURE AFTER EXTENDED TIME = 4019.44  
 ELEVATION CYLINDER STROKE = 8.07513  
 TEMPERATURE COMPENSATION VOLUME = 426.434

DEPRESSION CYCLE TIME (SEC)	ELEVATION (DEG)	ELEVATION PRESSURE (PSI)	EQUILIBRATOR PRESSURE (PSI)	ANGULAR VELOCITY (DEG/SEC)	ANGULAR VELOCITY (DEG/SEC)
1.89903	44.92	2257.61	3904.78	9.43499	-2.51333
1.94904	44.6957	1253.66	3924.19	14.8993	-4.00105
1.99904	44.4096	834.608	4009.89	16.6519	-4.51835
2.04903	44.1039	712.245	4023.9	17.1229	-4.69857
2.09903	43.7912	680.691	4037.87	17.2351	-4.78455
2.14903	43.475	675.534	4052.02	17.2452	-4.84453
2.19902	43.1563	677.957	4066.42	17.226	-4.89813
2.24902	42.8352	682.656	4081.08	17.198	-4.95094
2.29902	42.5119	688.149	4096.02	17.1667	-5.00462
2.34901	42.1862	694.022	4111.27	17.1339	-5.05967
2.39901	41.858	700.164	4126.81	17.0999	-5.11632
2.449	41.5272	706.554	4142.68	17.0647	-5.17469
2.499	41.1938	713.187	4158.87	17.0285	-5.23488
2.549	40.8577	720.08	4175.41	16.9911	-5.297
2.59899	40.5186	727.235	4192.31	16.9525	-5.36115
2.64899	40.1766	734.676	4209.59	16.9125	-5.42745
2.69899	39.8314	742.412	4227.25	16.8713	-5.49603
2.74898	39.483	750.459	4245.32	16.8286	-5.56702
2.79898	39.1312	758.839	4263.81	16.7844	-5.64057
2.84898	38.7759	767.564	4282.75	16.7386	-5.71684
2.89897	38.4169	776.66	4302.16	16.691	-5.796
2.94897	38.054	786.154	4322.05	16.6417	-5.87825
2.99897	37.6871	796.065	4342.46	16.5903	-5.9638
3.04896	37.3159	806.421	4363.41	16.537	-6.05287
3.09896	36.9403	817.259	4384.92	16.4813	-6.1457
3.14895	36.5601	828.606	4407.03	16.4233	-6.24259
3.19895	36.175	840.501	4429.77	16.3627	-6.34384
3.24895	35.7847	852.991	4453.18	16.2994	-6.44978
3.29894	35.3891	866.12	4477.3	16.2329	-6.56079
3.34894	34.9877	879.938	4502.17	16.1632	-6.67728
3.39894	34.5804	894.51	4527.83	16.09	-6.79972
3.44893	34.1669	912.753	4559.27	16.0009	-6.92342
3.49893	33.7467	927.347	4577.94	15.9264	-7.06226
3.54893					-7.20475
3.59893					-7.3512
3.64893					-5.32047
3.69893					-5.9879
3.74893					-6.20437
3.79893					-6.29502
3.84893					-6.35092
3.89893					-6.39815
3.94893					-6.4441
3.99893					-6.49093
4.04893					-6.53932
4.09893					-6.58952
4.14893					-6.64167
4.19893					-6.69588
4.24893					-6.75228
4.29893					-6.81098
4.34893					-6.8721
4.39893					-6.93578
4.44893					-7.00217
4.49893					-7.07143
4.54893					-7.14374
4.59893					-7.21928
4.64893					-7.29827
4.69893					-7.38094
4.74893					-7.46753
4.79893					-7.55832
4.84893					-7.65362
4.89893					-7.75376
4.94893					-7.85911
4.99893					-7.97009
5.04893					-8.08715
5.09893					-8.21081
5.14893					-8.33538
5.19893					-8.47751

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M	M	9	0	00	0	555
M	M	999	0	3333	0	S
M	M	9	0	E	0	S
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SS	II	MMM	UU	UU	LL	AA	TT	II	00	NN	NN
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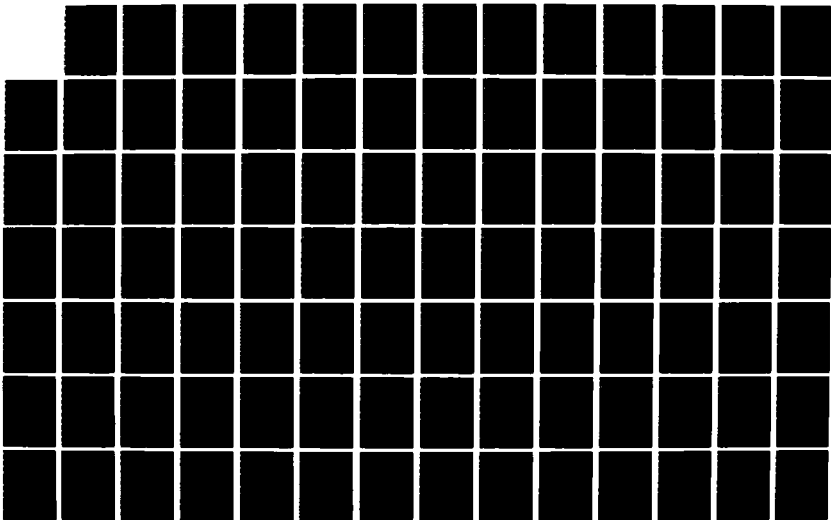
LIGHTWEIGHT TOWED HOWITZER DEMONSTRATOR PHASE 1 AND  
PARTIAL PHASE 2 VOLUM (U) FMC COR MINNEAPOLIS MINN  
NORTHERN ORDNANCE DIV R RATHE ET AL APR 87  
FMC-E-3041-VOL-C-PT-1 DAAA21-86-C-0047

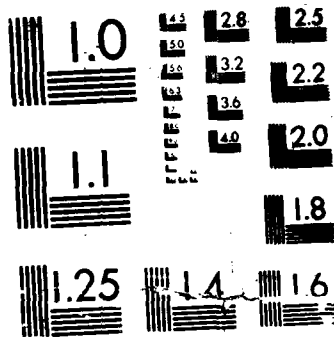
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MICROCOPY RESOLUTION TEST CHART



ENERGY P-VERY ELEVATION : 05-Mar-87 01:07 PM

EQUILIBRATION CYLINDER PARAMETERS:

PISTON AREA  
EQUILIBRATOR VOLUME  
AMBIENT TEMPERATURE  
AMBIENT PRESSURE  
BALANCE PRESSURE  
BALANCE POSITION  
CHARGE PRESSURE AT 70 deg-F & 14.7 PSI  
X LOCATION OF WIRE ROPE  
Y LOCATION OF WIRE ROPE

ELEVATION CYLINDER PARAMETERS:

MAXIMUM MANUAL PRESSURE  
MAXIMUM MANUAL POWER INPUT  
STARTING DECELERATION PRESS  
MAXIMUM DECELERATION TORQUE  
ENERGY STORAGE ACCUMULATOR GAS VOLUME  
ENERGY STORAGE ACCUMULATOR GAS PRESSURE  
PISTON DIAMETER  
ROD DIAMETER  
GAIN VALUE

SYSTEM PARAMETERS:

STARTING ELEVATION (THETA0)  
ENDING ELEVATION (THETA1)  
ELEVATING WEIGHT  
MASS MOMENT OF INERTIA (I)

ELEVATION CYCLE  
TIME  
(SEC)  
ELEVATION  
(DEG)  
ELEVATION  
PRESSURE  
(PSI)  
EQUILIBRATOR  
PRESSURE  
(PSI)  
EQUILIBRATOR  
FLOWRATE  
(GPM)  
ELEVATION  
FLOWRATE  
(GPM)  
ANGULAR  
VELOCITY  
(DEG/SEC)

1.299	43.2247	1448.86	4401.65	14.0656	5.31873	6.95289
1.3490	43.5706	1448.46	4395.23	14.0576	5.24645	6.88532
1.39901	43.9116	1483.28	4255.55	13.8823	5.11541	6.7397
1.44901	44.2491	1509.75	4248.85	13.7455	5.00294	6.61726
1.49901	44.574	1523.96	4242.2	13.6671	4.91515	6.52651
1.54902	44.8994	1531.41	4235.62	13.6214	4.84175	6.45416
PRESSURE AFTER EXTENDED TIME = 4427.4						
ELEVATION CYLINDER STROKE = 8.07513						
TEMPERATURE COMPENSATION VOLUME = 298.095						
DEPRESSION CYCLE TIME (SEC)	ELEVATION (DEG)	ELEVATION PRESSURE (PSI)	EQUILIBRATOR PRESSURE (PSI)	ANGULAR VELOCITY (DEG/SEC)		
1.59902	44.9589	2603.28	4450.3	6.5725	-1.74837	-2.33233
1.64902	44.7806	1708.81	4459.03	12.7157	-3.40423	-4.53147
1.69902	44.5276	1192.55	4467.59	15.1631	-4.09674	-5.43678
1.74903	44.2463	1004.77	4475.16	15.9541	-4.35496	-5.76025
1.79903	43.9548	946.36	4482.34	16.1856	-4.46593	-5.88695
1.84903	43.6587	929.754	4489.48	16.2438	-4.53179	-5.95339
1.89903	43.3598	926	4496.69	16.2494	-4.58475	-6.00252
1.94904	43.0585	926.203	4504.01	16.2387	-4.63471	-6.04745
1.99904	42.7551	927.677	4511.46	16.2227	-4.68472	-6.09221
2.04903	42.4493	929.616	4519.04	16.2047	-4.73577	-6.13808
2.09903	42.1413	931.775	4526.77	16.1857	-4.78821	-6.18551
2.14903	41.8308	934.085	4534.65	16.166	-4.84221	-6.23469
2.19902	41.5178	936.527	4542.68	16.1457	-4.89787	-6.28576
2.24902	41.2023	939.101	4550.87	16.1247	-4.9553	-6.33882
2.29902	40.884	941.812	4559.22	16.103	-5.01459	-6.39398
2.34901	40.5629	944.671	4567.75	16.0806	-5.07586	-6.45137
2.39901	40.2389	947.678	4576.46	16.0574	-5.13921	-6.51109
2.449	39.9118	950.848	4585.36	16.0334	-5.20477	-6.57329
2.499	39.5815	954.195	4594.46	16.0086	-5.27267	-6.63811
2.549	39.248	957.721	4603.76	15.9829	-5.34305	-6.7057
2.59899	38.911	961.445	4613.27	15.9562	-5.41607	-6.77624
2.64899	38.5704	965.378	4623.01	15.9284	-5.4919	-6.84992
2.69899	38.226	969.538	4632.99	15.8996	-5.57072	-6.92693
2.74898	37.8777	973.939	4643.21	15.8696	-5.65274	-7.0075
2.79898	37.5253	978.597	4653.7	15.8382	-5.73818	-7.09187
2.84898	37.1685	983.537	4664.46	15.8056	-5.82728	-7.18033
2.89897	36.8073	988.784	4675.51	15.7714	-5.92031	-7.27314
2.94897	36.4412	994.356	4686.87	15.7356	-6.01757	-7.37065
2.99897	36.0702	1000.3	4698.55	15.698	-6.11939	-7.47322
3.04896	35.6939	1006.62	4710.58	15.6585	-6.22612	-7.58124
3.09896	35.3121	1013.37	4722.97	15.617	-6.33818	-7.69516
3.14895	34.9244	1020.6	4735.75	15.5731	-6.45602	-7.8155
3.19895	34.5306	1028.35	4748.94	15.5267	-6.58015	-7.94279
3.24895	34.1302	1036.67	4762.58	15.4774	-6.71113	-8.07768

[illegible]

M	M	999	000	EEEE	000	55555
M	M	9	0	E	0	5
M	M	9	0	E	0	555
M	M	999	0	EEE	0	5
M	M	9	0	E	0	5
M	M	9	0	E	0	5
M	M	999	0	EEE	000	555

[illegible][illegible]

File\_HSC000\$QV45:[M90.GREEN\_JR.VMS.PROGRAMS.LTND]SIMULATION.P06;1 (1633,14,0), last revised on 5-MAR-1987 13:11, is a 17 block sequential file owned by UIC [M90.GREEN\_JR]. The records are variable length with implied (CM) carriage control. The longest record is 93 bytes.

Job SIMULATION (94) queued to LMSYS on 3-MAR-1987 14:51 by user M90E05, UIC [M90, GREEN\_JE], under account M93 at priority 100, started on printer VENUS\$XMG6: on 3-MAR-1987 14:53 from queue LMSYS.

[illegible]

## DYNAMIC ANALYSIS

ENERGY - OVERY ELEVATION : 05-Mar-87 01:09 PM

## EQUILIBRATION CYLINDER PARAMETERS:

PISTON AREA  
 EQUILIBRATOR VOLUME  
 AMBIENT TEMPERATURE  
 AMBIENT PRESSURE  
 BALANCE PRESSURE  
 BALANCE POSITION  
 CHARGE PRESSURE AT 70 deg-F & 14.7 PSI  
 X LOCATION OF WIRE ROPE  
 Y LOCATION OF WIRE ROPE

IN<sup>2</sup> 5.52  
 IN<sup>3</sup> 1200.00  
 deg-F 160.00  
 LB/IN<sup>2</sup> 14.70  
 LB/IN<sup>2</sup> 5414.00  
 DEG 0.00  
 LB/IN<sup>2</sup> 2690.00  
 INCH -2.00  
 INCH 35.50

## ELEVATION CYLINDER PARAMETERS:

MAXIMUM MANUAL PRESSURE  
 MAXIMUM MANUAL POWER INPUT  
 STARTING DECELERATION PRESS  
 MAXIMUM DECELERATION TORQUE  
 ENERGY STORAGE ACCUMULATOR GAS VOLUME  
 ENERGY STORAGE ACCUMULATOR GAS PRESSURE  
 PISTON DIAMETER  
 ROD DIAMETER  
 GAIN VALUE

LB/IN<sup>2</sup> 3000.000  
 HP 0.300  
 LB/IN<sup>2</sup> 3000.000  
 FT-LB 10000.000  
 IN<sup>3</sup> 2500.000  
 LB/IN<sup>2</sup> 3000.000  
 INCH 3.000  
 INCH 1.500  
 0.650

## SYSTEM PARAMETERS:

STARTING ELEVATION (THETA0)  
 ENDING ELEVATION (THETAf)  
 ELEVATING WEIGHT  
 MASS MOMENT OF INERTIA (I)

DEGREES 33.750  
 DEGREES 45.000  
 LBS 6348.450  
 SLUG-FT<sup>2</sup> 40176.600

## ELEVATION CYCLE

TIME (SEC)	ELEVATION (DEG)	ELEVATION PRESSURE (PSI)	EQUILIBRATOR PRESSURE (PSI)	ELEVATION FLOWRATE (GPM)	EQUILIBRATOR FLOWRATE (GPM)	ANGULAR VELOCITY (DEG/SEC)
.049	33.8136	2905.86	4788.16	3.52647	2.07678	2.49412
.099	33.9936	2668.72	4777.27	6.61391	3.85419	4.63454
.149	34.2692	2368.37	4762.62	9.13003	5.23637	6.30887
.199	34.6164	2074.75	4746.84	11.0461	6.21156	7.50256
.249	35.0125	1829.06	4731.53	12.4207	6.83223	8.27634
.299	35.4386	1644.49	4717.32	13.3565	7.17843	8.72369
.34899	35.881	1516.55	4704.26	13.9639	7.3302	8.93861
.39899	36.3299	1433.4	4692.18	14.3401	7.35381	8.9993
.44898	36.7793	1382.4	4680.85	14.561	7.29821	8.96385
.49897	37.2254	1352.97	4670.08	14.6816	7.19696	8.87226
.54897	37.6661	1337.31	4659.75	14.7395	7.07175	8.7506
.59896	38.1004	1330.07	4649.74	14.7596	6.93604	8.6151
.64895	38.5277	1327.77	4640.02	14.7578	6.79778	8.47546
.69895	38.9481	1328.2	4630.53	14.7438	6.66147	8.33724
.74894	39.3617	1330.05	4621.25	14.7237	6.5295	8.20343
.79893	39.7687	1332.53	4612.17	14.701	6.40297	8.07546
.84893	40.1694	1335.18	4603.27	14.6777	6.28228	7.9539
.89892	40.5643	1337.75	4594.55	14.6549	6.16742	7.83883
.94891	40.9535	1340.13	4585.99	14.6331	6.05816	7.73004
.99891	41.3375	1342.26	4577.58	14.6126	5.95422	7.62721
1.04899	41.7164	1344.11	4569.33	14.5935	5.85523	7.52998
1.099	42.0907	1345.7	4561.22	14.5758	5.76086	7.43797
1.149	42.4604	1347.03	4553.26	14.5593	5.67077	7.35081
1.199	42.8259	1348.11	4545.43	14.5442	5.58465	7.26818
1.249	43.1874	1348.97	4537.73	14.5302	5.50222	7.18974

DEPRESSION CYCLE				
TIME	ELEVATION	ELEVATION	EQUILIBRATOR	ANGULAR
(SEC)	(DEG)	PRESSURE	PRESSURE	VELOCITY
		(PSI)	(PSI)	(DEG/SEC)
1.54902	44.9437	2515.87	4615.2	7.40125
1.59902	44.7578	1694.57	4623.74	12.7808
1.64902	44.5069	1249.5	4631.89	14.911
1.69902	44.231	1087.34	4639.18	15.6065
1.74903	43.946	1035.96	4646.15	15.8138
1.79903	43.6567	1021.11	4653.06	15.8663
1.84903	43.3647	1017.77	4660.02	15.8704
1.89903	43.0706	1018.06	4667.07	15.8593
1.94904	42.7744	1019.54	4674.22	15.8432
1.99904	42.476	1021.46	4681.48	15.8251
2.04903	42.1754	1023.57	4688.84	15.8061
2.09903	41.8726	1025.81	4696.32	15.7865
2.14903	41.5673	1028.16	4703.91	15.7663
2.19902	41.2597	1030.62	4711.63	15.7455
2.24902	40.9495	1033.19	4719.47	15.7242
2.29902	40.6366	1035.88	4727.44	15.7022
2.34901	40.3211	1038.69	4735.55	15.6797
2.39901	40.0026	1041.63	4743.81	15.6564
2.449	39.6812	1044.7	4752.21	15.6324
2.499	39.3566	1047.92	4760.76	15.6076
2.549	39.0292	1053.04	4826.55	15.5235
2.59899	38.7	1079.99	4832.93	15.4881
2.64899	38.3679	1086.97	4839.5	15.4667
2.69899	38.0323	1091.19	4846.22	15.3769
2.74898	37.6929	1094.55	4853.09	15.3507
2.79898	37.3495	1097.7	4860.12	15.3251
2.84898	37.0018	1100.93	4867.31	15.2991
2.89897	36.6497	1104.3	4874.66	15.2722
2.94897	36.2929	1107.92	4882.19	15.2441
2.99897	35.9311	1111.8	4889.9	15.2146
3.04896	35.5641	1115.97	4897.81	15.1836
3.09896	35.1916	1120.47	4905.94	15.151
3.14895	34.8133	1125.34	4914.29	15.1164
3.19895	34.4289	1130.65	4922.87	15.0798
3.24895	34.038	1136.32	4931.72	15.0409
3.29895	33.6437	1142.25	4940.75	15.0000
3.34895	33.2466	1148.36	4949.95	14.9573
3.39895	32.8466	1154.61	4959.31	14.9131
3.44895	32.4437	1161.01	4968.82	14.8675
3.49895	32.0381	1167.56	4978.48	14.8205
3.54895	31.6299	1174.26	4988.29	14.7722
3.59895	31.2183	1181.11	4998.25	14.7227
3.64895	30.8035	1188.11	5008.36	14.6719
3.69895	30.3857	1195.26	5018.61	14.6198
3.74895	29.9649	1202.56	5029.01	14.5665
3.79895	29.5413	1210.01	5039.55	14.5119
3.84895	29.1151	1217.61	5050.24	14.4569
3.89895	28.6864	1225.36	5061.07	14.4005
3.94895	28.2552	1233.19	5072.04	14.3428
3.99895	27.8226	1241.16	5083.15	14.2838
4.04895	27.3886	1249.27	5094.4	14.2235
4.09895	26.9533	1257.52	5105.79	14.1619
4.14895	26.5167	1265.91	5117.32	14.0991
4.19895	26.0789	1274.34	5128.99	14.0351
4.24895	25.64	1282.91	5140.8	13.97
4.29895	25.1999	1291.52	5152.74	13.9057
4.34895	24.7576	1300.19	5164.83	13.842
4.39895	24.3131	1308.91	5177.06	13.7773
4.44895	23.8666	1317.68	5189.43	13.7111
4.49895	23.4181	1326.59	5201.94	13.6436
4.54895	22.9677	1335.64	5214.58	



DYNAMIC ANALYSIS  
ENERGY 1 VERY ELEVATION : 05-Mar-87 01:12 PM

### EQUILIBRATION CYLINDER PARAMETERS:

PISTON AREA	IN <sup>2</sup>	5.52
EQUILIBRATOR VOLUME	IN <sup>3</sup>	1200.00
AMBIENT TEMPERATURE	deg-F	-25.00
AMBIENT PRESSURE	LB/IN <sup>2</sup>	14.70
BALANCE PRESSURE	LB/IN <sup>2</sup>	5414.00
BALANCE POSITION	DEG	0.00
CHARGE PRESSURE AT 70 deg-F & 14.7 PSI	LB/IN <sup>2</sup>	2690.00
LOCATION OF WIRE ROPE	INCH	-2.00
LOCATION OF WIRE ROPE	INCH	35.50

**ELEVATION CYLINDER PARAMETERS:**

MAXIMUM MANUAL PRESSURE	LB/IN <sup>2</sup>	3000.000
MAXIMUM MANUAL POWER INPUT	HP	0.300
MAXIMUM DECELERATION PRESS	LB/IN <sup>2</sup>	3000.000
MAXIMUM DECELERATION TORQUE	FT-LB	10000.000
ENERGY STORAGE ACCUMULATOR GAS VOLUME	IN <sup>3</sup>	2500.000
ENERGY STORAGE ACCUMULATOR GAS PRESSURE	LB/IN <sup>2</sup>	3000.000
PISTON DIAMETER	INCH	3.000
ROD DIAMETER	INCH	1.500
RAIN VALUE		0.650

**SYSTEM PARAMETERS:**

DEGREES	33.750
DEGREES	72.000
LBS	638.450
SLUG-FT <sup>-2</sup>	40176.600

ELEVATION CYCLE		EQUILIBRATOR				EQUILIBRATOR				EQUILIBRATOR			
TIME	ELEVATION	PRESSURE	PRESSURE	FLOWRATE	FLOWRATE	FLOWRATE	FLOWRATE	VELOCITY	VELOCITY	VELOCITY	VELOCITY	VELOCITY	VELOCITY
(SEC)	(DEG)	(PSI)	(PSI)	(GPN)	(GPN)	(GPN)	(GPN)	(DEG/SEC)	(DEG/SEC)	(DEG/SEC)	(DEG/SEC)	(DEG/SEC)	(DEG/SEC)
.099	33.94	2796.95	4239.88	5.17463	3.02491	3.63598							
.199	34.4362	2405.37	4202.32	8.84889	5.02698	6.06385							
.299	35.1116	2085.31	4158.35	10.963	5.99767	7.27077							
.398998	35.8635	1905.78	4115.19	11.9734	6.29108	7.67044							
.498997	36.6322	1829.09	4074.65	12.3645	6.24353	7.65925							
.598996	37.3899	1806.86	4036.78	12.4573	6.05753	7.47796							
.698995	38.1263	1808.61	4001.28	12.423	5.83084	7.24401							
.798993	38.8385	1828.99	3992.73	12.2893	5.5803	6.9771							
.898992	39.5199	1873.5	3845.45	12.0229	5.29434	6.6615							
.998991	40.173	1905.05	3801.15	11.8345	5.06027	6.40696							
1.099	40.8028	1929.86	3759.47	11.6821	4.85874	6.1902							
1.199	41.4122	1950.66	3720.08	11.5214	4.68026	5.99992							
1.299	42.0036	1968.73	3682.76	11.3956	4.51962	5.83998							
1.39901	42.5789	1984.73	3647.28	11.2812	4.37359	5.67664							
1.49901	43.1395	1999.05	3613.48	11.1783	4.23994	5.53736							
1.59902	43.6869	2011.95	3581.21	11.0795	4.11698	5.41021							
1.69902	44.2179	2055.76	3459.06	10.7942	3.93271	5.28001							
1.79903	44.729	2089.4	3413.61	10.566	3.77866	5.03675							
1.89903	45.2245	2114.11	3370.56	10.3908	3.6508	4.88599							
1.99904	45.7069	2134.49	3329.63	10.2412	3.53783	4.78325							
2.09903	46.1777	2152.38	3290.61	10.1062	3.43498	4.65246							
2.19902	46.6378	2168.56	3253.33	9.98132	3.33999	4.55081							
2.29902	47.0882	2183.4	3217.64	9.86038	3.2516	4.45678							
2.39901	47.5295	2197.1	3183.42	9.75424	3.16899	4.36942							
2.499	47.9577	2244.68	3041.79	9.40745	3.01424	4.18051							





9.09905	69.5446	2608.89	2700.67	5.1100	2.98434	4.4443
9.1990	69.7705	2606.99	2699.29	5.12411	2.97534	2.26734
9.2991	69.998	2605.08	2697.91	5.13784	2.96825	2.28404
9.39917	70.2273	2603.14	2696.54	5.15178	2.96132	2.30132
9.49921	70.4583	2601.19	2695.17	5.16595	2.95542	2.3192
9.59925	70.6911	2599.21	2693.8	5.18033	2.9497	2.3377
9.69929	70.9259	2597.22	2692.44	5.19496	2.94447	2.35687
9.79933	71.1625	2595.2	2691.07	5.20982	2.93974	2.37673
9.89937	71.4012	2593.16	2689.72	5.22495	2.93554	2.39731
9.99941	71.642	2591.09	2688.36	5.24034	2.93186	2.41867
10.0995	71.8849	2589	2687.01	5.25601	2.92874	2.44083

PRESSURE AFTER EXTENDED TIME = 3383.26  
 ELEVATION CYLINDER STROKE = 24.1001  
 TEMPERATURE COMPENSATION VOLUME = 426.434

DEPRESSION CYCLE TIME (SEC)	ELEVATION (DEG)	ELEVATION PRESSURE (PSI)	EQUILIBRATOR PRESSURE (PSI)	ANGULAR VELOCITY (DEG/SEC)	ANGULAR VELOCITY (DEG/SEC)
10.1995	71.938	2465.48	3345.94	6.62742	-2.31141
10.2995	71.5563	1290.71	3360.58	14.1265	-4.87964
10.3996	71.0255	790.425	3379.7	16.2973	-5.55821
10.4996	70.4635	673.809	3399.91	16.7546	-5.64199
10.5997	69.901	652.08	3420.59	16.8295	-5.59998
10.6997	69.344	649.531	3441.65	16.8287	-5.53803
10.7997	68.7933	650.798	3463.05	16.8127	-5.47642
10.8998	68.2485	653.052	3484.83	16.7928	-5.41849
10.9998	67.7094	655.802	3506.97	16.7708	-5.36449
11.0999	67.1773	658.027	3529.12	16.7437	-5.31249
11.1999	66.6517	660.826	3551.26	16.7194	-5.26227
11.2999	66.1305	663.842	3573.41	16.6994	-5.21466
11.4	65.613	667.465	3595.56	16.6781	-5.16984
11.5	65.099	671.302	3617.71	16.6556	-5.12787
11.6001	64.5881	675.427	3639.86	16.6331	-5.08849
11.7001	64.0802	679.551	3662.01	16.6106	-5.05152
11.8001	63.5749	683.674	3684.16	16.5881	-5.01634
11.9002	63.0721	687.798	3706.31	16.5656	-4.9949
12.0002	62.5715	691.922	3728.46	16.5431	-4.97544
12.1003	62.073	696.046	3750.61	16.5206	-4.95785
12.2003	61.5764	700.170	3772.76	16.4981	-4.94208
12.3003	61.0814	704.294	3794.91	16.4756	-4.92805
12.4004	60.5879	708.418	3817.06	16.4531	-4.91569
12.5004	60.0957	712.542	3839.21	16.4306	-4.90495
12.6005	59.6047	716.666	3861.36	16.4081	-4.89579
12.7005	59.1147	720.790	3883.51	16.3856	-4.88815
12.8005	58.6255	724.914	3905.66	16.3631	-4.88199
12.9006	58.137	729.038	3927.81	16.3406	-4.87722
13.0006	57.6495	733.162	3949.96	16.3181	-4.87392
13.1007	57.1654	737.286	3972.11	16.2956	-4.87161
13.2007	56.6817	741.410	3994.26	16.2731	-4.86829
13.3007	56.1978	745.534	4016.41	16.2506	-4.86585
13.4008	55.7133	749.658	4038.56	16.2281	-4.86483
13.5008	55.2283	753.782	4060.71	16.2056	-4.86483
13.6009	54.7426	757.906	4082.86	16.1831	-4.86483
13.7009	54.2559	762.030	4105.01	16.1606	-4.86483
13.8009	53.7682	766.154	4127.16	16.1381	-4.86483
13.901	53.2793	770.278	4149.31	16.1156	-4.86483
14.001	52.789	774.402	4171.46	16.0931	-4.86483
14.1011	52.2973	778.526	4193.61	16.0706	-4.86483
14.2011	51.8038	782.650	4215.76	16.0481	-4.86483
14.3011	51.3085	786.774	4237.91	16.0256	-4.86483
14.4012	50.8112	790.898	4260.06	16.0031	-4.86483
14.5012	50.3117	795.022	4282.21	15.9806	-4.86483
14.6013	49.8098	799.146	4304.36	15.9581	-4.86483

14.8014	48.7982	853.092	4313.3	15.487	-3.62385	-5.08584
14.901	48.2882	860.145	4334.91	15.4423	-3.67192	-5.11615
15.001	47.7765	894.253	4417.6	15.2803	-3.69349	-5.10981
15.1015	47.2644	905.689	4433.18	15.2158	-3.73987	-5.13812
15.2015	46.7486	910.697	4449.18	15.1789	-3.79528	-5.17866
15.3016	46.2286	915.357	4465.6	15.1434	-3.85359	-5.22284
15.4016	45.704	920.25	4482.46	15.1066	-3.91435	-5.26999
15.5016	45.1745	925.446	4499.79	15.0682	-3.97768	-5.3202
15.6017	44.6399	930.969	4517.61	15.028	-4.04378	-5.37369
15.7017	44.0997	936.84	4535.94	14.9861	-4.11385	-5.43067
15.8018	43.5537	943.079	4554.82	14.9422	-4.18514	-5.49141
15.9018	43.0014	949.717	4574.27	14.8962	-4.26091	-5.55617
16.0018	42.4424	956.775	4594.34	14.848	-4.34047	-5.6253
16.1018	41.8762	964.289	4615.06	14.7974	-4.42416	-5.69915
16.2017	41.3024	972.294	4636.47	14.7441	-4.51235	-5.77813
16.3017	40.7205	980.833	4658.63	14.688	-4.60548	-5.86271
16.4016	40.1298	989.951	4681.57	14.6287	-4.70404	-5.95343
16.5016	39.5297	999.703	4705.37	14.5661	-4.8086	-6.05089
16.6015	38.9195	1010.15	4730.09	14.4997	-4.9198	-6.15582
16.7015	38.2984	1021.36	4755.79	14.4292	-5.03839	-6.26902
16.8014	37.6677	1038.91	4843.11	14.2358	-5.12218	-6.33827
16.9013	37.0283	1076.71	4862.16	14.1325	-5.24679	-6.4575
17.0013	36.3754	1087.38	4882.13	14.0617	-5.39565	-6.60539
17.1012	35.7068	1097.69	4903.06	13.9918	-5.55959	-6.77031
17.2012	35.021	1108.9	4925.07	13.9167	-5.7387	-6.95212
17.3011	34.316	1121.4	4948.25	13.8345	-5.935	-7.15298



ENERGY P-COVERY ELEVATION : 05-Mar-87 01:24 PM

EQUILIBRATION CYLINDER PARAMETERS:

PISTON AREA  
IN<sup>2</sup> 5.52  
IN<sup>3</sup> 1200.00  
EQUILIBRATOR VOLUME  
deg-F 70.00  
AMBIENT TEMPERATURE  
LB/IN<sup>2</sup> 14.70  
BALANCE PRESSURE  
LB/IN<sup>2</sup> 5414.00  
BALANCE POSITION  
DEG 0.00  
CHARGE PRESSURE AT 70 deg-F & 14.7 PSI  
INCH 2690.00  
X LOCATION OF WIRE ROPE  
INCH -2.00  
Y LOCATION OF WIRE ROPE  
INCH 35.50

ELEVATION CYLINDER PARAMETERS:

MAXIMUM MANUAL PRESSURE  
LB/IN<sup>2</sup> 3000.000  
MAXIMUM MANUAL POWER INPUT  
HP 0.300  
STARTING DECELERATION PRESS  
LB/IN<sup>2</sup> 3000.000  
MAXIMUM DECELERATION TORQUE  
FT-LB 10000.000  
ENERGY STORAGE ACCUMULATOR GAS VOLUME  
IN<sup>3</sup> 2500.000  
ENERGY STORAGE ACCUMULATOR GAS PRESSURE  
LB/IN<sup>2</sup> 3000.000  
PISTON DIAMETER  
INCH 3.000  
ROD DIAMETER  
INCH 1.500  
GAIN VALUE  
0.650

SYSTEM PARAMETERS:

STARTING ELEVATION (THETA0)  
DEGREES 33.750  
ENDING ELEVATION (THETA1)  
DEGREES 72.000  
ELEVATING WEIGHT  
LBS 6348.450  
MASS MOMENT OF INERTIA (I)  
SLUG-FT<sup>2</sup> 40176.600

ELEVATION CYCLE

TIME (SEC)	ELEVATION (DEG)	ELEVATION PRESSURE (PSI)	EQUILIBRATOR PRESSURE (PSI)	ELEVATION FLOWRATE (GPM)	EQUILIBRATOR FLOWRATE (GPM)	ANGULAR VELOCITY (DEG/SEC)
.099	33.9781	2708.8	4622.76	6.19999	3.61625	4.34794
.199	34.5653	2174	4595.33	10.4351	5.88492	7.10539
.299	35.3479	1770.09	4568.25	12.7204	6.87012	8.34326
.398998	36.2038	1560.93	4545.14	13.7414	7.09283	8.67119
.498997	37.0689	1475.12	4525	14.1235	6.97721	8.59011
.598996	37.9173	1446.78	4506.66	14.2308	6.74591	8.36555
.698995	38.7413	1440.78	4489.5	14.2344	6.49238	8.1103
.798993	39.54	1442.02	4473.22	14.2051	6.24968	7.86504
.898992	40.3153	1444.76	4457.69	14.1695	6.02682	7.64135
.998991	41.0693	1447.11	4442.83	14.1364	5.82438	7.44045
1.099	41.8042	1448.58	4428.56	14.108	5.64042	7.26041
1.199	42.5221	1449.13	4414.85	14.0846	5.47259	7.09868
1.299	43.2247	1448.86	4401.65	14.0656	5.31873	6.95289
1.39901	43.9116	1483.28	4255.55	13.8823	5.11541	6.7397
1.49901	44.574	1523.96	4242.2	13.6671	4.91515	6.52651
1.59902	45.2196	1535.11	4229.12	13.5939	4.77705	6.3929
1.69902	45.8536	1537.08	4216.43	13.5658	4.66255	6.28915
1.79903	46.478	1536.01	4204.11	13.5529	4.55965	6.1997
1.89903	47.0939	1533.81	4192.17	13.5459	4.46429	6.11942
1.99904	47.7022	1531.06	4180.58	13.5419	4.37491	6.04636
2.09903	48.3035	1527.95	4169.32	13.54	4.29069	5.97958
2.19902	48.8984	1524.57	4158.37	13.5397	4.2111	5.91851
2.29902	49.4874	1520.94	4147.72	13.541	4.13572	5.86268
2.39901	50.0711	1517.08	4137.35	13.5436	4.06419	5.81175
2.499	50.65	1513.02	4127.24	13.5475	3.9962	5.76539

DEPRESSION CYCLE TIME (SEC)	ELEVATION (DEG)	ELEVATION PRESSURE (PSI)	EQUILIBRATOR PRESSURE (PSI)	ANGULAR VELOCITY (DEG/SEC)	
4.33039	51.4244	1508.76	4117.38	13.5525	3.93146
2.6989	51.7948	1504.31	4107.76	13.5587	3.86974
2.7981	52.3616	1499.68	4098.37	13.566	3.81082
2.8987	52.9252	1494.89	4089.2	13.5744	3.7545
2.9987	53.4859	1489.93	4080.23	13.5837	3.7006
3.0986	54.0441	1484.81	4071.46	13.594	3.64896
3.1985	54.6001	1479.54	4062.88	13.6032	3.59943
3.2984	55.1543	1474.12	4054.48	13.6173	3.55189
3.3983	55.7069	1468.54	4046.25	13.6303	3.50621
3.4983	56.2583	1462.82	4038.19	13.6442	3.46229
3.5982	56.8087	1456.95	4030.28	13.6589	3.42002
3.6981	57.3586	1450.94	4022.53	13.6744	3.37931
3.7981	57.9071	1444.38	4015.45	13.6891	3.33861
3.8989	58.4418	1437.72	4008.07	13.7038	3.29791
3.9989	58.9693	1430.77	4000.72	13.7186	3.25721
4.0989	59.4952	1423.21	3993.48	13.7333	3.21651
4.1988	60.0214	1415.76	3986.34	13.7480	3.17581
4.2987	60.5486	1408.07	3979.31	13.7627	3.13511
4.3986	61.0772	1400.07	3972.4	13.7774	3.09441
4.4986	61.6075	1391.96	3965.59	13.7921	3.05371
4.5985	62.1398	1383.73	3958.88	13.8068	3.01301
4.6984	62.6745	1375.21	3952.27	13.8215	2.97231
4.7983	63.2118	1366.77	3945.76	13.8362	2.93161
4.8983	63.7522	1358.04	3939.35	13.8509	2.89091
4.9982	64.2959	1349.14	3933.02	13.8656	2.85021
5.0981	64.8434	1340.07	3926.78	13.8803	2.80951
5.1981	65.395	1330.82	3920.63	13.8950	2.76881
5.2988	65.9511	1321.39	3914.56	13.9097	2.72811
5.3987	66.5123	1311.78	3908.57	13.9244	2.68741
5.4987	67.0789	1302.04	3902.65	13.9391	2.64671
5.5987	67.6515	1292.17	3896.81	13.9538	2.60601
5.6987	68.1778	1282.13	3891.02	13.9685	2.56531
5.7987	68.4875	1271.97	3885.33	13.9832	2.52461
5.8987	68.7684	1261.72	3879.74	13.9979	2.48391
5.9987	69.048	1251.38	3874.25	14.0126	2.44321
6.0987	69.3294	1240.95	3868.81	14.0273	2.40251
6.1987	69.6126	1230.44	3863.57	14.0420	2.36181
6.2987	69.8979	1219.88	3858.41	14.0567	2.32111
6.3987	70.1854	1209.27	3853.33	14.0714	2.28041
6.4987	70.4751	1198.62	3848.33	14.0861	2.23971
6.5987	70.7672	1187.93	3843.41	14.1008	2.19901
6.6987	71.0618	1177.21	3838.57	14.1155	2.15831
6.7986	71.359	1166.46	3833.81	14.1302	2.11761
6.8986	71.6588	1155.68	3829.12	14.1449	2.07691
6.9986	71.9615	1144.87	3824.51	14.1596	2.03621
7.0986	72.2672	1134.04	3819.97	14.1743	1.99551
7.1986	72.5759	1123.19	3815.51	14.1890	1.95481
7.2986	72.8875	1112.32	3811.12	14.2037	1.91411
7.3986	73.2018	1101.44	3806.81	14.2184	1.87341
7.4986	73.5189	1090.54	3802.57	14.2331	1.83271
7.5986	73.8386	1079.63	3798.41	14.2478	1.79201
7.6986	74.1608	1068.71	3794.33	14.2625	1.75131
7.7986	74.4854	1057.78	3790.33	14.2772	1.71061
7.8986	74.8125	1046.84	3786.41	14.2919	1.66991
7.9986	75.1418	1035.89	3782.57	14.3066	1.62921
8.0986	75.4733	1024.93	3778.81	14.3213	1.58851

PRESSURE AFTER EXTENDED TIME = 4017.21  
ELEVATION CYLINDER STROKE = 24.1001  
TEMPERATURE COMPENSATION VOLUME = 298.095

DEPRESSION CYCLE TIME (SEC)	ELEVATION (DEG)	ELEVATION PRESSURE (PSI)	EQUILIBRATOR PRESSURE (PSI)	ANGULAR VELOCITY (DEG/SEC)	
7.09867	71.859	2223.15	4037.05	8.71934	-3.03485
7.19866	71.4573	1396.39	4043.47	13.6189	-4.69287
7.29865	70.9006	1081.56	4050.51	15.0643	-5.12996
7.39865	70.4433	998.275	4057.65	15.416	-5.18894
7.49864	69.9255	976.417	4064.89	15.4989	-5.15982
7.59863	69.4118	968.578	4072.24	15.5215	-5.11455
7.69862	68.9026	963.877	4079.7	15.5306	-5.06883
7.79862	68.3979	960.004	4087.28	15.5362	-5.02569
7.89861	67.8973	956.499	4094.98	15.5401	-4.98556
7.9986	67.4006	953.262	4102.8	15.5428	-4.94834
8.09864	66.9075	950.276	4110.75	15.5444	-4.91386

8.19868	66.4177	947.526	4118.82	15.5449	-2.39559	-4.86196
8.2987	65.931	945.008	4127.03	15.5444	-2.41589	-4.85249
8.39876	65.4471	942.713	4135.37	15.5429	-2.43648	-4.82531
8.4988	64.9659	940.635	4143.85	15.5405	-2.45736	-4.80031
8.59884	64.487	938.769	4152.47	15.537	-2.47855	-4.77737
8.69888	64.0103	937.112	4161.24	15.5327	-2.50006	-4.7564
8.79893	63.5356	935.657	4170.16	15.5274	-2.52189	-4.73732
8.89897	63.0628	934.401	4179.23	15.5212	-2.54408	-4.72004
8.99901	62.5915	933.34	4188.47	15.5141	-2.56662	-4.7045
9.09905	62.1218	932.473	4197.86	15.5061	-2.58953	-4.69063
9.19909	61.6534	931.795	4207.42	15.4973	-2.61284	-4.67837
9.29913	61.186	931.305	4217.16	15.4876	-2.63655	-4.66768
9.39917	60.7198	931.001	4227.07	15.4771	-2.66067	-4.65852
9.49921	60.2543	930.881	4237.16	15.4656	-2.68524	-4.65084
9.59925	59.7896	930.945	4247.45	15.4534	-2.71026	-4.64461
9.69929	59.3253	931.192	4257.92	15.4402	-2.73576	-4.63979
9.79933	58.8615	931.623	4268.6	15.4263	-2.76174	-4.63637
9.89937	58.3978	932.236	4279.49	15.4114	-2.78826	-4.63433
9.99941	57.9347	933.033	4290.58	15.3957	-2.81528	-4.63364
10.0995	57.4716	934.013	4301.89	15.3791	-2.84285	-4.6343
10.1995	57.008	935.181	4313.43	15.3616	-2.87103	-4.63629
10.2995	56.5442	936.536	4325.21	15.3433	-2.8998	-4.6396
10.3996	56.08	938.082	4337.23	15.324	-2.92921	-4.64424
10.4996	55.6164	957.27	4388.31	15.2279	-2.94453	-4.62713
10.5997	55.1536	961.337	4398.71	15.1974	-2.97308	-4.63142
10.6997	54.69	962.673	4409.28	15.1787	-3.00482	-4.6409
10.7997	54.2253	963.884	4420.03	15.1604	-3.03761	-4.65215
10.8998	53.7595	965.217	4430.97	15.1415	-3.07127	-4.66486
10.9998	53.2923	966.694	4442.09	15.1219	-3.10584	-4.67904
11.0999	52.8237	968.32	4453.42	15.1015	-3.14135	-4.69472
11.1999	52.3534	970.057	4464.95	15.0803	-3.17787	-4.71191
11.2999	51.8813	972.029	4476.69	15.0583	-3.21543	-4.73068
11.4	51.4072	974.12	4488.65	15.0354	-3.2541	-4.75105
11.5	50.931	976.371	4500.84	15.0118	-3.29393	-4.77308
11.6001	50.4525	978.788	4513.26	14.9872	-3.33501	-4.79684
11.7001	49.9716	981.375	4525.92	14.9618	-3.37738	-4.82237
11.8001	49.488	984.138	4538.84	14.9354	-3.42114	-4.84975
11.9002	49.0016	987.081	4552.02	14.908	-3.46636	-4.87907
12.0002	48.5122	990.21	4565.48	14.8797	-3.51313	-4.91039
12.1003	48.0195	993.535	4579.23	14.8503	-3.56156	-4.94383
12.2003	47.5234	997.062	4593.27	14.8198	-3.61174	-4.97947
12.3003	47.0236	1000.8	4607.62	14.7881	-3.6638	-5.01745
12.4004	46.5198	1004.76	4622.3	14.7553	-3.71786	-5.05789
12.5004	46.0119	1008.94	4637.32	14.7212	-3.77407	-5.10093
12.6005	45.4996	1013.37	4652.7	14.6858	-3.83257	-5.14673
12.7005	44.9823	1008.3	4631.92	14.6931	-3.90529	-5.21114
12.8005	44.4576	1004.15	4649.09	14.696	-3.98066	-5.27833
12.9006	43.927	1008.87	4668.8	14.6586	-4.04877	-5.33532
13.0006	43.3905	1014.91	4689.09	14.6149	-4.11876	-5.39432
13.1007	42.8481	1021.47	4704.02	14.5685	-4.19189	-5.4569
13.2007	42.2991	1028.5	4723.62	14.5196	-4.26853	-5.52351
13.3007	41.7433	1036	4743.93	14.4682	-4.34899	-5.59449
13.4008	41.1804	1060.22	4846.1	14.3392	-4.44645	-5.64077
13.5008	40.6154	1091.67	4859.61	14.1753	-4.55685	-5.67729
13.6009	40.0436	1099.99	4873.66	14.1182	-4.67232	-5.76232
13.7009	39.4626	1105.49	4888.19	14.0739	-4.75999	-5.86019
13.8009	38.8714	1110.97	4903.22	14.0294	-4.77066	-5.96658
13.901	38.2691	1116.86	4918.8	13.9833	-4.88906	-6.08163
14.001	37.6548	1123.29	4934.95	13.9322	-5.01603	-6.20625
14.1011	37.0276	1130.34	4951.75	13.8784	-5.15265	-6.3416
14.2011	36.3863	1138.11	4969.23	13.8207	-5.30018	-6.48909
14.3011	35.7295	1146.71	4987.49	13.7582	-5.46017	-6.65041
14.4012	35.0558	1156.28	5006.58	13.6902	-5.63445	-6.8276
14.5012	34.3636	1166.99	5026.61	13.6157	-5.82526	-7.02311



DYNAMIC ANALYSIS

ENERGY : 05-Mar-87 01:33 PM

EQUILIBRATION CYLINDER PARAMETERS:

PISTON AREA IN<sup>2</sup> 5.52  
EQUILIBRATOR VOLUME IN<sup>3</sup> 1200.00  
AMBIENT TEMPERATURE deg-F 160.00  
AMBIENT PRESSURE LB/IN<sup>2</sup> 14.70  
BALANCE PRESSURE LB/IN<sup>2</sup> 5414.00  
BALANCE POSITION DEG 0.00  
CHARGE PRESSURE AT 70 deg-F & 14.7 PSI LB/IN<sup>2</sup> 2690.00  
X LOCATION OF WIRE ROPE INCH -2.00  
Y LOCATION OF WIRE ROPE INCH 35.50

ELEVATION CYLINDER PARAMETERS:

MAXIMUM MANUAL PRESSURE LB/IN<sup>2</sup> 3000.000  
MAXIMUM MANUAL POWER INPUT HP 0.300  
STARTING DECELERATION PRESS LB/IN<sup>2</sup> 3000.000  
MAXIMUM DECELERATION TORQUE FT-LB 10000.000  
ENERGY STORAGE ACCUMULATOR GAS VOLUME IN<sup>3</sup> 2500.000  
ENERGY STORAGE ACCUMULATOR GAS PRESSURE LB/IN<sup>2</sup> 3000.000  
PISTON DIAMETER INCH 3.000  
ROD DIAMETER INCH 1.500  
GAIN VALUE 0.650

SYSTEM PARAMETERS:

STARTING ELEVATION (THETA0) DEGREES 33.750  
ENDING ELEVATION (THETA1) DEGREES 72.000  
ELEVATING WEIGHT LBS 6348.450  
MASS MOMENT OF INERTIA (I) SLUG-FT<sup>2</sup> 40176.600

ELEVATION CYCLE

TIME (SEC)	ELEVATION (DEG)	ELEVATION PRESSURE (PSI)	EQUILIBRATOR PRESSURE (PSI)	ELEVATION FLOWRATE (GPM)	EQUILIBRATOR FLOWRATE (GPM)	ANGULAR VELOCITY (DEG/SEC)
.099	33.9936	2668.72	4777.27	6.61391	3.85419	4.63454
.199	34.6164	2074.75	4746.84	11.0461	6.21156	7.50256
.299	35.4386	1644.49	4717.32	13.3565	7.17843	8.72369
.398998	36.3299	1433.4	4692.18	14.3401	7.33381	8.9993
.498997	37.2254	1352.97	4670.08	14.6816	7.19696	8.87226
.598996	38.1004	1330.07	4649.74	14.7596	6.93604	8.6151
.698995	38.9481	1328.2	4630.53	14.7438	6.66147	8.33724
.798993	39.7687	1332.53	4612.17	14.701	6.40297	8.07546
.898992	40.5643	1337.75	4594.55	14.6549	6.16742	7.83803
.998991	41.3375	1342.26	4577.58	14.6126	5.95422	7.62721
1.099	42.0907	1345.7	4561.22	14.5758	5.76086	7.43797
1.199	42.8259	1348.11	4545.43	14.5442	5.58465	7.26818
1.299	43.545	1349.63	4530.15	14.5172	5.42322	7.11523
1.39901	44.2496	1350.39	4515.36	14.4941	5.27461	6.97694
1.49901	44.941	1350.5	4501.03	14.4745	5.13719	6.85152
1.59902	45.6204	1350.06	4487.12	14.4579	5.00959	6.73748
1.69902	46.2889	1349.14	4473.61	14.4439	4.89069	6.63359
1.79903	46.9475	1347.8	4460.48	14.4321	4.77954	6.53882
1.89903	47.597	1346.08	4447.69	14.4225	4.67533	6.45229
1.99904	48.2383	1344.03	4435.25	14.4147	4.57737	6.37328
2.09902	48.872	1341.68	4423.12	14.4087	4.48505	6.30114
2.19902	49.4988	1339.05	4411.29	14.4043	4.39786	6.23534
2.29902	50.1193	1336.17	4399.74	14.4013	4.31534	6.1754
2.39901	50.7341	1333.05	4388.46	14.3996	4.23711	6.12094
2.499	51.3423	1331.96	4316.63	14.2864	4.13322	6.02835



TIME	DEPRESSION	ELEVATION	ELEVATION	EQUILIBRATOR	ANGULAR	
(SEC)	(DEG)	(PSI)	(PSI)	PRESSURE	VELOCITY	
2.69899	52.5341	1365.86	4287.34	14.201	3.97019	5.9045
2.7989	53.1224	1365.34	4273.17	14.1884	3.90335	5.86333
2.8989	53.707	1363.94	4259.31	14.1801	3.84036	5.82762
2.99897	54.2882	1362.14	4245.75	14.1739	3.78039	5.79628
3.09896	54.8664	1360.04	4232.48	14.1693	3.72309	5.76893
3.19895	55.4421	1357.7	4219.48	14.166	3.66826	5.7454
3.29894	56.0156	1355.12	4206.74	14.1641	3.61572	5.72555
3.39894	56.5873	1352.32	4194.24	14.1633	3.56533	5.7093
3.49893	57.1576	1349.3	4181.98	14.1638	3.51696	5.69658
3.59892	57.7268	1346.06	4169.95	14.1654	3.47049	5.68735
3.69891	58.2952	1342.6	4158.14	14.1682	3.42581	5.68157
3.79891	58.8634	1338.93	4146.54	14.1721	3.38281	5.67925
3.8989	59.4314	1335.05	4135.14	14.1772	3.34143	5.68039
3.99889	59.9996	1330.96	4123.93	14.1834	3.30157	5.68502
4.09889	60.5685	1326.66	4112.91	14.1907	3.26317	5.69319
4.19888	61.1384	1322.15	4102.07	14.1991	3.22613	5.70496
4.29887	61.7086	1317.43	4091.41	14.2086	3.19041	5.72041
4.39886	62.2826	1312.49	4080.91	14.2193	3.15593	5.73966
4.49886	62.8577	1307.34	4070.57	14.231	3.12266	5.76283
4.59885	63.4353	1301.98	4060.39	14.2438	3.09052	5.79008
4.69884	64.0158	1296.39	4050.36	14.2578	3.05949	5.8216
4.79883	64.5997	1290.59	4040.48	14.2728	3.0295	5.85759
4.89883	65.1874	1284.56	4030.73	14.289	3.00053	5.8983
4.99882	65.7795	1278.32	4021.12	14.3062	2.97253	5.94402
5.09881	66.3764	1271.85	4011.64	14.3246	2.94546	5.99507
5.19881	66.9786	1265.17	4002.29	14.344	2.91929	6.05184
5.2988	67.5869	1258.27	3993.06	14.3644	2.89398	6.11476
5.39879	68.1993	1246.26	3983.22	9.3922	1.87471	4.03475
5.49878	68.8097	1245.06	3983.26	6.95661	1.38126	3.0052
5.59878	69.4257	1243.92	3919.25	6.76302	1.33658	2.93684
5.69877	69.0784	1246.58	3913.42	6.706	1.3193	2.92769
5.79876	69.3719	1246.44	3907.63	6.70613	1.31339	2.94408
5.89876	69.6673	1245.73	3901.88	6.71204	1.30869	2.96381
5.99875	69.9647	1246.92	3896.16	6.71882	1.3042	2.98481
6.09874	70.2643	1246.09	3890.48	6.72596	1.29984	3.00689
6.19873	70.5661	1246.22	3884.82	6.73343	1.2956	3.03009
6.29873	70.8703	1245.32	3879.2	6.74123	1.29146	3.05448
6.39872	71.177	1245.38	3873.61	6.74938	1.28744	3.08013
6.49871	71.4863	1245.41	3868.05	6.75789	1.28354	3.1071
6.5987	71.7985	1245.41	3862.52	6.76677	1.27976	3.13549

PRESSURE AFTER EXTENDED TIME = 4222.96  
 ELEVATION CYLINDER STROKE = 24.1001  
 TEMPERATURE COMPENSATION VOLUME = 179.419

DEPRESSION CYCLE	ELEVATION	ELEVATION	EQUILIBRATOR	ANGULAR	
TIME	(DEG)	(PSI)	PRESSURE	VELOCITY	
6.6987	71.9772	1245.57	4278.28	3.66299	-1.27881
6.79869	71.7047	1245.09	4283.24	11.1103	-3.85198
6.89868	71.2631	1246.59	4290.19	13.9504	-4.78457
6.99868	70.7711	1154.21	4297.45	14.7368	-4.99666
7.09867	70.2702	1108.31	4304.8	14.9312	-5.00695
7.19866	69.7711	1094.92	4312.23	14.9797	-4.97126
7.29865	69.2761	1089.19	4319.75	14.9941	-4.9279
7.39865	68.7855	1085.32	4327.35	15.0002	-4.88537
7.49864	68.2989	1082.02	4335.04	15.0038	-4.84534
7.59863	67.8172	1097.13	4398.2	14.9258	-4.78238
7.69862	67.3413	1101.79	4403.9	14.8939	-4.73759
7.79862	66.8692	1099.74	4409.68	14.8919	-4.7051
7.89861	66.4002	1096.67	4415.52	14.8944	-4.67659
7.9986	65.9338	1093.58	4421.42	14.8969	-4.65049
8.09864	65.47	1090.64	4427.4	14.8987	-4.62646

8.19868	65.0084	1087.87	4433.45	14.8997	-2.35421	-4.60434
8.2987	64.549	1085.27	4439.57	14.8999	-2.37418	-4.58406
8.39876	64.0915	1082.83	4445.76	14.8993	-2.39445	-4.56552
8.4988	63.6358	1080.55	4452.03	14.898	-2.41502	-4.54867
8.59884	63.1817	1078.42	4458.37	14.8959	-2.43594	-4.53344
8.69888	62.7291	1076.43	4464.79	14.8932	-2.45719	-4.51977
8.79893	62.2777	1074.59	4471.29	14.8897	-2.4788	-4.50761
8.89897	61.8275	1072.88	4477.88	14.8856	-2.50079	-4.49693
8.99901	61.3783	1071.31	4484.54	14.8808	-2.52316	-4.48767
9.09905	60.9299	1069.87	4491.29	14.8754	-2.54594	-4.47982
9.19909	60.4823	1068.56	4498.13	14.8694	-2.56914	-4.47333
9.29913	60.0352	1067.37	4505.06	14.8627	-2.59279	-4.46818
9.39917	59.5885	1066.3	4512.08	14.8555	-2.6169	-4.46435
9.49921	59.1423	1065.35	4519.19	14.8476	-2.64148	-4.46183
9.59925	58.6963	1064.51	4526.39	14.8392	-2.6657	-4.46059
9.69929	58.2503	1063.79	4533.7	14.8302	-2.69218	-4.46063
9.79933	57.8043	1063.19	4541.1	14.8206	-2.71834	-4.46193
9.89937	57.358	1062.69	4548.61	14.8104	-2.74507	-4.46451
9.99941	56.9114	1062.31	4556.23	14.7997	-2.77241	-4.46834
10.0995	56.4643	1062.03	4563.95	14.7884	-2.80037	-4.47345
10.1995	56.0166	1061.87	4571.79	14.7765	-2.82898	-4.47982
10.2995	55.5683	1061.81	4579.74	14.7641	-2.85828	-4.48748
10.3996	55.1191	1061.86	4587.81	14.7511	-2.88829	-4.49644
10.4996	54.669	1062.02	4596	14.7375	-2.91906	-4.5067
10.5997	54.2177	1062.28	4604.32	14.7233	-2.95061	-4.51829
10.6997	53.7653	1062.65	4612.77	14.7086	-2.98299	-4.53124
10.7997	53.3115	1063.13	4621.35	14.6932	-3.01625	-4.54557
10.8998	52.8561	1063.72	4630.07	14.6773	-3.05041	-4.56131
10.9998	52.3992	1064.43	4638.93	14.6607	-3.08553	-4.5785
11.0999	51.9404	1065.24	4647.94	14.6436	-3.12167	-4.59717
11.1999	51.4797	1066.17	4657.1	14.6258	-3.15887	-4.61738
11.2999	51.0169	1067.21	4666.41	14.6073	-3.1972	-4.63917
11.4	50.5518	1068.38	4675.89	14.5882	-3.23672	-4.66259
11.5	50.0843	1069.66	4685.54	14.5684	-3.27749	-4.68772
11.6001	49.6143	1071.06	4695.36	14.5479	-3.31959	-4.71461
11.7001	49.1414	1072.6	4705.37	14.5267	-3.36311	-4.74334
11.8001	48.6655	1074.27	4715.56	14.5047	-3.40812	-4.774
11.9002	48.1866	1076.07	4725.95	14.4819	-3.45471	-4.80668
12.0002	47.7042	1078.01	4736.55	14.4584	-3.503	-4.84147
12.1003	47.2182	1080.09	4747.35	14.4339	-3.5531	-4.8785
12.2003	46.7285	1082.31	4758.35	14.4071	-3.59568	-4.90501
12.3003	46.2381	1112.66	4823.6	14.2531	-3.62886	-4.9148
12.4004	45.7466	1115.95	4831.91	14.2224	-3.68005	-4.95708
12.5004	45.2466	1117.28	4840.42	14.2007	-3.73914	-5.00558
12.6005	44.7434	1118.51	4849.13	14.1792	-3.80114	-5.05754
12.7005	44.235	1119.85	4858.03	14.157	-3.86601	-5.11285
12.8005	43.7208	1121.35	4867.16	14.1338	-3.93395	-5.17171
12.9006	43.2006	1123.01	4876.51	14.1096	-4.00522	-5.23439
13.0006	42.6739	1124.85	4886.1	14.0843	-4.08009	-5.3012
13.1007	42.1403	1126.88	4895.95	14.0579	-4.15889	-5.37248
13.2007	41.5993	1129.13	4906.06	14.0301	-4.24199	-5.44864
13.3007	41.0504	1131.62	4916.47	14.0009	-4.3298	-5.53012
13.4008	40.4931	1134.36	4927.18	13.9701	-4.42278	-5.61742
13.5008	39.9268	1137.39	4938.22	13.9376	-4.52146	-5.71114
13.6009	39.3508	1140.74	4949.61	13.9032	-4.62646	-5.81193
13.7009	38.7643	1144.44	4961.39	13.8667	-4.7385	-5.92059
13.8009	38.1685	1148.57	4973.58	13.8277	-4.85839	-6.038
13.901	37.5655	1153.16	4986.21	13.786	-4.98709	-6.16524
14.001	36.9332	1158.29	4999.33	13.7411	-5.12574	-6.30354
14.1011	36.2955	1164.04	5012.99	13.6927	-5.27568	-6.45439
14.2011	35.642	1170.53	5027.24	13.64	-5.43851	-6.61954
14.3011	34.9712	1177.89	5042.14	13.5823	-5.61616	-6.80114
14.4012	34.2814	1186.28	5057.76	13.5186	-5.81099	-7.00179



DYNAMIC ANALYSIS  
ENERGY OVER ELEVATION : 05-Mar-87 01:49 PM

EQUILIBRATION CYLINDER PARAMETERS:

PISTON AREA  
IN<sup>2</sup> 5.52  
IN<sup>3</sup> 1200.00  
AMBIENT TEMPERATURE  
deg-F 10.00  
AMBIENT PRESSURE  
LB/IN<sup>2</sup> 14.70  
BALANCE PRESSURE  
LB/IN<sup>2</sup> 5414.00  
BALANCE POSITION  
DEG 0.00  
CHARGE PRESSURE AT 70 deg-F & 14.7 PSI  
LB/IN<sup>2</sup> 2690.00  
X LOCATION OF WIRE ROPE  
INCH -2.00  
Y LOCATION OF WIRE ROPE  
INCH 35.50

ELEVATION CYLINDER PARAMETERS:

MAXIMUM MANUAL PRESSURE  
LB/IN<sup>2</sup> 3000.000  
MAXIMUM MANUAL POWER INPUT  
HP 0.300  
STARTING DECELERATION PRESS  
LB/IN<sup>2</sup> 3000.000  
MAXIMUM DECELERATION TORQUE  
FT-LB 10000.000  
ENERGY STORAGE ACCUMULATOR GAS VOLUME  
IN<sup>3</sup> 2500.000  
ENERGY STORAGE ACCUMULATOR GAS PRESSURE  
LB/IN<sup>2</sup> 3000.000  
PISTON DIAMETER  
INCH 3.000  
ROD DIAMETER  
INCH 1.500  
GAIN VALUE  
0.650

SYSTEM PARAMETERS:

STARTING ELEVATION (THETA0)  
DEGREES 0.000  
ENDING ELEVATION (THETA1)  
DEGREES 72.000  
ELEVATING WEIGHT  
LBS 6348.450  
MASS MOMENT OF INERTIA (I)  
SLUG-FT<sup>2</sup> 40176.600

ELEVATION CYCLE TIME (SEC)	ELEVATION (DEG)	ELEVATION PRESSURE (PSI)	EQUILIBRATOR PRESSURE (PSI)	ELEVATION FLOWRATE (GPM)	EQUILIBRATOR FLOWRATE (GPM)	ANGULAR VELOCITY (DEG/SEC)
0.99897	3.90254	1956.2	5217.4	11.6369	10.9579	12.4878
0.99891	10.4553	1749.42	4887.36	12.5546	11.5498	12.9964
1.49901	16.7317	1837.17	4568.96	11.871	10.6528	11.9856
1.99904	22.4604	1959.63	4249.01	10.9575	9.59117	10.9067
2.499	27.6619	2069.98	3975.08	10.0641	8.59621	9.9645
2.99897	32.134	2090.02	3629.36	9.75314	6.37219	7.56811
3.49893	35.3098	2298.92	3315.68	8.05982	4.362	5.29579
3.99889	37.6237	2442.95	3024.54	6.64048	3.19252	3.94899
4.49886	39.3	2567.76	2824.74	5.12656	2.27974	2.86254
4.99882	40.6029	2559.89	2923.59	5.13432	2.15721	2.74289
5.49878	42.0084	2532.58	2832.05	5.38107	2.13379	2.75257
5.99875	43.3226	2549.09	2751.74	5.0807	1.91405	2.50489
6.49871	44.5203	2563.83	2682.27	4.79573	1.72807	2.29312
6.99868	45.6707	2507.29	2799.81	5.4685	1.88457	2.53618
7.49864	46.9939	2457.47	2785.15	5.94744	1.9666	2.69213
7.9986	48.3454	2432.42	2770.93	6.14525	1.94478	2.71188
8.4986	49.706	2408.04	2757.13	6.23846	1.92066	2.73151
8.99901	51.078	2383.07	2743.72	6.31705	1.89855	2.75746
9.49921	52.4646	2357.39	2730.68	6.706	1.87841	2.79034
9.99941	53.8695	2330.91	2717.98	6.89783	1.86009	2.83074
10.4996	55.2967	2303.53	2705.59	7.09322	1.84151	2.8795
10.9998	56.7505	2275.15	2693.5	7.29285	1.8286	2.93773
11.5	58.2362	2245.6	2681.69	7.49765	1.81536	3.00693
12.0002	59.7596	2214.71	2670.13	7.70867	1.80301	3.08912
12.5004	61.3278	2182.26	2658.81	7.92726	1.79404	3.18699

13.0006 62.9497 2147.96 2667.7 8.42902 4.7802 2.30960  
 13.500 64.636 2111.45 2636.8 8.39407 1.7805 3.44611  
 14.001 66.401 2072.27 2626.08 8.64685 1.77724 3.62  
 14.5012 68.2001 2396.87 2616.95 5.55285 1.10764 2.38704  
 15.0014 69.1981 2472.85 2611.84 4.5048 1.97111 1.97111  
 15.5016 70.1897 2469.29 2567.13 4.50804 1.872165 2.01215  
 16.0018 71.2152 2461.01 2559.34 4.5803 1.873224 2.09215

PRESSURE AFTER EXTENDED TIME = 1670.55  
 ELEVATION CYLINDER STROKE = 48.1097  
 TEMPERATURE COMPENSATION VOLUME = 379.151

DEPRESSION CYCLE TIME	ELEVATION (SEC)	ELEVATION (DEG)	ELEVATION PRESSURE (PSI)	EQUILIBRATOR PRESSURE (PSI)	ANGULAR VELOCITY (DEG/SEC)	
16.5016	71.7065	1623.16	3680.92	11.4742	-1.62956	-3.97832
17.0013	69.1934	793.119	3737.59	15.503	-2.28342	-5.08714
17.501	66.7039	785.35	3799.2	15.4868	-2.37494	-4.88204
18.0007	64.3007	784.679	3865.3	15.4391	-2.47148	-4.73938
18.5005	61.9582	814.608	3993.82	15.3569	-2.55636	-4.61175
19.0002	59.6678	820.461	4047.94	15.1792	-2.66927	-4.56182
19.4999	57.3902	824.78	4106.46	15.1056	-2.79765	-4.53301
19.9996	55.1092	833.391	4170.02	15.0112	-2.93996	-4.57602
20.4994	52.8088	846.487	4239.44	14.8945	-3.09956	-4.63109
20.9991	50.4725	864.479	4315.74	14.753	-3.28095	-4.72054
21.4988	48.0819	888.046	4400.27	14.5825	-3.49036	-4.84919
21.9985	45.6156	918.239	4494.81	14.3767	-3.73673	-5.02529
22.4983	43.0472	949.972	4586.61	14.1374	-4.04246	-5.27401
22.998	40.3243	978.864	4673.14	13.8635	-4.44632	-5.63795
23.4977	37.3874	1056.93	4881.27	13.4802	-4.91679	-6.0696
23.9974	34.1889	1107.85	4939.88	13.1306	-5.67427	-6.83254
24.4972	30.4594	1164.23	5017.6	12.7274	-6.99666	-8.22725
24.9969	25.8876	1214.26	5189.95	12.4876	-8.30091	-9.54934
25.4966	21.2224	1186.96	5378.13	12.3235	-8.13524	-9.22147
25.9963	16.63	1205.14	5478.03	12.0856	-8.13754	-9.13478
26.4961	12.0633	1227.23	5586.47	11.8266	-8.11025	-9.11538
26.9958	7.38716	1208.61	5710.04	11.7951	-8.23031	-9.30169
27.4955	4.06593	2130.23	7133.59	3.82624	-2.70075	-3.07636
27.9952	2.64143	2150.1	7163.11	3.32668	-2.36069	-2.70073
28.495	1.35083	2159.32	7197.7	3.00546	-2.14039	-2.45963
28.9947	.183825	2167.96	7230.17	2.67412	-1.91147	-2.20635



DYNAMIC ANALYSIS

ENERGY OVER ELEVATION : 05-Mar-87 02:21 PM

EQUILIBRATION CYLINDER PARAMETERS:

PISTON AREA  
 EQUILIBRATOR VOLUME  
 AMBIENT TEMPERATURE  
 AMBIENT PRESSURE  
 BALANCE PRESSURE  
 BALANCE POSITION  
 CHARGE PRESSURE AT 70 deg-F & 14.7 PSI  
 X LOCATION OF WIRE ROPE  
 Y LOCATION OF WIRE ROPE

IN<sup>2</sup> 5.52  
 IN<sup>3</sup> 1200.00  
 deg-F 70.00  
 LB/IN<sup>2</sup> 14.70  
 LB/IN<sup>2</sup> 5414.00  
 DEG 0.00  
 LB/IN<sup>2</sup> 2690.00  
 INCH -2.00  
 INCH 35.50

ELEVATION CYLINDER PARAMETERS:

MAXIMUM MANUAL PRESSURE  
 MAXIMUM MANUAL POWER INPUT  
 STARTING DECELERATION PRESS  
 MAXIMUM DECELERATION TORQUE  
 ENERGY STORAGE ACCUMULATOR GAS VOLUME  
 ENERGY STORAGE ACCUMULATOR GAS PRESSURE  
 PISTON DIAMETER  
 ROD DIAMETER  
 GAIN VALUE

LB/IN<sup>2</sup> 3000.000  
 HP 0.300  
 LB/IN<sup>2</sup> 3000.000  
 FT-LB 10000.000  
 IN<sup>3</sup> 2500.000  
 LB/IN<sup>2</sup> 3000.000  
 INCH 3.000  
 INCH 1.500  
 INCH 0.650

SYSTEM PARAMETERS:

STARTING ELEVATION (THETA0)  
 ENDING ELEVATION (THETAf)  
 ELEVATING WEIGHT  
 MASS MOMENT OF INERTIA (I)

DEGREES 0.000  
 DEGREES 72.000  
 LBS 6348.450  
 SLUG-FT<sup>2</sup> 40176.600

ELEVATION CYCLE TIME	ELEVATION (DEG)	ELEVATION PRESSURE (PSI)	EQUILIBRATOR PRESSURE (PSI)	ELEVATION FLOWRATE (GPM)	EQUILIBRATOR FLOWRATE (GPM)	ANGULAR VELOCITY (DEG/SEC)
498997	3.91447	1943.18	5246.29	11.7105	11.0268	12.5658
998991	10.552	1699.16	4971.99	12.8144	11.7846	13.2594
1.49901	17.0646	1681.02	4828.97	12.7032	11.3838	12.8123
1.99904	23.3104	1756.3	4539.5	12.0982	10.5486	12.0254
2.499	29.2474	1648.13	4329.95	12.4904	10.0372	11.7254
2.99897	34.3309	1640.53	4196.81	12.372	7.07076	8.52272
3.49893	38.1166	1729.53	4096.15	11.7637	5.52392	6.86211
3.99889	41.3434	1719.39	4052.26	11.7191	4.77405	6.11582
4.49886	44.1874	1817.29	3825.92	11.0585	4.03354	5.33143
4.99882	46.7519	1831.94	3734.95	10.8875	3.62928	4.95237
5.49878	49.1596	1836.33	3655.42	10.7843	3.32705	4.69373
5.99875	51.4591	1834.62	3584.6	10.7234	3.06987	4.51503
6.49871	53.66	1872.02	3446.77	10.4211	2.82586	4.28461
6.99868	55.7738	1876.61	3368.07	10.3278	2.65227	4.1804
7.49864	57.8484	1874.82	3296.25	10.2782	2.511	4.12539
7.9986	59.906	1868.41	3230.07	10.261	2.39339	4.11243
8.4988	61.9675	1857.6	3168.59	10.2744	2.29493	4.14107
8.99901	64.0287	1883.54	3035.23	10.8507	2.15618	4.10422
9.49921	66.0983	1877.74	2961.58	10.0364	2.0737	4.18582
9.99941	68.1741	2315.27	2895.39	6.45551	1.28823	2.77387
10.4996	69.2771	2442.15	2862.34	4.3263	.967455	2.16156
10.9998	70.3728	2436.32	2830.78	4.0155	.957341	2.22329
11.5	71.5026	2429.95	2799.92	4.99787	.949043	2.29881

PRESSURE AFTER EXTENDED TIME = 4017.22  
 ELEVATION CYLINDER STROKE = 48.1097

TEMPERATURE COMPENSATION VOLUME = 298.095

DEPRESS. TIME	CYCLE ELEVATION (DEG)	ELEVATION PRESSURE (PSI)	EQUILIBRATOR PRESSURE (PSI)	ANGULAR VELOCITY (DEG/SEC)	
(SEC)					
12.0002	71.0429	1092.95	4049.12	14.1998	-2.03529
12.5004	68.6034	957.29	4083.89	14.7717	-4.84482
13.0006	66.248	941.706	4121.35	14.792	-2.19579
13.5008	63.9594	931.567	4161.86	14.7868	-4.79544
14.001	61.7151	926.16	4205.79	14.7591	-2.26226
14.5012	59.4972	925.098	4253.63	14.7106	-2.38229
15.0014	57.29	928.231	4305.96	14.6417	-2.48523
15.5016	55.0827	955.108	4399.84	14.4626	-4.45663
16.0018	52.865	961.459	4451.9	14.3748	-4.42066
16.5016	50.6105	970.997	4508.55	14.2697	-4.41461
17.0013	48.3018	984.313	4570.66	14.1439	-2.83442
17.501	45.9181	1002.03	4639.35	13.9933	-4.4669
18.0007	43.4233	1006.28	4683.06	13.9019	-3.1606
18.5005	40.7899	1077.42	4854.29	13.4803	-4.68485
19.0002	38.0035	1109.14	4924.37	13.2394	-4.85664
19.4999	34.9361	1145.37	5008.18	12.9626	-5.1267
19.9996	31.4344	1207.82	5113.79	12.5287	-3.91298
20.4994	27.1957	1196.48	5256.82	12.4564	-5.3687
20.9991	22.5768	1211.86	5411.73	12.2305	-4.68769
21.4988	18.0569	1247.38	5526.41	11.8955	-5.81754
21.9985	13.4973	1208.93	5119.63	13.0325	-6.50175
22.4983	8.60394	1212.7	5737.41	11.807	-7.60574
22.998	4.60519	2104.05	7684.1	4.29729	-9.25134
23.4977	3.27079	2165.57	7177.1	3.07157	-8.97139
23.9974	2.08136	2172.12	7205.42	2.79296	-9.98479
24.4972	.997741	2178.26	7232.2	2.5093	-9.25119
24.9969	.241735E-01	2183.94	7257.04	2.22069	-3.44366
					-2.482
					-2.27447
					-2.05857
					-1.83432



[illegible]

M	M	999	000	EEEEEE	000	55555
M	M	9	0	E	0	5
M	M	9	0	E	0	555
M	M	9999	0	EEEE	0	5
M	M	9	0	E	0	5
M	M	9	0	E	0	5
M	M	999	000	EEEEEE	000	555

[illegible]

File \_RSC000\$DUA5:[M90.GREEN\_JE.VMS.PROGRAMS.LTHDISIMULATION.P12;1 (1615,17,0), last revised on 5-MAR-1987 14:50, is a 14 block sequential file owned by UIC [M90.GREEN\_JE]. The records are variable length with implied (CR) carriage control. The longest record is 93 bytes.

Job SIMULATION (100) queued to LMSYS on 5-MAR-1987 14:51 by user M90205, UTC [M90, GREEN\_JE], under account M93 at priority 100, started on printer VENUSSTIME6: on 5-MAR-1987 14:52 from queue LMSYS.

[illegible]

ENERGY RECOVERY ELEVATION : 05-Mar-87 02:32 PM

# EQUILIBRATION CYLINDER PARAMETERS:

PISTON AREA IN"2 5.52  
 EQUILIBRATOR VOLUME IN"3 1200.00  
 AMBIENT TEMPERATURE DEG-F 160.00  
 AMBIENT PRESSURE LB/IN"2 14.70  
 BALANCE PRESSURE LB/IN"2 5414.00  
 BALANCE POSITION DEG 0.00  
 CHARGE PRESSURE AT 70 DEG-F & 14.7 PSI LB/IN"2 2690.00  
 X LOCATION OF WIRE ROPE INCH -2.00  
 Y LOCATION OF WIRE ROPE INCH 35.50

# ELEVATION CYLINDER PARAMETERS:

MAXIMUM MANUAL PRESSURE LB/IN"2 3000.000  
 MAXIMUM MANUAL POWER INPUT HP 0.300  
 STARTING DECELERATION PRESS LB/IN"2 3000.000  
 MAXIMUM DECELERATION TORQUE FT-LB 10000.000  
 ENERGY STORAGE ACCUMULATOR GAS VOLUME IN"3 2500.000  
 ENERGY STORAGE ACCUMULATOR GAS PRESSURE LB/IN"2 3000.000  
 PISTON DIAMETER INCH 3.000  
 ROD DIAMETER INCH 1.500  
 GAIN VALUE 0.650

# SYSTEM PARAMETERS:

STARTING ELEVATION (THETA0) DEGREES 0.000  
 ENDING ELEVATION (THETA1) DEGREES 72.000  
 ELEVATING WEIGHT LBS 6348.450  
 MASS MOMENT OF INERTIA (I) SLUG-FT"2 40176.600

# ELEVATION CYCLE

TIME (SEC)	ELEVATION (DEG)	ELEVATION PRESSURE (PSI)	EQUILIBRATOR PRESSURE (PSI)	ELEVATION FLOWRATE (GPM)	EQUILIBRATOR FLOWRATE (GPM)	ANGULAR VELOCITY (DEG/SEC)
.498997	3.92036	1938.02	5256.53	11.7395	11.0538	12.5964
.998991	10.6295	1650.6	5031.65	13.061	12.0078	13.5096
1.49901	17.2563	1642.07	4865.24	12.899	11.55	13.0021
1.99904	23.6594	1650.39	4652.7	12.6546	11.0161	12.5721
2.499	29.8086	1516.14	4482.48	13.156	10.121	11.8585
2.99897	34.8835	1548.54	4321.44	12.8394	7.11309	8.60832
3.49893	38.7323	1634.51	4203.1	12.2691	5.59832	6.99288
3.99889	42.0002	1661.35	4107.28	12.0233	4.76923	6.15173
4.49886	44.9369	1668.4	4026.3	11.8959	4.2226	5.63145
4.99882	47.6215	1737.01	3842.86	11.425	3.70068	5.10891
5.49878	50.1211	1720.29	3799.27	11.4476	3.43011	4.90873
5.99875	52.5276	1721.52	3721.44	11.371	3.17956	4.72816
6.49871	54.8601	1717.94	3651.12	11.3263	2.97656	4.61164
6.99868	57.1484	1709.64	3586.87	11.3128	2.80965	4.50007
7.49864	59.4181	1699.52	3500.83	11.3127	2.66708	4.53266
7.9986	61.6774	1698.78	3442.01	11.2604	2.53008	4.53286
8.4988	63.9631	1679.28	3388.51	11.3205	2.43161	4.62028
8.99901	66.3084	1654.19	3339.37	11.4143	2.34981	4.77296
9.49921	68.4593	2380.23	3301.21	5.73773	1.1398	2.47735
9.99941	69.677	2389.54	3280.22	5.57955	1.08772	2.46422
10.4996	70.9306	2381.29	3259.89	5.62829	1.07732	2.55375

PRESSURE AFTER EXTENDED TIME = 4292.97  
 ELEVATION CYLINDER STROKE = 48.1097  
 TEMPERATURE COMPENSATION VOLUME = 179.419

DEPRESSION CYCLE		ELEVATION		EQUILIBRATOR		ANGULAR	
TIME	(SEC)	(DEG)	PRESSURE (PSI)	PRESSURE (PSI)	VELOCITY (DEG/SEC)	VELOCITY (DEG/SEC)	
10.9998	71.8778	2189.43	4280.1	7.52442	-1.06614	-2.62021	
11.5	69.6631	1089.11	4313.57	14.1897	-2.07513	-4.69889	
12.0002	67.3634	1096.88	4403.33	14.1039	-2.13901	-4.48776	
12.5004	65.1515	1083.28	4431.24	14.1177	-2.22486	-4.36906	
13.0006	62.9876	1071.75	4460.77	14.1206	-2.31791	-4.29205	
13.5008	60.854	1063.57	4492.07	14.1066	-2.41821	-4.24743	
14.001	58.735	1058.28	4525.36	14.0777	-2.52751	-4.23152	
14.5012	56.6169	1055.6	4560.86	14.035	-2.64787	-4.24262	
15.0014	54.4873	1055.38	4598.85	13.9789	-2.78184	-4.28065	
15.5016	52.3316	1057.59	4639.71	13.9093	-2.93288	-4.3471	
16.0018	50.135	1062.31	4683.88	13.8253	-3.10561	-4.44529	
16.5016	47.8802	1069.76	4731.97	13.7251	-3.30649	-4.58094	
17.0013	45.5576	1108.52	4834.3	13.4684	-3.50773	-4.71391	
17.501	43.1407	1114.68	4876.66	13.3662	-3.80286	-4.9666	
18.0007	40.5764	1124.6	4924.45	13.2396	-4.17671	-5.30927	
18.5005	37.8093	1140.59	4979.54	13.0749	-4.67257	-5.78898	
19.0002	34.7501	1167.56	5045.24	12.8427	-5.37596	-6.49964	
19.4999	31.2376	1219.15	5128.17	12.4624	-6.48414	-7.65901	
19.9996	26.9551	1180.86	5240.06	12.5319	-8.05564	-9.30841	
20.4994	22.307	1191.64	5371.69	12.3314	-8.10091	-9.20812	
20.9991	17.7223	1205.95	5459.62	12.1142	-8.11947	-9.14527	
21.4988	13.1543	1219.32	5553.15	11.9033	-8.12818	-9.13233	
21.9985	8.51026	1092.85	5400.01	12.4597	-8.65894	-9.76733	
22.4983	4.30345	2083.2	7169.54	4.58646	-3.23476	-3.68218	
22.998	2.55355	2097.54	7066.5	4.24245	-3.0096	-3.4441	
23.4977	.852761	2098.98	7093.38	4.08958	-2.91709	-3.35838	

PART NUMBER: 12585718, 12585719, Energy Storage Accumulator

DESCRIPTION: This is a dual-function accumulator. One function is to store energy to power the hydraulic system, the other function is to return the cannon to battery during counter-recoil.

Nitrogen Volume: 4800 cu. in. (2400 cu. in. each)  
Pre-Charge Pressure: 2640 psi at 70 F

STATUS:

Mounting, size, flow, pressure and cycle life requirements have been determined and were provided to York to be finalized.

AUTHOR: Jeff Ireland

## ACCUMULATOR SIZING (ENERGY STORAGE)

$$V_0 = 4800 \text{ in}^3$$

$$P_{RELIEF} = 3800 \text{ PSI}$$

$$\Delta V = 900 \text{ in}^3$$

$$T_H = 160^\circ\text{F} = 620^\circ\text{R}$$

$$T_C = 70^\circ\text{F} = 530^\circ\text{R}$$

$$T_L = -25^\circ\text{F} = 435^\circ\text{R}$$

$$\Delta V_{BS} = 650 \text{ in}^3$$

$$P_{SYS} = 3000 \text{ PSI}$$

$$I) \quad \frac{P_C V_0}{T_C} = \frac{P_R (V_0 - \Delta V)}{T_H}$$

$$P_C = (T_C/T_H) (1 - \Delta V/V_0) P_R = \underline{\underline{2640 \text{ PSI}}}$$

$$II \quad \frac{P_C V_0}{T_C} = \frac{P_L V_0}{T_L}$$

$$\underline{\underline{P_L = (T_L/T_C) P_C = 2166 \text{ PSI}}}$$

III  $\Delta V$  VOLUME TO BLOW RELIEF AT  $435^\circ\text{R}$

$$\frac{P_L V_0}{T_L} = \frac{P_R (V_0 - \Delta V_R)}{T_C}$$

$$\underline{\underline{\Delta V_R = V_0 (P_R - P_L)/P_R = V_0 (1 - P_L/P_R) = 2064 \text{ in}^3}}$$

IV PEAK PRESSURE

$$\underline{\underline{P_{MAX} = P_R / [1 - \frac{\Delta V_{BS}}{V_0 - \Delta V_R}]^{1.4} = 5555 \text{ PSI}}}$$

$$V \quad \underline{\underline{V_{MAX} = \text{MAX OIL IN ACCUMULATOR} = 2064 \text{ in}^3 + 650 \text{ in}^3 = 2714 \text{ in}^3}}$$

$$VI \quad \frac{P_L V_0}{T_L} = \frac{P_{SYS} (V_0 - \Delta V_{SYS})}{T_C}$$

$$\underline{\underline{\Delta V_{SYS} = V_0 (1 - P_L/P_{SYS}) = 1334 \text{ in}^3}}$$

$$\text{VOLUME OF OIL } \geq 3000 \text{ PSI} = 2064 \text{ in}^3 - 1334 \text{ in}^3 = \underline{\underline{730 \text{ in}^3}}$$

$$I. \quad \frac{P_c V_c}{T_c} = \frac{P_R (V_c - \Delta V)}{T_H}$$

$$\begin{aligned} T_H &= 620^\circ R \\ T_c &= 530^\circ R \\ T_L &= 435^\circ R \end{aligned}$$

$$\underline{P_c = (T_c/T_H) (1 - \Delta V/V_c) P_R}$$

$$II. \quad \frac{P_c V_c}{T_c} = \frac{P_L V_c}{T_L}$$

Empty Accumulator Pressure at 435°R

$$\underline{P_L = (T_L/T_c) P_c = (T_L/T_c) (T_c/T_H) (1 - \Delta V/V_c) P_R = (T_L/T_H) (1 - \Delta V/V_c) P_R}$$

$$III. \quad \frac{P_L V_c}{T_L} = \frac{P_R V_{435}}{T_L} \quad \text{VOLUME TO BLOW RELIEF AT 435°R}$$

$$\underline{V_{435} = (P_L/P_R) V_c = (T_L/T_H) (1 - \Delta V/V_c) V_c = (T_L/T_H) (V_c - \Delta V)}$$

$$IV. \quad \underline{P_{MAX} = P_R / [1 - \Delta V_{BS}/V_{435}]^{1.4}}$$

$$\begin{aligned} V_c &= 4800 \text{ in}^3 \\ \Delta V_{BS} &= 650 \text{ in}^3 \\ P_{SYS} &= 3000 \text{ PSI} \end{aligned}$$

$$V. \quad \frac{P_{SYS} V_c}{T_{SYS}} = \frac{P_c V_c}{T_c}$$

$$\underline{T_{SYS} = (P_{SYS}/P_c) T_c = (P_{SYS}/P_R) \left( \frac{1}{1 - \Delta V/V_c} \right) T_H = (P_{SYS}/P_R) \left( \frac{V_c}{V_c - \Delta V} \right) T_H = K V_c}$$

$$VI. \quad \frac{P_{SYS} V_L}{T_L} = \frac{P_c V_c}{T_c}$$

$$K = (P_{SYS}/P_R) \left[ \frac{T_H}{V_c - \Delta V} \right]$$

$$\underline{V_L = (P_c/P_{SYS}) (T_L/T_c) V_c = (T_L/T_H) (P_R/P_{SYS}) (V_c - \Delta V) = T_L/K}$$

$V_0$	$\Delta V$	$V_{OIL\ MAX}$	$P_{MAX}$	$T_{SYS}$	$\Delta V_L$	$\Delta V_H$	$P_{PRESS}$
4800.	900.	2714	7309	-2°F	240.	0	5000
4800	800	2644	7230	-13.6°F	123.	100	5000
4600	900	2654	7185	22°F	446	0	4800
4600	800	2583	7098	9°F	334	100	4800
4600	700	2514	7016	-3°F	222	200	4800
4400	900	2594	6888	48°F	635	0	4600
4400	900	2594	6767	71°F	800	0	4400
4400	900	2594	6613	84°F	880	0	4300
4800	900	2714	5847	112°F	1,152	(912) 0	4000
4800	900	2714	5555	142°F	1,334	(739) 0	3800
4800	900	2714	5117	171°F	1,608	(1129) 0	3500
5000	900	2774	4580	249°F	1931	(1193) 0	3200
5000	900	2774	5152	170°F	1518	(575) 0	3600
5000	900	2774	5295	153°F	1152	(671) 0	3700

## EMPLACE VOLUME

$$\text{MAX. TRAVERSE FROM C/L} = (55.002\text{in} - 48.000\text{in}) \left(\frac{\pi}{4}\right) [4.75\text{in}]^2 \\ = \underline{\underline{99.332\text{ in}^3}}$$

$$\text{MAX. ELEVATION} = \underline{\underline{227.001\text{ in}^3}}$$

$$\text{WHEEL ACTUATOR (REAR)} = 2(15.720\text{ in}^3) = \underline{\underline{31.440\text{ in}^3}}$$

$$\text{WHEEL ACTUATOR (FRONT)} = 2(7.024\text{ in}^3) = \underline{\underline{14.048\text{ in}^3}}$$

$$\text{CANNON TO BATTERY} = (105\text{in}) \left(\frac{\pi}{4}\right) [(3.0\text{in})^2 - (2.25\text{in})^2] = \underline{\underline{324.713\text{ in}^3}}$$

$$\text{RAMMER} = \underline{\underline{34.785\text{ in}^3}}$$

$$\text{BREECH (OPEN)} = \underline{\underline{9.572\text{ in}^3}}$$

$$\text{BREECH (CLOSE)} = \underline{\underline{11.928\text{ in}^3}}$$

$$\text{PRIMER} = \underline{\underline{.397\text{ in}^3}}$$

$$\text{LANYARD} = \underline{\underline{.068\text{ in}^3}}$$

$$\underline{\underline{\text{TOTAL EMPLACE VOLUME} = 753.284\text{ in}^3}}$$



# DISPLACE VOLUME

$$\text{MAX. TRAVERSE TO C/L} = (48.00 - 40.323) \text{ in} \left(\frac{\pi}{4}\right) (4.25 \text{ in})^2 = \underline{\underline{108.908 \text{ in}^3}}$$

$$\text{MAX. DEPRESSION TO TOW} = \underline{\underline{311.905 \text{ in}^3}}$$

$$\text{WHEEL ACTUATOR TO TOW (REAR)} = 2(38.692 \text{ in} - 28.128 \text{ in}) \left(\frac{\pi}{4}\right) (3.25 \text{ in})^2 = \underline{\underline{175.272 \text{ in}^3}}$$

$$\text{WHEEL ACTUATOR TO TOW (FRONT)} = 2(37.152 \text{ in} - 25.140 \text{ in}) \left(\frac{\pi}{4}\right) (2.375 \text{ in})^2 = \underline{\underline{106.430 \text{ in}^3}}$$

$$\text{GUN FROM BATTERY TO STOW \& 1/2 CANNON TO BATTERY} = \frac{324.713 \text{ in}^3}{2} = \underline{\underline{162.357 \text{ in}^3}}$$

$$\underline{\underline{\text{TOTAL DISPLACE} = 864.872 \text{ in}^3}}$$

UNIT NUMBER: 12505415, Equilibration Intermitter

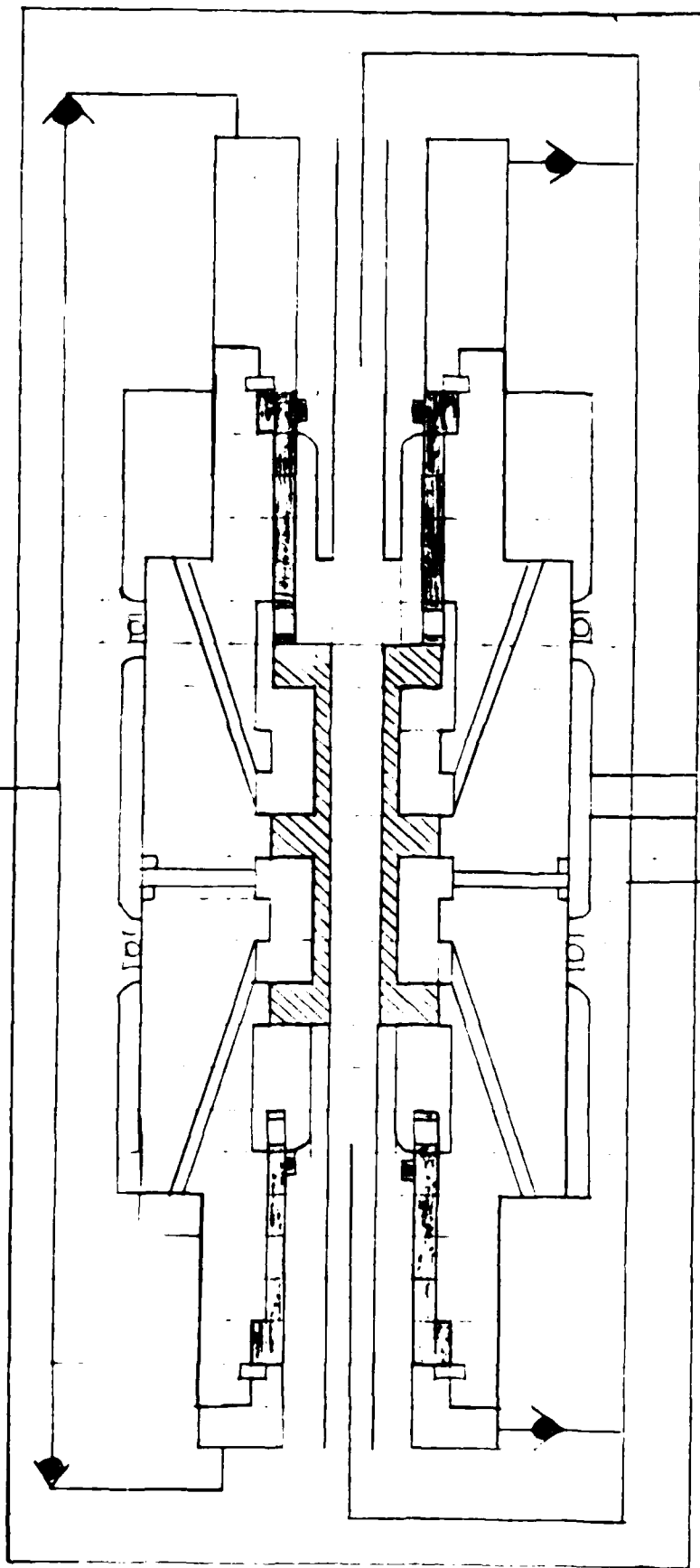
DESCRIPTION:

This device allows the canisters to use the lower pressure oil (5000 psi) stored in the energy recovery accumulator to pump up the high pressure (5400 psi) equilibration accumulator.

Notes:

Two sets of technical specifications were provided to the contractor for this device.

Subject: Test Results



INTENSIFIER

## DESCRIPTION: FIRING STABILITY

(Note: The reader is also referred to Section C/060, Mass-Coordinate Data File, since the data was used for firing stability analysis.)

A three-dimensional stability program, called HOP.BAS, was originally written prior to Phase I work, but was enhanced frequently throughout the LTHD program to meet current needs.

The purpose of the program is to provide insight into firing stability by simulating LTHD firing throughout the recoil stroke and up to the time of maximum hop (at the tips of the trails). The basic inputs include component weight and CG data, system geometry, firing conditions and a recoil force profile.

The simulation is flexible to include a wide range of firing conditions. These include any combination of: firing on a forward slope, firing on a side slope, any elevation angle, any traverse angle, and any spade position or orientation with the ground.

A list of program inputs is described below:

VARIABLE NAME	DESCRIPTION
BL	Horiz. dist. from pivot point to tip of barrel, inches
SL	Horiz. dist. from pivot point to trail pad, inches, with trail in tow position
SLA	Angle between fwd. direction and trails, radians
H	Vertical trunnion height from pivot, inches
HXF	Horiz. dist. from trunnion to pivot point (point of ground contact on spade), inches
HXS	Horiz. dist. from trunnion center to side pivot plane, inches (used only in analysis of side hop)
HXCG	Horiz. dist. from CG of non-recoiling components to side pivot plane, inches (side hop analysis only)
KSF	Individual trail spring constant, lb/inch (as in a cantilevered beam)
SWFD	Traverse angle of tube, degrees
EAD	DE or elevation angle of tube, degrees
SLFD	Forward slope of ground, degrees (uphill = +)
SSLFD	Side slope of ground, degrees

## Data files:

LFBA.DAT See description found in Section C/060.  
 LFTS.DAT Same.  
 LFTE.DAT Same.  
 FORC: A data file consisting of recoil force values (lbs.)  
 and recoil stroke values (feet) at 1.0 msec time  
 intervals starting at  $t = 0$  and ending at the  
 end of the recoil stroke.

The following pages of this section contain the current program inputs, listing and corresponding outputs.

It should be noted that in early work, HOP.BAS also served the purpose of determining the maximum allowable recoil force profile for given geometry. If the LTHD were completely rigid (or at least very stiff) this information would have been useful to specify a recoil force profile that would minimize hop. However, because sufficient flexibility exists in the trails, it was determined that a recoil force profile whose peak occurs early on in the stroke and whose magnitude exceeds the "maximum allowable recoil force" curve will result in a lower hop height than if the recoil force profile were to remain under such a curve at all times. Consequently, the purpose of the program shifted more towards an analytical tool than a design tool.

A rough analysis was also performed on a 7500 lb LTHD to explore the weight-range tradeoff. This analysis was not performed under contract, but is included for the reader's reference. The calculations and results are contained at the end of this section.

#### STATUS:

The most recent computer runs of HOP.BAS produced the results shown in Table C/140-1. These results indicate that the LTHD remains quite stable during worst-case normal firing conditions (firing from battery position) and also remains fairly stable during a cookoff condition. The results presented are for worst-cases only. Further simple runs would indicate less and less hop as the firing QE increases.

Phase I work included varying traverse angle and forward and side slopes. It was concluded from this work that firing at non-zero traverse angles does not cause higher hop heights compared to a 0 degree traverse angle at the same QE.

Furthermore, computer runs with non-zero forward (uphill) and side slopes did show a reduction in LTHD stability (i.e., increase in hop height values). It was shown that sufficient stability was maintained when firing within the  $\pm 10\%$  hill grade requirement. The reader is referred to the Phase I Dynamic Analysis Report for additional information in this area.

AUTHOR: Scott Dacko

TABLE C/140-1 LTHD STABILITY RESULTS

3

SPADE ALL THE WAY IN GROUND, FIRE FROM BATTERY POSITION:

Starting Weight at Trails, pounds:	3427
Starting System CG- Z-Dir., inches:	163.44
Starting Trail Deflection, inches:	1.14
Barrel Deflection at Shot Ejection, in.:	.0036
Maximum Trail Hop Height, inches:	1.21

SPADE COMPLETELY OUT OF GROUND, FIRE FROM BATTERY POSITION:

Starting Weight at Trails, pounds:	3099
Starting System CG- Z-Dir., inches:	147.78
Starting Trail Deflection, inches:	1.03
Barrel Deflection at Shot Ejection, in.:	.026
Maximum Trail Hop Height, inches:	2.65

SPADE ALL THE WAY IN GROUND, FIRE FROM LOAD POS. (COOKOFF):

Starting Weight at Trails, pounds:	3223
Starting System CG- Z-Dir., inches:	153.68
Starting Trail Deflection, inches:	1.07
Barrel Deflection at Shot Ejection, in.:	.0064
Maximum Trail Hop Height, inches:	2.13

SPADE COMPLETELY OUT OF GROUND, FIRE FROM LOAD POS. (COOKOFF):

Starting Weight at Trails, pounds:	2895
Starting System CG- Z-Dir., inches:	138.03
Starting Trail Deflection, inches:	.965
Barrel Deflection at Shot Ejection, in.:	.048
Maximum Trail Hop Height, inches:	4.15

STABILITY COMPUTER PROGRAM

PART 1. INPUTS

PART 2. PROGRAM LISTING

PART 3. OUTPUTS

STABILITY COMPUTER PROGRAM

PART 1. INPUTS



BBBBBBBBBBBB  
BBBBBBBBBBBB  
BBBBBBBBBBBB

DDDDDDDD		AAAAAA	TTTTTTTTTT	;;;	222222
DDDDDDDD		AAAAAA	TTTTTTTTTT	;;;	222222
DD	DD	AA	AA	TT	;;;
DD	DD	AA	AA	TT	22
DD	DD	AA	AA	TT	22
DD	DD	AA	AA	TT	22
DD	DD	AA	AA	TT	22
DD	DD	AA	AA	TT	22
DD	DD	AAAAA	AA	TT	;;;
DD	DD	AAAAA	AA	TT	;;;
DD	DD	AAAAA	AA	TT	22
DD	DD	AAAAA	AA	TT	22
DD	DD	AA	AA	TT	;;
DD	DD	AA	AA	TT	;;
DDDDDDDD		AA	AA	TT	;;
DDDDDDDD		AA	AA	TT	;;

Job HOP3 (1347) queued to LN on 8-APR-1987 13:11 by user M20E96, UIC [M20,DACKO SG], under account M22 at priority 100, started on printer VENUS\$TXM6: on 8-APR-1987 13:14 from queue LNSYS.

BBBBBBBBBBBB  
BBBBBBBBBBBB  
BBBBBBBBBBBB

5000.  
0.001  
5001.  
0.004  
5004.  
0.010  
5022.  
0.023  
5081.  
0.045  
5236.  
0.077  
5568.  
0.119  
6169.  
0.171  
7126.  
0.231  
8516.  
0.296  
10400.  
0.367  
12826.  
0.442  
15831.  
0.520  
19405.  
0.600  
23519.  
0.680  
28178.  
0.761  
33383.  
0.842  
39133.  
0.924  
45426.  
1.005  
52150.  
1.087  
58846.  
1.168  
64989.  
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70060.  
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1.492  
75000.  
1.572  
75000.  
1.652  
75000.  
1.731  
75000.  
1.810  
75000.  
1.888  
75000.  
1.966

75000.  
2.043  
75000.  
2.120  
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2.196  
75000.  
2.272  
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2.347  
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2.421  
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2.495  
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2.569  
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2.641  
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2.714  
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2.785  
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2.927  
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2.997  
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75000.  
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3.270  
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3.337  
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3.403  
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3.469  
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3.534  
73802.  
3.598  
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3.850  
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3.972  
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4.092

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7.092  
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AAAAA  
AAAAA  
AAAAA

15

BBBBBBBBB		AAAAAA	TTTTTTTTTTT	;;;;	222222
BBBBBBBBB		AAAAAA	TTTTTTTTTTT	;;;;	222222
BB	BB	AA	AA	TT	22
BB	BB	AA	AA	TT	22
BB	BB	AA	AA	TT	22
BB	BB	AA	AA	TT	22
BBBBBBBBB		AA	AA	TT	22
BBBBBBBBB		AA	AA	TT	22
BB	BB	AAAAAAAAA	TT	22	
BB	BB	AAAAAAAAA	TT	22	
BB	BB	AA	AA	TT	22
BB	BB	AA	AA	TT	22
BBBBBBBBB		AA	AA	TT	2222222222
BBBBBBBBB		AA	AA	TT	2222222222

Job HOP3 (1347) queued to LN on 8-APR-1987 13:11 by user M20E96, UIC [M20,DACKO SG], under account M22 at priority 100, started on printer VENUS\$TXM6: on 8-APR-1987 13:13 from queue LNSYS.

AAAAAAA  
AAAAAAA  
AAAAAAA

18974.  
3.001  
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8.575

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82552.  
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82552.  
8.636  
82553.  
8.638  
82553.  
8.640  
82553.  
8.641  
-9999

## STABILITY COMPUTER PROGRAM

## PART 2. PROGRAM LISTING



VVVVVVVVVV  
VVVVVVVVVV  
VVVVVVVVVV

M	M	222	000	EEEE	999	666			
MM	MM	2	2	0	0	E	9	9	6
M	M	M	2	0	00	E	9	9	6
M	M	2	0	0	0	EEEE	9999	6666	
M	M	2	00	0	E	9	6	6	
M	M	2	0	0	E	9	6	6	
M	M	22222	000	EEEE	999	666			

H	H	OOO	PPPP		BBBB	AAA	SSSS	::	1	222				
H	H	O	O	P	P	B	B	A	A	S	::	11	2	2
H	H	O	O	P	P	B	B	A	A	S		1		2
HHHHH	O	O	PPPP		BBBB	A	A	SSS	::	1			2	
H	H	O	O	P		B	B	AAAAA		S	::	1		2
H	H	O	O	P	..	B	B	A	A		S	:	1	2
H	H	OOO	P	..	BBBB	A	A	SSSS	:			111	22222	

File HSC000\$DUA9:[M20.DACKO SG.VMS]HOP.BAS;12 (2457,13,2), last revised on 10-MAR-1987 17:09, is a 63 block sequential file owned by UIC [M20,DACKO\_SG]. The records are variable length with implied (CR) carriage control. The longest record is 151 bytes.

Job HOP (1340) queued to LN on 8-APR-1987 12:56 by user M20E96, UIC [M20,DACKO SG], under account M22 at priority 100, started on printer VENUS\$TXM6: on 8-APR-1987 12:56 from queue LNSYS.

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5  REM  MODIFIED TO PROVIDE BEST EST'S FOR NON-ZERO TRAVERSE
6  REM  (FOR CGX, CGY, ETC)
7  REM  S. DACKO
10 REM  PROGRAM HOP.BAS - WRITTEN BY S. DACKO, 07/16/85
15 REM  PROGRAM READS FROM ANY GRAVITY.BAS DATA FILES, 3/3/87
18 REM
20 REM  FOR COMPLETE WRITEUP/INSTRUCTIONS, SEE USER'S MANUAL
30 REM  THIS PROGRAM ALLOWS THE USER TO EVALUATE ARTILLERY SYSTEM
40 REM  GEOMETRY, INCLUDING RECOIL SYSTEM CHARACTERISTICS, IN TERMS
50 REM  OF "HOP" AND STABILITY. THIS PROGRAM WILL FIND:
60 REM  1. STABILIZING MOMENTS AND MAXIMUM ALLOWABLE FORCES RESULTING
70 REM  FROM THE SYSTEM GEOMETRY
80 REM  2. STABILIZING, OVERTURNING AND SAFETY MOMENTS RESULTING FROM
90 REM  AN INPUT FORCE ACTING ON THE SYSTEM GEOMETRY
100 REM  -----
110 REM
130 DIM NWT(500),NXC(500),NYC(500)
140 DIM RWT(500),RXC(500),RYC(500)
150 DIM RXCN(500)
160 DIM RXCS(500)
170 DIM RXCNA(500),RYCNA(500)
175 DIM NXCS(500),NXCNA(500),NYCNA(500)
180 DIM F(600),X(600),X1(600)
190 DIM BRXCG(500),TSXCG(500),TEXCG(500)
930 REM
940 REM  -----
950 REM  FIND MAXIMUMS OR USE DATA
960 REM
970 PRINT "FIND:  1. MAX. FORCES & MOMENTS"
980 PRINT "          2. MOMENTS FROM FORCE DATA"
990 PRINT "(ENTER 1 OR 2):"
1000 INPUT FI
1010 IF FI = 1 THEN GOTO 1042
1020 PRINT "FROM:  1. RECOIL.BAS  OR  2. RECOIL.FORT"
1030 PRINT "(ENTER 1 OR 2):"
1040 INPUT PROG
1041 REM
1042 PRINT "OUTPUT TO FILE?  1-YES  2-NO  "
1043 INPUT OUT
1044 IF OUT=2 THEN GOTO 1070
1045 PRINT "ENTER FILENAME, E.G. [.OUTPUT]XXX.LIS  "
1046 INPUT FILE$
1047 OPEN FILE$ FOR OUTPUT AS FILE #9, RECORDTYPE ANY
1050 REM
1060 REM  -----
1070 REM  DEFINE REMAINDER OF SYSTEM GEOMETRY
1080 REM
1090 REM  BL = DIST (IN) FROM PIVOT POINT TO TIP OF BARREL
1100 BL = 260
1110 REM  SL = DIST. (IN) FROM PIVOT TO FRONT PAD CENTER ALONG TRAIL
1120 SL = 259
1130 REM  SLA = ANGLE BETW FWD DIR AND TRAILS, RADIANS
1140 SLA = 35*3.14159/180
1150 REM  H = HT AT WHICH FORCE IS APPLIED, INCHES
1151 PRINT "INPUT TRUNNION HEIGHT, IN. (18.5 TO 31.25)"
1152 INPUT H
1170 REM  HXF = HORIZ. DIST. FROM TRUNNION TO PT OF GND CONTACT ON SPADE
1171 PRINT "INPUT HORIZ. DIST. FROM TRUNNION TO"
1172 PRINT " POINT OF GROUND CONTACT ON SPADE, IN. (24 TO 14.25)"
1173 INPUT HXF
1190 REM  HXS = HORIZ. DIST. FROM SIDE PIVOT PLANE TO WHERE INPUT FORCE IS APP
1200 HXS = 44

```

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1210 REM HXCG = HORIZ. DIST. FROM SIDE PIVOT PLANE TO CG OF NON-REC COMPONENT
1220 HXCG = 43
1270 REM KSP = SPRING CONSTANT OF EACH TRAIL, LBS/IN
1280 PRINT "INPUT SPRING CONSTANT OF EACH TRAIL (LBS/IN)"
1285 INPUT KSP
1290 REM
1300 REM -----
1310 REM DEFINE SYSTEM CONDITION OF FIRING
1320 REM
1330 REM SWPD = ANGLE OF SWEEP, DEGREES
1335 PRINT "INPUT TRAVERSE ANGLE OF GUN, DEGREES:"
1340 INPUT SWPD
1350 SWP = 3.14159/180*SWPD
1360 REM EAD = ELEVATION ANGLE, DEGREES
1365 PRINT "INPUT ELEVATION ANGLE OF GUN, DEGREES:"
1370 INPUT EAD
1380 EA = 3.14159/180*EAD
1390 REM
1400 REM -----
1410 REM DEFINE EXTERNAL CONDITIONS OF FIRING
1420 REM
1430 REM SLPD = SLOPE OF HILL - FORWARD, DEGREES
1435 PRINT "INPUT FORWARD (UPWARD) SLOPE OF HILL, DEGREES:"
1440 INPUT SLPD
1450 SLP = 3.14159/180*SLPD
1460 REM SSLPD = SLOPE OF HILL - SIDE, DEGREES
1465 PRINT "INPUT SIDE SLOPE OF HILL, DEGREES:"
1470 INPUT SSLPD
1480 SSLP = 3.14159/180*SSLPD
1490 REM -----
1500 REM FIND SINES AND COSINES AND OTHER CONSTANTS
1510 REM
1520 CSSLP = COS(SSLP)
1530 SSSLP = SIN(SSLP)
1540 CSLP = COS(SLP)
1550 CSLPL = CSLP
1560 SSLP = SIN(SLP)
1570 SSLPL = SSLP
1580 CEA = COS(EA)
1590 SEA = SIN(EA)
1600 CSWP = COS(SWP)
1610 SSWP = SIN(SWP)
1620 DENF = CEA*H*CSWP-SEA*HXP
1630 DENS = CEA*H*SSWP-SEA*HXS
1640 REM
1650 REM -----
1660 REM W1 = ANGULAR VELOCITY VALUE, INITIALLY = 0
1670 W1 = 0
1680 REM HA = INITIAL HOP ANGLE, RADIANS
1690 HA = 0
1700 HAL = HA
1701 REM
1702 REM -----
1712 REM READ IN RECOIL COMPONENT DATA
1713 OPEN "[.WEIGHT]LFBR.DAT" FOR INPUT AS FILE #1, RECORDTYPE ANY
1714 REM INPUT INITIAL DATA FROM FILE TO BE IGNORED
1715 INPUT #1, DES$
1716 INPUT #1, BRWT
1717 INPUT #1, BRGX
1718 INPUT #1, BRGY
1719 INPUT #1, BRGZ
1720 INPUT #1, BRJYZ

```

```
1721 INPUT #1, BRJXY
1722 INPUT #1, BRJXZ
1723 REM INPUT DATA TO BE USED, EXCEPT FOR DESN,BRXCG(I)
1724 I=1
1725 INPUT #1, BRNO
1726 INPUT #1, DESN
1727 IF (DESN = 0) THEN GOTO 1736
1728 INPUT #1, RWT(I)
1729 INPUT #1, BRXCG(I)
1730 INPUT #1, RYC(I)
1731 INPUT #1, RXC(I)
1732 RYC(I)=RYC(I)+H
1733 RXC(I)=RXC(I)+HXF
1734 I=I+1
1735 GOTO 1725
1736 CLOSE #1
1737 NRPTS=BRNO-1
1738 REM DIVIDE BARREL INTO 11 DISTRIBUTED MASS SEGMENTS
1739 FOR I = 1 TO 10
1740 RWT(NRPTS+I) = RWT(NRPTS)/11
1741 RXC(NRPTS+I) = RXC(NRPTS) - 100 + I*20
1742 RYC(NRPTS+I) = RYC(NRPTS)
1743 NEXT I
1744 RWT(NRPTS) = RWT(NRPTS+1)
1745 RXC(NRPTS) = RXC(NRPTS) - 100
1746 REM -----
1748 REM FIND TOTAL SYS. WT, SYS. C.G., CGX, CGY, MASS M.I., J
1750 REM UNITS: CG, INCHES; MASS M.I., FT-LB-S^2
1751 WT1 = 0
1752 REM READ IN NON-RECOILING / NON-ELEV/TRAV COMPONENTS
1753 REM THEN FIND C.G. OF COMPONENTS
1754 OPEN "[.WEIGHT]LPTS.DAT" FOR INPUT AS FILE #1, RECORDTYPE ANY
1755 REM INPUT INITIAL DATA FROM FILE TO BE IGNORED
1756 INPUT #1, DESS
1757 INPUT #1, TSWT
1758 INPUT #1, TSCGX
1759 INPUT #1, TSCGY
1760 INPUT #1, TSCGZ
1762 INPUT #1, TSJYZ
1763 INPUT #1, TSJXY
1764 INPUT #1, TSJXZ
1766 REM INPUT DATA TO BE USED, EXCEPT FOR TSNO,DESN,TSXCG(I)
1767 I=1
1768 INPUT #1, TSNO
1769 INPUT #1, DESN
1770 IF (DESN = 0) THEN GOTO 1785
1772 INPUT #1, NWT(I)
1773 INPUT #1, TSXCG(I)
1774 INPUT #1, NYC(I)
1775 INPUT #1, NXC(I)
1776 NYC(I)=NYC(I)+H
1777 NXC(I)=NXC(I)+HXF
1778 WT1 = WT1+NWT(I)
1779 CGST1 = CGST1 + NWT(I)/32.2*HXCG
1780 CGXT1 = CGXT1+NWT(I)/32.2*NXC(I)
1781 CGYT1 = CGYT1+NWT(I)/32.2*NYC(I)
1782 J1 = J1+((NXC(I)/12)^2+(NYC(I)/12)^2)*NWT(I)/32.2
1783 I=I+1
1784 GOTO 1768
1785 CLOSE #1
1787 REM
1788 REM READ IN NON-RECOILING / ELEV/TRAV COMPONENTS DATA
```

```

1789 REM THEN FIND C.G. OF NON-RECOILING / ELEV/TRAV COMPONENTS
1790 OPEN "[.WEIGHT]LPTE.DAT" FOR INPUT AS FILE #1, RECORDTYPE ANY
1791 REM INPUT INITIAL DATA FROM FILE TO BE IGNORED
1792 INPUT #1, DESS
1793 INPUT #1, TEWT
1794 INPUT #1, TECGX
1795 INPUT #1, TECGY
1796 INPUT #1, TECGZ
1797 INPUT #1, TEJYZ
1798 INPUT #1, TEJXY
1799 INPUT #1, TEJXZ
1800 REM INPUT DATA TO BE USED, EXCEPT FOR TENO,DESN,TEXCG(I)
1802 INPUT #1, TENO
1804 INPUT #1, DESN
1806 IF (DESN = 0) THEN GOTO 2024
1808 INPUT #1, NWT(I)
1809 INPUT #1, TEXCG(I)
1810 INPUT #1, NYC(I)
1812 INPUT #1, NXC(I)
2009 NYC(I)=NYC(I)+H
2010 NXC(I)=NXC(I)+HXF
2014 WT1 = WT1+NWT(I)
2015 NXCNA(I) = (NXC(I)-HXF)*CSWP*CEA+HXF
2016 CGXT1 = CGXT1 + NWT(I)/32.2*NXCNA(I)
2017 NYCNA(I) = H+(NYC(I)-H)*CEA+NXC(I)*SEA
2018 CGYT1 = CGYT1 + NWT(I)/32.2*NYCNA(I)
2019 NXCS(I) = (NXC(I)-HXF)*SSWP*CEA+HXS
2020 CGST1 = CGST1 + NWT(I)/32.2*NXCS(I)
2021 J1 = J1+((NXCNA(I)/12)^2+(NYCNA(I)/12)^2)*NWT(I)/32.2
2022 I=I+1
2023 GOTO 1802
2024 CLOSE #1
2074 REM
2076 WT2 = 0
2080 REM FIND C.G. OF RECOILING COMPONENTS
2090 FOR I = 1 TO NRPTS+10
2100 WT2 = WT2+RWT(I)
2110 RXCNA(I) = (RXC(I)-HXF)*CSWP*CEA+HXF
2120 CGXT2 = CGXT2 + RWT(I)/32.2*RXCNA(I)
2130 RYCNA(I) = H+(RYC(I)-H)*CEA+RXC(I)*SEA
2140 CGYT2 = CGYT2 + RWT(I)/32.2*RYCNA(I)
2150 RXCS(I) = (RXC(I)-HXF)*SSWP*CEA+HXS
2160 CGST2 = CGST2 + RWT(I)/32.2*RXCS(I)
2170 J2 = J2+((RXCNA(I)/12)^2+(RYCNA(I)/12)^2)*RWT(I)/32.2
2180 NEXT I
2190 REM
2200 WT = WT1+WT2
2210 CGX = (CGXT1+CGXT2)/(WT/32.2)
2220 CGY = (CGYT1+CGYT2)/(WT/32.2)
2230 CGS = (CGST1+CGST2)/(WT/32.2)
2240 CGR = (CGX^2+CGY^2)^.5
2250 J = J1+J2
2260 THET1 = ATN(CGY/CGX)
2270 REM -----
2280 REM FIND EQUIVALENT SPRING CONSTANT FOR TWO TRAILS
2290 KSP = KSP*2
2300 WTB = WT*CSLP*CSSLP*CGX/(SL*COS(SLA))
2310 IF KSP = 0 THEN GOTO 2340
2320 DEFL2 = WTB/KSP
2330 GOTO 2350
2340 DEFL2 = 0
2350 DEFL0 = DEFL2

```

```

2360 REM FSP = FORCE OF THE SPRING, LBS
2370 FSP = KSP*DEFL2
2380 REM GWT = PRESSURE OR WEIGHT OF THE SYSTEM ON THE GROUND
2390 GWT = FSP
2400 FSPL = FSP
2410 HAD = HA*180/3.14159
2420 REM -----
2430 PRINT "INITIAL CONDITIONS:"
2440 PRINT "WEIGHT OF RECOILING COMPONENTS (LB) = ";WT2
2450 PRINT "WEIGHT OF NON-RECOILING COMPONENTS (LB) = ";WT1
2460 PRINT "SYSTEM WEIGHT (LB) = ";WT
2470 PRINT "INDIV. TRAIL'S SPRING CONSTANT (LB/IN) = ";KSP/2
2490 PRINT " "
2500 PRINT "AT MAXIMUM EXTENSION OF BARREL:"
2510 PRINT "CGZ (IN) = ";CGX
2520 PRINT "CGY (IN) = ";CGY
2530 PRINT "CGX (IN) = ";CGS
2540 PRINT "DEFLECTION OF TRAILS (IN) = ";DEFL0
2550 PRINT "MASS MOMENT OF INERTIA (FT-LB-S^2) = ";J
2560 PRINT " "
2570 PRINT "SWEEP ANGLE LEFT (DEGREES) = ";SWPD
2580 PRINT "ELEVATION ANGLE (DEGREES) = ";EAD
2590 PRINT "UPWARD SLOPE OF HILL - FORWARD (DEGREES) = ";SLPD
2600 PRINT "UPWARD SLOPE OF HILL - SIDE (DEGREES) = ";SSLPD
2605 PRINT " "
2608 REM
2609 IF OUT=2 THEN GOTO 2630
2610 PRINT #9,"INITIAL CONDITIONS:"
2611 PRINT #9,"WEIGHT OF RECOILING COMPONENTS (LB) = ";WT2
2612 PRINT #9,"WEIGHT OF NON-RECOILING COMPONENTS (LB) = ";WT1
2613 PRINT #9,"SYSTEM WEIGHT (LB) = ";WT
2614 PRINT #9,"INDIV. TRAIL'S SPRING CONSTANT (LB/IN) = ";KSP/2
2616 PRINT #9," "
2617 PRINT #9,"AT MAXIMUM EXTENSION OF BARREL:"
2618 PRINT #9,"CGZ (IN) = ";CGX
2619 PRINT #9,"CGY (IN) = ";CGY
2620 PRINT #9,"CGX (IN) = ";CGS
2621 PRINT #9,"DEFLECTION OF TRAILS (IN) = ";DEFL0
2622 PRINT #9,"MASS MOMENT OF INERTIA (FT-LB-S^2) = ";J
2623 PRINT #9," "
2624 PRINT #9,"SWEEP ANGLE LEFT (DEGREES) = ";SWPD
2625 PRINT #9,"ELEVATION ANGLE (DEGREES) = ";EAD
2626 PRINT #9,"UPWARD SLOPE OF HILL - FORWARD (DEGREES) = ";SLPD
2627 PRINT #9,"UPWARD SLOPE OF HILL - SIDE (DEGREES) = ";SSLPD
2628 PRINT #9," "
2629 REM
2630 IF FI = 2 THEN GOTO 2720
2640 PRINT "STROKE","CG-Z","MAX FORCE","STA MOM","CG X","MAX FORCE"
2650 PRINT "FEET","INCHES","LBS, W/O","FT-LBS","INCHES","LBS, W/O"
2660 PRINT "","","BACKW HOP","","","SIDE HOP"
2670 PRINT "-----","-----","-----","-----","-----","-----"
2680 REM
2681 IF OUT=2 THEN GOTO 2960
2682 PRINT #9,"STROKE","CG-Z","MAX FORCE","STA MOM","CG X","MAX FORCE"
2683 PRINT #9,"FEET","INCHES","LBS, W/O","FT-LBS","INCHES","LBS, W/O"
2684 PRINT #9,"","","BACKW HOP","","","SIDE HOP"
2685 PRINT #9,"-----","-----","-----","-----","-----","-----"
2690 GOTO 2960
2700 REM -----
2710 REM INPUT FORCE DATA FROM SPECIFIED DATA FILE
2720 PRINT "ENTER INPUT FORCE DATAFILE NAME, E.G., [.OUTPUT]XXX.LIS "
2740 INPUT FORC$

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2750 OPEN FORC$ FOR INPUT AS FILE #1, RECORDTYPE ANY
2760 P = 0
2770 P = P+1
2780 INPUT #1, F(P)
2790 IF F(P) = -9999 THEN GOTO 2840
2800 REM
2810 INPUT #1, X1(P)
2820 IF PROG = 2 THEN X1(P) = X1(P)*12
2830 GOTO 2770
2840 CLOSE #1
2850 P = P-1
2860 ST = 1
2870 B = 1
2880 PRINT "DATA FILE: ";FORC$
2890 PRINT " "
2900 PRINT " "
2910 PRINT "STROKE,","CG -Z,","STABLE ","OVERTURN-","SAFETY","WT. AT"
2920 PRINT "INCHES ","INCHES","MOMENT,","ING MOM.,","MOMENT","EA TRAIL,"
2930 PRINT "","","FT-LBS ","FT-LBS ","FT-LBS","LBS "
2940 PRINT "-----","-----","-----","-----","-----","-----"
2941 IF OUT=2 THEN GOTO 3060
2942 PRINT #9,"DATA FILE: ";FORC$
2943 PRINT #9," "
2944 PRINT #9," "
2945 PRINT #9,"STROKE,","CG -Z,","STABLE ","OVERTURN-","SAFETY","WT. AT"
2946 PRINT #9,"INCHES ","INCHES","MOMENT,","ING MOM.,","MOMENT","EA TRAIL,"
2947 PRINT #9,"","","FT-LBS ","FT-LBS ","FT-LBS","LBS "
2948 PRINT #9,"-----","-----","-----","-----","-----","-----"
2950 GOTO 3060
2960 FOR P = 0 TO 102
2970 X1(P) = P
2980 NEXT P
2990 ST = 3
3000 B = 0
3010 P = 102
3020 REM
3030 REM -----
3040 REM FIND THE NET MOMENT ON THE SYSTEM FOR EACH TIME T
3050 REM
3060 FOR N = B TO P STEP ST
3070 CGXT2 = 0
3080 CGYT2 = 0
3090 CGST2 = 0
3100 J2 = 0
3110 REM -----
3120 REM CHANGE SYS. X-COORD, C.G. X'S,C.G., MASS M.I., J
3130 REM
3140 FOR I = 1 TO NRPTS+10
3150 RXCN(I) = RXC(I) - X1(N)
3160 RXCNA(I) = (RXCN(I)-HXF)*CSWP*CEA+HXF
3170 RXCS(I) = (RXCN(I)-HXF)*SSWP*CEA+HXS
3180 CGST2 = CGST2 + RWT(I)/32.2*RXCS(I)
3190 CGXT2 = CGXT2 + RWT(I)/32.2*RXCNA(I)
3200 RYCNA(I) = RYC(I)+RXCN(I)*SEA
3210 CGYT2 = CGYT2 + RWT(I)/32.2*RYCNA(I)
3220 J2 = J2 + ((RXCNA(I)/12)^2+(RYCNA(I)/12)^2)*RWT(I)/32.2
3230 NEXT I
3240 CGS = (CGST1+CGST2)/(WT/32.2)
3250 CGX = (CGXT1+CGXT2)/(WT/32.2)
3260 CGY = (CGYT1+CGYT2)/(WT/32.2)
3270 IF FI = 1 THEN GOTO 4290
3280 CGR = (CGX^2+CGY^2)^.5

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3290 J = J1+J2
3300 REM -----
3310 REM CALCULATE STABILIZING, OVERTURNING AND NET MOMENTS
3320 IF N = 1 THEN GOTO 3340
3330 GOTO 3450
3340 FSP = WT*CSLP*CSSLP*CGX/(SL*COS(SLA))
3350 IF KSP = 0 THEN FSP = 0
3360 FSPL = FSP
3370 GWT = FSP
3380 IF KSP = 0 THEN GOTO 3410
3390 DEFL2 = FSP/KSP
3400 GOTO 3420
3410 DEFL2 = 0
3420 DEFL0 = DEFL2
3430 CSLP = COS(SLP)
3440 SSLP = SIN(SLP)
3450 STM = WT*CSLP*CSSLP*CGX+F(N)*SEA*HXF
3460 OTM = F(N)*CEA*CSWP*H+WT*SSLP*CSSLP*CGY+FSP*SL*COS(SLA)
3470 C = STM-OTM
3480 REM IF HT OF HOP > 0 THEN PRINT HOP HT INSTEAD OF WEIGHT ON GROUND
3490 IF HEI > 0 THEN GOTO 3570
3500 IF KSP = 0 THEN GOTO 3540
3510 REM GWT IS FORCE OF SPRING, DIVIDE BY 2 FOR 2 TRAILS
3520 GWT = GWT/2
3530 GOTO 3550
3540 GWT = (C/12)/(CSLP*CSSLP*SL)*.5
3550 PRINT X1(N),CGX,STM/12,OTM/12,C/12,GWT
3555 IF OUT=1 THEN PRINT #9,X1(N),CGX,STM/12,OTM/12,C/12,GWT
3560 GOTO 3590
3570 PRINT X1(N),CGX,STM/12,OTM/12,C/12,"HOP=";HEI
3575 IF OUT=1 THEN PRINT #9,X1(N),CGX,STM/12,OTM/12,C/12,"HOP=";HEI
3580 REM SET LAST VALUES OF OMEGA AND HOP ANGLE = CURRENT VALUES
3590 W1 = W2
3600 HAL = HA2
3610 REM FIND FIRST APPROXIMATION OF NEW HOP ANGLE
3620 REM I'S AFTER VARIABLE NAMES DENOTE INITIAL CALCULATED VALUES
3630 ALPHI = -(C/12)/J
3640 REM
3650 HAI = HAL+ (.5*ALPHI*(.001)^2+W1*(.001))
3655 WI = ALPHI*(.001)+W1
3660 DXI = SIN(HAI-HAL)*SL*COS(SLA)
3670 DEFLI = DEFL2 - DXI
3680 FSPI = DEFLI*KSP
3690 IF DEFLI > 0 THEN GOTO 3710
3700 FSPI = 0
3710 CSLPI = COS(SLP+HAI)
3720 SSLPI = SIN(SLP+HAI)
3730 REM NOW USE FSPI, CS,SSLPI TO FIND NEW AVG. VALUES FOR WT & FSP
3740 CSLP = (CSLPL+CSLPI)/2
3750 SSLP = (SSLPL+SSLPI)/2
3760 STMI = WT*CSLP*CSSLP*CGX+F(N)*SEA*HXF
3770 OTMI = F(N)*CEA*CSWP*H+WT*SSLP*CSSLP*CGY+FSP*SL*COS(SLA)
3780 C = STMI-OTMI
3790 REM FIND REAL ESTIMATE OF THE NEW POSITION
3800 ALPH = -(C/12)/J
3810 REM
3820 HA2 = HAL+ (.5*ALPH*(.001)^2+W1*(.001))
3825 W2 = ALPH*(.001)+W1
3830 DX = SIN(HA2-HAL)*SL*COS(SLA)
3840 DEFL2 = DEFL2 - DX
3850 IF N > 15 THEN GOTO 3880
3860 REM BDEFL = DEFLECTION (IN) OF BARREL 15 MSEC AFTER FIRING

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3870 BDEFL = SIN(HA2)*BL*COS(SLA)
3880 FSP = DEFL2*KSP
3890 FSPL = FSP
3900 GWT = FSP
3970 HEI = SIN(HA2)*SL-DEFL0
4070 CSLP = COS(SLP+HA2)
4080 CSLPL = CSLP
4090 SSLP = SIN(SLP+HA2)
4100 SSLPL = SSLP
4110 REM IF BACK OF STROKE IS ENCOUNTERED AND ON GROUND, THEN STOP
4120 IF N >= P AND W2 <= 0 THEN GOTO 4210
4130 REM IF BACK OF STROKE IS ENCOUNTERED AND HOPPING, THEN KEEP
4140 REM SYSTEM AT BACK MOST POSITION
4150 IF N > P THEN GOTO 4410
4160 GOTO 4400
4210 PRINT " "
4220 PRINT "INITIAL DEFLECTION (IN) OF TRAILS = ";DEFL0
4225 IF OUT=1 THEN PRINT #9,"INIT. DEFL. (IN) OF TRAILS: ";DEFL0
4230 PRINT " "
4240 GOTO 4430
4250 REM
4260 REM -----
4270 REM CALCULATIONS OF MAX FORCE VALUES, STABILIZING MOMENTS
4280 REM
4290 NUMF = WT*(CSLP*CSSLP*CGX-SSLP*CSSLP*CGY)
4300 MAXF = NUMF/DENF
4310 IF MAXF < 0 THEN MAXF = 999999
4320 IF SWPD = 0 THEN GOTO 4360
4330 NUMS = WT*(CSSLP*CSLP*CGS-SSSLP*CSLP*CGY)
4340 MAXFS = NUMS/DENS
4350 GOTO 4380
4360 MAXFS = 999999
4370 IF MAXFS < 0 THEN MAXFS = 999999
4380 STAMF = WT*CGX*COS(SLP)/12
4390 PRINT X1(N)/12,CGX,MAXF,STAMF,CGS,MAXFS
4395 IF OUT=1 THEN PRINT #9, X1(N)/12,CGX,MAXF,STAMF,CGS,MAXFS
4400 NEXT N
4410 REM IF FI = 2 THEN GOTO 4422
4420 REM GOTO 4445
4422 N = P+1
4423 F(N) = 0
4424 X1(N) = X1(P)
4425 GOTO 3070
4426 REM
4430 PRINT " "
4440 PRINT "DEFLECTION (IN) OF GUN BARREL AFTER 15 MSEC = ";BDEFL
4442 IF OUT=1 THEN PRINT #9,"GUN BARREL DEFL. AFTER 15 MSEC: ";BDEFL
4443 REM
4445 PRINT "HOP HEIGHT VALUES, IF ANY, ARE IN INCHES"
4446 IF OUT=1 THEN PRINT #9,"HOP HT VALUES, IF ANY, ARE IN INCHES"
4460 END

```

STABILITY COMPUTER PROGRAM

PART 3. OUTPUTS

CCCCCCCCC  
CCCCCCCCC  
CCCCCCCCC

32

```

DDDD      AAA      TTTTT      ;;      222
D   D   A   A   T      ;;      2   2
D   D   A   A   T      2
D   D   A   A   T      ;;      2
D   D   AAAAA   T      ;;      2
D   D   A   A   T      ;
DDDD      A   A   T      :      22222

```

CCCCCCCCC  
CCCCCCCCC  
CCCCCCCCC

## A8600 System (VENUS)

Username: M20E96

Password:

Hello...

Last interactive login on Wednesday, 8-APR-1987 13:00

Last non-interactive login on Thursday, 26-MAR-1987 08:57

Last system boot on 5-MAR-1987 22:17:49.02

THE DATE AND TIME IS

8-APR-1987 13:04:12

VENUS&gt; RUN HOP

FIND: 1. MAX. FORCES & MOMENTS  
2. MOMENTS FROM FORCE DATA

(ENTER 1 OR 2):

? 2

FROM: 1. RECOIL.BAS OR 2. RECOIL.FORT

(ENTER 1 OR 2):

? 2

OUTPUT TO FILE? 1-YES 2-NO

? 2

INPUT TRUNNION HEIGHT, IN. (18.5 TO 31.25)

? 18.5

INPUT HORIZ. DIST. FROM TRUNNION TO

POINT OF GROUND CONTACT ON SPADE, IN. (24 TO 14.25)

? 24

INPUT SPRING CONSTANT OF EACH TRAIL (LBS/IN)

? 3000

INPUT TRAVERSE ANGLE OF GUN, DEGREES:

? 0

INPUT ELEVATION ANGLE OF GUN, DEGREES:

? 0

INPUT FORWARD (UPWARD) SLOPE OF HILL, DEGREES:

? 0

INPUT SIDE SLOPE OF HILL, DEGREES:

? 0

INITIAL CONDITIONS:

WEIGHT OF RECOILING COMPONENTS (LB) = 3870.15

WEIGHT OF NON-RECOILING COMPONENTS (LB) = 5029.85

SYSTEM WEIGHT (LB) = 8900

INDIV. TRAIL'S SPRING CONSTANT (LB/IN) = 3000

AT MAXIMUM EXTENSION OF BARREL:

CGZ (IN) = 163.435

CGY (IN) = 18.2265

CGX (IN) = 43.7133

DEFLECTION OF TRAILS (IN) = 1.14267

MASS MOMENT OF INERTIA (FT-LB-S<sup>2</sup>) = 68595.9

SWEEP ANGLE LEFT (DEGREES) = 0

ELEVATION ANGLE (DEGREES) = 0

UPWARD SLOPE OF HILL - FORWARD (DEGREES) = 0

UPWARD SLOPE OF HILL - SIDE (DEGREES) = 0

ENTER INPUT FORCE DATAFILE NAME, E.G., [.OUTPUT]XXX.LIS

? HOP3.DAT

DATA FILE: HOP3.DAT

| STROKE,<br>INCHES | CG -Z,<br>INCHES | STABLE<br>MOMENT,<br>FT-LBS | OVERTURN-<br>ING MOM.,<br>FT-LBS | SAFETY<br>MOMENT<br>FT-LBS | WT. AT<br>EA TRAIL<br>LBS |
|-------------------|------------------|-----------------------------|----------------------------------|----------------------------|---------------------------|
| .012              | 163.43           | 121211                      | 128919                           | -7708.33                   | 3427.9                    |
| .048              | 163.414          | 121199                      | 128919                           | -7720.23                   | 3427.8                    |
| .12               | 163.383          | 121176                      | 128920                           | -7744.28                   | 3427.7                    |
| .276              | 163.315          | 121126                      | 128942                           | -7816.03                   | 3427.5                    |
| .54               | 163.201          | 121040                      | 129024                           | -7983.23                   | 3427.3                    |
| .924              | 163.034          | 120917                      | 129251                           | -8334.56                   | 3427                      |
| 1.428             | 162.814          | 120754                      | 129749                           | -8994.79                   | 3426.6                    |
| 2.052             | 162.543          | 120553                      | 130658                           | -10105.6                   | 3426.1                    |
| 2.772             | 162.23           | 120321                      | 132114                           | -11792.9                   | 3425.5                    |
| 3.552             | 161.891          | 120069                      | 134233                           | -14163.6                   | 3424.8                    |
| 4.404             | 161.52           | 119794                      | 137109                           | -17314.7                   | 3424.0                    |
| 5.304             | 161.129          | 119504                      | 140816                           | -21311.6                   | 3423.1                    |
| 6.24              | 160.722          | 119202                      | 145408                           | -26206.3                   | 3422                      |
| 7.2               | 160.304          | 118892                      | 150870                           | -31977.8                   | 3420.6                    |
| 8.16              | 159.887          | 118583                      | 157155                           | -38572                     | 3419                      |
| 9.132             | 159.464          | 118269                      | 164268                           | -45998.2                   | 3417.0                    |
| 10.104            | 159.042          | 117956                      | 172207                           | -54251.5                   | 3414.6                    |
| 11.088            | 158.614          | 117639                      | 180970                           | -63331.7                   | 3411.7                    |
| 12.06             | 158.191          | 117325                      | 190550                           | -73224.7                   | 3408.2                    |
| 13.044            | 157.763          | 117008                      | 200770                           | -83762.1                   | 3404.1                    |
| 14.016            | 157.341          | 116694                      | 210919                           | -94224.9                   | 3399.2                    |
| 15                | 156.913          | 116377                      | 220184                           | -103808                    | 3393.4                    |
| 15.972            | 156.49           | 116063                      | 227762                           | -111699                    | 3386.6                    |
| 16.944            | 156.067          | 115750                      | 232871                           | -117122                    | 3378.7                    |
| 17.904            | 155.65           | 115440                      | 234761                           | -119321                    | 3369.7                    |
| 18.864            | 155.232          | 115131                      | 234417                           | -119286                    | 3359.4                    |
| 19.824            | 154.815          | 114821                      | 234011                           | -119190                    | 3347.9                    |
| 20.772            | 154.403          | 114515                      | 233562                           | -119047                    | 3335.2                    |
| 21.72             | 153.99           | 114210                      | 233069                           | -118860                    | 3321.3                    |
| 22.656            | 153.583          | 113908                      | 232533                           | -118625                    | 3306.1                    |
| 23.592            | 153.176          | 113606                      | 231952                           | -118346                    | 3289.7                    |
| 24.516            | 152.775          | 113308                      | 231327                           | -118019                    | 3272.0                    |
| 25.44             | 152.373          | 113010                      | 230658                           | -117649                    | 3253.0                    |
| 26.352            | 151.976          | 112716                      | 229945                           | -117229                    | 3232.9                    |
| 27.264            | 151.58           | 112422                      | 229187                           | -116766                    | 3211.4                    |
| 28.164            | 151.188          | 112131                      | 228385                           | -116254                    | 3188.7                    |
| 29.052            | 150.802          | 111845                      | 227539                           | -115694                    | 3164.8                    |
| 29.94             | 150.416          | 111559                      | 226647                           | -115089                    | 3139.6                    |
| 30.828            | 150.03           | 111272                      | 225712                           | -114440                    | 3113.1                    |
| 31.692            | 149.654          | 110993                      | 224732                           | -113738                    | 3085.3                    |
| 32.568            | 149.273          | 110711                      | 223707                           | -112996                    | 3056.3                    |
| 33.42             | 148.903          | 110436                      | 222638                           | -112202                    | 3026.1                    |
| 34.272            | 148.532          | 110161                      | 221525                           | -111364                    | 2994.6                    |
| 35.124            | 148.162          | 109887                      | 220368                           | -110481                    | 2961.8                    |
| 35.964            | 147.796          | 109616                      | 219166                           | -109551                    | 2927.8                    |
| 36.792            | 147.436          | 109349                      | 217921                           | -108572                    | 2892.6                    |
| 37.62             | 147.076          | 109082                      | 216632                           | -107550                    | 2856.1                    |
| 38.436            | 146.722          | 108818                      | 215299                           | -106481                    | 2818.4                    |
| 39.24             | 146.372          | 108559                      | 213916                           | -105357                    | 2779.5                    |
| 40.044            | 146.022          | 108300                      | 212377                           | -104077                    | 2739.3                    |
| 40.836            | 145.678          | 108044                      | 210658                           | -102613                    | 2698.0                    |
| 41.628            | 145.333          | 107789                      | 208773                           | -100984                    | 2655.4                    |
| 42.408            | 144.994          | 107537                      | 206736                           | -99198.2                   | 2611.7                    |
| 43.176            | 144.66           | 107290                      | 204559                           | -97269.8                   | 2566.8                    |
| 43.944            | 144.326          | 107042                      | 202258                           | -95215.8                   | 2520.7                    |
| 44.7              | 143.998          | 106798                      | 199843                           | -93045.3                   | 2473.5                    |

|        |         |         |         |          |         |
|--------|---------|---------|---------|----------|---------|
| 45.456 | 143.669 | 106554  | 197325  | -90770.6 | 2425.2  |
| 46.2   | 143.345 | 106314  | 194718  | -88404.1 | 2375.8  |
| 46.932 | 143.027 | 106078  | 192031  | -85952.8 | 2325.3  |
| 47.664 | 142.709 | 105842  | 189274  | -83432   | 2273.8  |
| 48.396 | 142.39  | 105606  | 186458  | -80852.1 | 2221.2  |
| 49.104 | 142.083 | 105378  | 183592  | -78213.9 | 2167.7  |
| 49.812 | 141.775 | 105149  | 180685  | -75535.4 | 2113.2  |
| 50.52  | 141.467 | 104921  | 177746  | -72825.3 | 2057.7  |
| 51.216 | 141.164 | 104696  | 174783  | -70087   | 2001.3  |
| 51.9   | 140.867 | 104476  | 171803  | -67327.6 | 1944.1  |
| 52.584 | 140.569 | 104255  | 168815  | -64559.8 | 1886.0  |
| 53.256 | 140.277 | 104039  | 165824  | -61785.5 | 1827.1  |
| 53.928 | 139.985 | 103822  | 162839  | -59017.4 | 1767.4  |
| 54.588 | 139.698 | 103609  | 159854  | -56245   | 1707.0  |
| 55.236 | 139.416 | 103400  | 156851  | -53450.9 | 1645.8  |
| 55.884 | 139.134 | 103191  | 153831  | -50640.1 | 1584.0  |
| 56.532 | 138.852 | 102982  | 150797  | -47815.5 | 1521.5  |
| 57.168 | 138.576 | 102777  | 147749  | -44972.6 | 1458.4  |
| 57.804 | 138.299 | 102572  | 144688  | -42116.6 | 1394.6  |
| 58.416 | 138.033 | 102374  | 141615  | -39240.9 | 1330.4  |
| 59.04  | 137.762 | 102173  | 138533  | -36359.9 | 1265.6  |
| 59.652 | 137.496 | 101975  | 135440  | -33464.1 | 1200.3  |
| 60.252 | 137.235 | 101782  | 132340  | -30557.8 | 1134.5  |
| 60.852 | 136.974 | 101588  | 129233  | -27644.6 | 1068.4  |
| 61.452 | 136.713 | 101395  | 126120  | -24725.7 | 1001.9  |
| 62.04  | 136.457 | 101205  | 123002  | -21797.1 | 935.06  |
| 62.616 | 136.207 | 101019  | 119882  | -18863.2 | 867.89  |
| 63.192 | 135.956 | 100833  | 116761  | -15927.5 | 800.46  |
| 63.756 | 135.711 | 100652  | 113638  | -12986.1 | 732.80  |
| 64.32  | 135.466 | 100470  | 110515  | -10045.6 | 664.95  |
| 64.884 | 135.221 | 100288  | 107395  | -7107.45 | HOP= .9 |
| 65.436 | 134.981 | 100110  | 104279  | -4169.15 | HOP= .3 |
| 65.988 | 134.741 | 99931.5 | 101166  | -1234.34 | HOP= .0 |
| 66.528 | 134.506 | 99757.3 | 98059.4 | 1697.9   | HOP= .9 |
| 67.056 | 134.276 | 99587   | 94959.2 | 4627.73  | HOP= .1 |
| 67.584 | 134.047 | 99416.6 | 91869.8 | 7546.79  | HOP= .1 |
| 68.112 | 133.817 | 99246.3 | 88787.9 | 10458.3  | HOP= .1 |
| 68.628 | 133.593 | 99079.8 | 85718   | 13361.8  | HOP= .2 |
| 69.144 | 133.368 | 98913.4 | 82661.6 | 16251.8  | HOP= .2 |
| 69.66  | 133.144 | 98746.9 | 79618.4 | 19128.5  | HOP= .2 |
| 70.164 | 132.925 | 98584.3 | 76589.9 | 21994.4  | HOP= .2 |
| 70.656 | 132.711 | 98425.5 | 73579   | 24846.6  | HOP= .3 |
| 71.148 | 132.497 | 98266.8 | 70585.6 | 27681.2  | HOP= .3 |
| 71.64  | 132.283 | 98108.1 | 67612.7 | 30495.4  | HOP= .3 |
| 72.12  | 132.074 | 97953.2 | 64658.5 | 33294.7  | HOP= .3 |
| 72.6   | 131.865 | 97798.3 | 61727.7 | 36070.7  | HOP= .4 |
| 73.068 | 131.662 | 97647.4 | 58820   | 38827.4  | HOP= .4 |
| 73.536 | 131.458 | 97496.4 | 55936.8 | 41559.6  | HOP= .4 |
| 74.004 | 131.255 | 97345.4 | 53081   | 44264.3  | HOP= .4 |
| 74.46  | 131.057 | 97198.3 | 50251.1 | 46947.1  | HOP= .5 |
| 74.916 | 130.858 | 97051.1 | 47451.4 | 49599.7  | HOP= .5 |
| 75.36  | 130.665 | 96907.9 | 44680.3 | 52227.6  | HOP= .5 |
| 75.804 | 130.472 | 96764.6 | 41942.2 | 54822.4  | HOP= .6 |
| 76.248 | 130.279 | 96621.4 | 39235.3 | 57386.1  | HOP= .6 |
| 76.68  | 130.091 | 96482   | 36562.6 | 59919.3  | HOP= .6 |
| 77.112 | 129.903 | 96342.6 | 33927   | 62415.6  | HOP= .6 |
| 77.532 | 129.721 | 96207.1 | 31326.7 | 64880.4  | HOP= .6 |
| 77.952 | 129.538 | 96071.6 | 28764.5 | 67307    | HOP= .7 |
| 78.372 | 129.355 | 95936   | 26240.3 | 69695.7  | HOP= .7 |
| 78.78  | 129.178 | 95804.4 | 23758.4 | 72046    | HOP= .7 |
| 79.188 | 129.001 | 95672.8 | 21317   | 74355.8  | HOP= .7 |
| 79.584 | 128.828 | 95545   | 18918.9 | 76626.1  | HOP= .8 |

|        |         |         |          |         |         |
|--------|---------|---------|----------|---------|---------|
| 79.98  | 128.656 | 95417.2 | 16565.3  | 78851.9 | HOP- .8 |
| 80.376 | 128.484 | 95289.4 | 14257.5  | 81031.9 | HOP- .8 |
| 80.772 | 128.312 | 95161.7 | 11995.1  | 83166.5 | HOP- .8 |
| 81.156 | 128.145 | 95037.8 | 9779.42  | 85258.4 | HOP- .8 |
| 81.528 | 127.983 | 94917.8 | 7613.05  | 87304.7 | HOP- .9 |
| 81.912 | 127.816 | 94793.9 | 5497.19  | 89296.7 | HOP- .9 |
| 82.284 | 127.654 | 94673.8 | 3432.95  | 91240.9 | HOP- .9 |
| 82.644 | 127.498 | 94557.7 | 1418.38  | 93139.3 | HOP- .9 |
| 83.004 | 127.341 | 94441.5 | -540.813 | 94982.3 | HOP- .9 |
| 83.364 | 127.185 | 94325.4 | -2446.67 | 96772.1 | HOP- 1. |
| 83.724 | 127.028 | 94209.2 | -4298.15 | 98507.4 | HOP- 1. |
| 84.072 | 126.877 | 94096.9 | -6094.22 | 100191  | HOP- 1. |
| 84.42  | 126.725 | 93984.7 | -7832.37 | 101817  | HOP- 1. |
| 84.768 | 126.574 | 93872.4 | -9511.62 | 103384  | HOP- 1. |
| 85.104 | 126.428 | 93764   | -11134.1 | 104898  | HOP- 1. |
| 85.44  | 126.282 | 93655.6 | -12695.9 | 106352  | HOP- 1. |
| 85.764 | 126.141 | 93551.1 | -14196.1 | 107747  | HOP- 1. |
| 86.1   | 125.995 | 93442.7 | -15637   | 109080  | HOP- 1. |
| 86.424 | 125.854 | 93338.1 | -17014.5 | 110353  | HOP- 1. |
| 86.736 | 125.718 | 93237.5 | -18329.5 | 111567  | HOP- 1. |
| 87.048 | 125.583 | 93136.8 | -19581.3 | 112718  | HOP- 1. |
| 87.36  | 125.447 | 93036.2 | -20769   | 113805  | HOP- 1. |
| 87.672 | 125.311 | 92935.5 | -21890.5 | 114826  | HOP- 1. |
| 87.972 | 125.181 | 92838.8 | -22948.2 | 115787  | HOP- 1. |
| 88.272 | 125.05  | 92742   | -23938.4 | 116680  | HOP- 1. |
| 88.572 | 124.92  | 92645.2 | -24862   | 117507  | HOP- 1. |
| 88.872 | 124.789 | 92548.4 | -25718.5 | 118267  | HOP- 1. |
| 89.16  | 124.664 | 92455.6 | -26507.3 | 118963  | HOP- 1. |
| 89.436 | 124.544 | 92366.5 | -27228   | 119595  | HOP- 1. |
| 89.724 | 124.419 | 92273.6 | -27880.1 | 120154  | HOP- 1. |
| 90     | 124.299 | 92184.6 | -28463.2 | 120648  | HOP- 1. |
| 90.276 | 124.179 | 92095.6 | -28978.4 | 121074  | HOP- 1. |
| 90.552 | 124.059 | 92006.6 | -29422.3 | 121429  | HOP- 1. |
| 90.816 | 123.944 | 91921.5 | -29796.2 | 121718  | HOP- 1. |
| 91.08  | 123.829 | 91836.3 | -30099.8 | 121936  | HOP- 1. |
| 91.344 | 123.715 | 91751.2 | -30334.4 | 122086  | HOP- 1. |
| 91.596 | 123.605 | 91669.9 | -30496.7 | 122167  | HOP- 1. |
| 91.848 | 123.495 | 91588.7 | -30589.7 | 122178  | HOP- 1. |
| 92.1   | 123.386 | 91507.4 | -30611.7 | 122119  | HOP- 1. |
| 92.352 | 123.276 | 91426.1 | -30562.6 | 121989  | HOP- 1. |
| 92.592 | 123.172 | 91348.8 | -30442.3 | 121791  | HOP- 1. |
| 92.832 | 123.067 | 91271.4 | -30252.6 | 121524  | HOP- 1. |
| 93.072 | 122.963 | 91194   | -29991.7 | 121186  | HOP- 1. |
| 93.312 | 122.859 | 91116.6 | -29659.8 | 120776  | HOP- 1. |
| 93.54  | 122.76  | 91043.1 | -29257.1 | 120300  | HOP- 1. |
| 93.768 | 122.66  | 90969.6 | -28785.3 | 119755  | HOP- 1. |
| 93.984 | 122.567 | 90900   | -28241.3 | 119141  | HOP- 1. |
| 94.212 | 122.467 | 90826.5 | -27630.2 | 118457  | HOP- 1. |
| 94.428 | 122.373 | 90756.9 | -26947.6 | 117704  | HOP- 1. |
| 94.644 | 122.28  | 90687.2 | -26196.9 | 116884  | HOP- 1. |
| 94.86  | 122.186 | 90617.6 | -25376.8 | 115994  | HOP- 1. |
| 95.064 | 122.097 | 90551.9 | -24489.4 | 115041  | HOP- 1. |
| 95.268 | 122.008 | 90486.1 | -23533.5 | 114020  | HOP- 1. |
| 95.472 | 121.919 | 90420.4 | -22509.6 | 112930  | HOP- 1. |
| 95.664 | 121.836 | 90358.5 | -21419.8 | 111778  | HOP- 1. |
| 95.868 | 121.747 | 90292.8 | -20263   | 110556  | HOP- 1. |
| 96.06  | 121.664 | 90230.9 | -19041.5 | 109272  | HOP- 1. |
| 96.252 | 121.58  | 90169   | -17754.3 | 107923  | HOP- .9 |
| 96.432 | 121.502 | 90111   | -16403.6 | 106515  | HOP- .9 |
| 96.624 | 121.419 | 90049.2 | -14988.5 | 105038  | HOP- .9 |
| 96.804 | 121.34  | 89991.1 | -13511.5 | 103503  | HOP- .9 |
| 96.972 | 121.267 | 89937   | -11971.7 | 101909  | HOP- .9 |

|         |         |         |          |          |         |
|---------|---------|---------|----------|----------|---------|
| 97.152  | 121.189 | 89879   | -10371.4 | 100250   | HOP= .8 |
| 97.32   | 121.116 | 89824.9 | -8710.03 | 98534.9  | HOP= .8 |
| 97.488  | 121.043 | 89770.8 | -6989.98 | 96760.8  | HOP= .8 |
| 97.656  | 120.97  | 89716.7 | -5210.64 | 94927.3  | HOP= .8 |
| 97.824  | 120.897 | 89662.6 | -3374.51 | 93037.1  | HOP= .7 |
| 97.98   | 120.829 | 89612.3 | -1481.06 | 91093.4  | HOP= .7 |
| 98.136  | 120.761 | 89562.1 | 465.612  | 89096.4  | HOP= .7 |
| 98.292  | 120.693 | 89511.8 | 2469.06  | 87042.8  | HOP= .7 |
| 98.448  | 120.625 | 89461.6 | 4523.57  | 84938    | HOP= .6 |
| 98.592  | 120.563 | 89415.2 | 6631.08  | 82784.1  | HOP= .6 |
| 98.736  | 120.5   | 89368.8 | 8790.45  | 80578.4  | HOP= .6 |
| 98.88   | 120.438 | 89322.4 | 10997.4  | 78325.1  | HOP= .6 |
| 99.024  | 120.375 | 89276.1 | 13253.7  | 76022.3  | HOP= .5 |
| 99.156  | 120.317 | 89233.6 | 15558.3  | 73675.3  | HOP= .5 |
| 99.3    | 120.255 | 89187.2 | 17906.6  | 71280.6  | HOP= .5 |
| 99.432  | 120.197 | 89144.7 | 20300.6  | 68844.1  | HOP= .5 |
| 99.552  | 120.145 | 89106   | 22738.8  | 66367.3  | HOP= .4 |
| 99.684  | 120.088 | 89063.5 | 25216.8  | 63846.7  | HOP= .4 |
| 99.804  | 120.036 | 89024.9 | 27736.3  | 61288.6  | HOP= .4 |
| 99.924  | 119.984 | 88986.3 | 30294.3  | 58691.9  | HOP= .3 |
| 100.044 | 119.931 | 88947.6 | 32891    | 56056.6  | HOP= .3 |
| 100.164 | 119.879 | 88909   | 35521.8  | 53387.2  | HOP= .3 |
| 100.272 | 119.832 | 88874.2 | 38188.3  | 50685.9  | HOP= .2 |
| 100.38  | 119.785 | 88839.4 | 40887.4  | 47952    | HOP= .2 |
| 100.488 | 119.738 | 88804.7 | 43619.2  | 45185.5  | HOP= .2 |
| 100.596 | 119.691 | 88769.9 | 46379    | 42390.9  | HOP= .1 |
| 100.704 | 119.644 | 88735.1 | 49168.3  | 39566.8  | HOP= .1 |
| 100.8   | 119.603 | 88704.2 | 51984.1  | 36720.1  | HOP= .1 |
| 100.896 | 119.561 | 88673.3 | 54824.7  | 33848.6  | HOP= .8 |
| 100.992 | 119.519 | 88642.4 | 57690    | 30952.4  | HOP= .0 |
| 101.088 | 119.477 | 88611.5 | 60575.3  | 28036.2  | HOP= .1 |
| 101.172 | 119.441 | 88584.5 | 63482.1  | 25102.3  | 673.59  |
| 101.256 | 119.404 | 88557.4 | 66407.2  | 22150.3  | 759.50  |
| 101.34  | 119.368 | 88530.4 | 69348.8  | 19181.6  | 845.79  |
| 101.424 | 119.331 | 88503.3 | 72306.8  | 16196.5  | 932.42  |
| 101.508 | 119.295 | 88476.3 | 75276.5  | 13199.8  | 1019.3  |
| 101.58  | 119.263 | 88453.1 | 78259.3  | 10193.9  | 1106.4  |
| 101.652 | 119.232 | 88429.9 | 81250.2  | 7179.73  | 1193.8  |
| 101.724 | 119.201 | 88406.8 | 84250.8  | 4155.98  | 1281.3  |
| 101.796 | 119.169 | 88383.6 | 87257.6  | 1125.93  | 1368.8  |
| 101.856 | 119.143 | 88364.3 | 90269.1  | -1904.88 | 1456.5  |
| 101.916 | 119.117 | 88345   | 93285    | -4940.06 | 1544.1  |
| 101.976 | 119.091 | 88325.6 | 96300.5  | -7974.83 | 1631.6  |

INITIAL DEFLECTION (IN) OF TRAILS = 1.14263

DEFLECTION (IN) OF GUN BARREL AFTER 15 MSEC = .363865E-02

HOP HEIGHT VALUES, IF ANY, ARE IN INCHES

VENUS> LO

M20E96

logged out at 8-APR-1987 13:05:21.37



DDDDDDDDDD  
DDDDDDDDDD  
DDDDDDDDDD

38

```

DDDD      AAA      TTTTT      ;;      222
D   D   A   A   T      ;;      2   2
D   D   A   A   T      2
D   D   A   A   T      ;;      2
D   D   AAAAA   T      ;;      2
D   D   A   A   T      ;
DDDD      A   A   T      :      22222

```

DDDDDDDDDD  
DDDDDDDDDD  
DDDDDDDDDD

## A8600 System (VENUS)

Username: M20E96

Password:

Hello...

Last interactive login on Wednesday, 8-APR-1987 13:04

Last non-interactive login on Thursday, 26-MAR-1987 08:57

Last system boot on 5-MAR-1987 22:17:49.02

VENUS&gt;

VENUS&gt; RUN HOP

FIND: 1. MAX. FORCES &amp; MOMENTS

2. MOMENTS FROM FORCE DATA

(ENTER 1 OR 2):

? 2

FROM: 1. RECOIL.BAS OR 2. RECOIL.FORT

(ENTER 1 OR 2):

? 2

OUTPUT TO FILE? 1-YES 2-NO

? 2

INPUT TRUNNION HEIGHT, IN. (18.5 TO 31.25)

? 18.5

INPUT HORIZ. DIST. FROM TRUNNION TO

POINT OF GROUND CONTACT ON SPADE, IN. (24 TO 14.25)

? 24

INPUT SPRING CONSTANT OF EACH TRAIL (LBS/IN)

? 3000

INPUT TRAVERSE ANGLE OF GUN, DEGREES:

? 0

INPUT ELEVATION ANGLE OF GUN, DEGREES:

? 0

INPUT FORWARD (UPWARD) SLOPE OF HILL, DEGREES:

? 0

INPUT SIDE SLOPE OF HILL, DEGREES:

? 0

INITIAL CONDITIONS:

WEIGHT OF RECOILING COMPONENTS (LB) = 3870.15

WEIGHT OF NON-RECOILING COMPONENTS (LB) = 5029.85

SYSTEM WEIGHT (LB) = 8900

INDIV. TRAIL'S SPRING CONSTANT (LB/IN) = 3000

AT MAXIMUM EXTENSION OF BARREL:

CGZ (IN) = 163.435

CGY (IN) = 18.2265

CGX (IN) = 43.7133

DEFLECTION OF TRAILS (IN) = 1.14267

MASS MOMENT OF INERTIA (FT-LB-S<sup>2</sup>) = 68595.9

SWEEP ANGLE LEFT (DEGREES)

= 0

ELEVATION ANGLE (DEGREES)

= 0

UPWARD SLOPE OF HILL - FORWARD (DEGREES)

= 0

UPWARD SLOPE OF HILL - SIDE

(DEGREES) = 0

ENTER INPUT FORCE DATAFILE NAME, E.G., [.OUTPUT]XXX.LIS

? HOP3.BAT

DATA FILE: HOP3.BAT

STROKE,

CG -Z,

STABLE

OVERTURN-

SAFETY

WT. AT

| INCHES | INCHES  | MOMENT,<br>FT-LBS | ING MOM.,<br>FT-LBS | MOMENT<br>FT-LBS | EA TRAI<br>LBS |
|--------|---------|-------------------|---------------------|------------------|----------------|
| 36.012 | 147.776 | 109600            | 138852              | -29251.6         | 3099.5         |
| 36.036 | 147.765 | 109593            | 139167              | -29574.1         | 3099.3         |
| 36.12  | 147.729 | 109565            | 140430              | -30864.7         | 3098.8         |
| 36.276 | 147.661 | 109515            | 144094              | -34579.2         | 3098.0         |
| 36.528 | 147.551 | 109434            | 151957              | -42523.3         | 3096.8         |
| 36.9   | 147.389 | 109314            | 164556              | -55242.1         | 3095.1         |
| 37.404 | 147.17  | 109151            | 180827              | -71676.2         | 3092.9         |
| 38.004 | 146.909 | 108958            | 197277              | -88319.1         | 3090.0         |
| 38.7   | 146.607 | 108733            | 213319              | -104586          | 3086.2         |
| 39.468 | 146.273 | 108486            | 227467              | -118981          | 3081.2         |
| 40.296 | 145.913 | 108219            | 239057              | -130839          | 3075.0         |
| 41.148 | 145.542 | 107944            | 247408              | -139465          | 3067.3         |
| 42.048 | 145.151 | 107654            | 234313              | -126660          | 3058.1         |
| 42.948 | 144.759 | 107363            | 233947              | -126584          | 3047.3         |
| 43.848 | 144.368 | 107073            | 233528              | -126455          | 3035.0         |
| 44.76  | 143.972 | 106779            | 233057              | -126278          | 3021.2         |
| 45.66  | 143.58  | 106489            | 232532              | -126044          | 3005.9         |
| 46.572 | 143.184 | 106195            | 231955              | -125760          | 2989.1         |
| 47.472 | 142.792 | 105904            | 231324              | -125420          | 2970.9         |
| 48.372 | 142.401 | 105614            | 230640              | -125026          | 2951.1         |
| 49.26  | 142.015 | 105328            | 229902              | -124575          | 2929.7         |
| 50.148 | 141.629 | 105041            | 229111              | -124070          | 2906.9         |
| 51.036 | 141.242 | 104755            | 228266              | -123511          | 2882.6         |
| 51.924 | 140.856 | 104468            | 227367              | -122899          | 2856.7         |
| 52.8   | 140.475 | 104186            | 226415              | -122229          | 2829.3         |
| 53.676 | 140.094 | 103903            | 225409              | -121505          | 2800.4         |
| 54.54  | 139.719 | 103625            | 224349              | -120724          | 2770.0         |
| 55.404 | 139.343 | 103346            | 223234              | -119888          | 2738.0         |
| 56.256 | 138.972 | 103071            | 222068              | -118996          | 2704.6         |
| 57.108 | 138.602 | 102796            | 220847              | -118051          | 2669.6         |
| 57.948 | 138.237 | 102526            | 219573              | -117047          | 2633.2         |
| 58.788 | 137.871 | 102255            | 218246              | -115992          | 2595.2         |
| 59.616 | 137.511 | 101988            | 216866              | -114878          | 2555.7         |
| 60.444 | 137.151 | 101721            | 215433              | -113712          | 2514.8         |
| 61.26  | 136.797 | 101457            | 213949              | -112492          | 2472.4         |
| 62.064 | 136.447 | 101198            | 212412              | -111214          | 2428.5         |
| 62.868 | 136.097 | 100939            | 210823              | -109884          | 2383.1         |
| 63.66  | 135.753 | 100683            | 209183              | -108500          | 2336.3         |
| 64.452 | 135.408 | 100428            | 207492              | -107064          | 2288.1         |
| 65.232 | 135.069 | 100176            | 205751              | -105575          | 2238.4         |
| 66     | 134.735 | 99928.6           | 203960              | -104031          | 2187.4         |
| 66.768 | 134.401 | 99680.9           | 202118              | -102437          | 2134.9         |
| 67.524 | 134.073 | 99437.1           | 200228              | -100791          | 2081.0         |
| 68.28  | 133.744 | 99193.3           | 198291              | -99097.4         | 2025.8         |
| 69.024 | 133.42  | 98953.3           | 196304              | -97350.4         | 1969.2         |
| 69.756 | 133.102 | 98717.2           | 194271              | -95553.9         | 1911.3         |
| 70.488 | 132.784 | 98481.1           | 192191              | -93709.5         | 1852.1         |
| 71.208 | 132.471 | 98248.9           | 190064              | -91815.5         | 1791.6         |
| 71.928 | 132.158 | 98016.6           | 187893              | -89876.5         | 1729.8         |
| 72.624 | 131.855 | 97792.2           | 185678              | -87885.5         | 1666.7         |
| 73.332 | 131.547 | 97563.8           | 183419              | -85854.9         | 1602.5         |
| 74.016 | 131.25  | 97343.1           | 181117              | -83774           | 1537.0         |
| 74.7   | 130.952 | 97122.5           | 178774              | -81651.2         | 1470.3         |
| 75.372 | 130.66  | 96905.8           | 176389              | -79483.6         | 1402.5         |
| 76.044 | 130.368 | 96689             | 173965              | -77276.1         | 1333.6         |
| 76.704 | 130.081 | 96476.1           | 171500              | -75024           | 1263.5         |
| 77.352 | 129.799 | 96267.1           | 168999              | -72731.6         | 1192.4         |
| 78     | 129.517 | 96058.1           | 166459              | -70400.6         | 1120.2         |
| 78.636 | 129.241 | 95852.9           | 163884              | -68031.1         | 1047.0         |

|         |         |         |          |          |         |
|---------|---------|---------|----------|----------|---------|
| 79.26   | 128.969 | 95651.7 | 161273   | -65621.3 | 972.83  |
| 79.884  | 128.698 | 95450.4 | 158628   | -63177.6 | 897.68  |
| 80.496  | 128.432 | 95253   | 155950   | -60697.2 | 821.60  |
| 81.096  | 128.171 | 95059.4 | 153241   | -58181.3 | 744.62  |
| 81.696  | 127.91  | 94865.9 | 150501   | -55635.1 | 666.79  |
| 82.284  | 127.654 | 94676.2 | 147732   | -53055.6 | 588.12  |
| 82.86   | 127.404 | 94490.4 | 144935   | -50444.3 | HOP- .2 |
| 83.436  | 127.153 | 94304.6 | 142109   | -47804.7 | HOP- .5 |
| 84      | 126.908 | 94122.6 | 139260   | -45137.3 | HOP- .0 |
| 84.552  | 126.668 | 93944.5 | 136385   | -42440.2 | HOP- .1 |
| 85.104  | 126.428 | 93766.4 | 133488   | -39721.9 | HOP- .1 |
| 85.644  | 126.193 | 93592.2 | 130569   | -36976.6 | HOP- .1 |
| 86.172  | 125.964 | 93421.9 | 127629   | -34207.3 | HOP- .2 |
| 86.7    | 125.734 | 93251.5 | 124671   | -31419.3 | HOP- .2 |
| 87.216  | 125.51  | 93085.1 | 121695   | -28610.1 | HOP- .2 |
| 87.732  | 125.285 | 92918.6 | 118704   | -25785   | HOP- .3 |
| 88.224  | 125.071 | 92759.9 | 115698   | -22937.7 | HOP- .3 |
| 88.728  | 124.852 | 92597.2 | 112679   | -20081.3 | HOP- .3 |
| 89.208  | 124.643 | 92442.4 | 109648   | -17205.7 | HOP- .4 |
| 89.688  | 124.435 | 92287.5 | 106606   | -14318.5 | HOP- .4 |
| 90.156  | 124.231 | 92136.5 | 103557   | -11420.6 | HOP- .4 |
| 90.612  | 124.033 | 91989.3 | 100500   | -8510.32 | HOP- .5 |
| 91.068  | 123.835 | 91842.2 | 97436.9  | -5594.67 | HOP- .5 |
| 91.512  | 123.641 | 91698.9 | 94371.8  | -2672.92 | HOP- .6 |
| 91.956  | 123.448 | 91555.7 | 91303    | 252.656  | HOP- .6 |
| 92.376  | 123.266 | 91420.1 | 88233.5  | 3186.6   | HOP- .6 |
| 92.808  | 123.078 | 91280.7 | 85165    | 6115.74  | HOP- .7 |
| 93.216  | 122.9   | 91149.1 | 82099    | 9050.08  | HOP- .7 |
| 93.624  | 122.723 | 91017.4 | 79035.6  | 11981.8  | HOP- .7 |
| 94.02   | 122.551 | 90889.6 | 75979.5  | 14910.1  | HOP- .8 |
| 94.404  | 122.384 | 90765.7 | 72930.8  | 17834.9  | HOP- .8 |
| 94.788  | 122.217 | 90641.7 | 69889.5  | 20752.2  | HOP- .8 |
| 95.16   | 122.055 | 90521.7 | 66858.9  | 23662.7  | HOP- .9 |
| 95.532  | 121.893 | 90401.6 | 63842.1  | 26559.5  | HOP- .9 |
| 95.892  | 121.737 | 90285.4 | 60837.7  | 29447.7  | HOP- .9 |
| 96.24   | 121.585 | 90173.1 | 57848.8  | 32324.2  | HOP- 1. |
| 96.576  | 121.439 | 90064.6 | 54877.1  | 35187.5  | HOP- 1. |
| 96.912  | 121.293 | 89956.2 | 51924.2  | 38031.9  | HOP- 1. |
| 97.236  | 121.152 | 89851.6 | 48991.8  | 40859.8  | HOP- 1. |
| 97.56   | 121.012 | 89747   | 46081.3  | 43665.7  | HOP- 1. |
| 97.86   | 120.881 | 89650.1 | 43193    | 46457.1  | HOP- 1. |
| 98.172  | 120.745 | 89549.4 | 40331.5  | 49217.9  | HOP- 1. |
| 98.46   | 120.62  | 89456.4 | 37495.3  | 51961.1  | HOP- 1. |
| 98.748  | 120.495 | 89363.5 | 34689.1  | 54674.3  | HOP- 1. |
| 99.024  | 120.375 | 89274.3 | 31911.4  | 57362.9  | HOP- 1. |
| 99.288  | 120.26  | 89189.1 | 29165.4  | 60023.8  | HOP- 1. |
| 99.552  | 120.145 | 89103.9 | 26452.4  | 62651.4  | HOP- 1. |
| 99.804  | 120.036 | 89022.5 | 23774.2  | 65248.3  | HOP- 1. |
| 100.056 | 119.926 | 88941.1 | 21132.2  | 67808.9  | HOP- 1. |
| 100.296 | 119.822 | 88863.6 | 18527.9  | 70335.7  | HOP- 1. |
| 100.524 | 119.723 | 88790   | 15962.9  | 72827.1  | HOP- 1. |
| 100.74  | 119.629 | 88720.3 | 13437.1  | 75283.2  | HOP- 1. |
| 100.956 | 119.535 | 88650.5 | 10954.9  | 77695.6  | HOP- 1. |
| 101.16  | 119.446 | 88584.6 | 8514.79  | 80069.8  | HOP- 1. |
| 101.364 | 119.357 | 88518.7 | 6121.23  | 82397.5  | HOP- 1. |
| 101.544 | 119.279 | 88460.6 | 3772.52  | 84688.1  | HOP- 1. |
| 101.736 | 119.196 | 88398.6 | 1471.61  | 86926.9  | HOP- 1. |
| 101.904 | 119.123 | 88344.3 | -780.198 | 89124.5  | HOP- 1. |
| 102.072 | 119.049 | 88290   | -2981.6  | 91271.6  | HOP- 1. |
| 102.228 | 118.982 | 88239.6 | -5131.27 | 93370.9  | HOP- 1. |
| 102.372 | 118.919 | 88193.1 | -7227.98 | 95421.1  | HOP- 1. |
| 102.516 | 118.856 | 88146.6 | -9272.04 | 97418.6  | HOP- 1. |

|         |         |         |          |        |         |
|---------|---------|---------|----------|--------|---------|
| 102.648 | 118.799 | 88103.9 | -11259.1 | 99363  | HOP- 1. |
| 102.78  | 118.742 | 88061.3 | -13191.2 | 101252 | HOP- 1. |
| 102.9   | 118.689 | 88022.5 | -15063.9 | 103086 | HOP- 1. |
| 103.008 | 118.642 | 87987.6 | -16879.4 | 104867 | HOP- 1. |
| 103.104 | 118.601 | 87956.5 | -18635   | 106592 | HOP- 1. |
| 103.2   | 118.559 | 87925.5 | -20329.6 | 108255 | HOP- 1. |
| 103.284 | 118.522 | 87898.3 | -21962.3 | 109861 | HOP- 1. |
| 103.356 | 118.491 | 87875   | -23532   | 111407 | HOP- 1. |
| 103.428 | 118.46  | 87851.7 | -25037.9 | 112890 | HOP- 1. |
| 103.488 | 118.434 | 87832.3 | -26479   | 114311 | HOP- 1. |
| 103.548 | 118.408 | 87812.9 | -27856   | 115669 | HOP- 2. |
| 103.596 | 118.387 | 87797.4 | -29165   | 116962 | HOP- 2. |
| 103.632 | 118.371 | 87785.7 | -30408.3 | 118194 | HOP- 2. |
| 103.656 | 118.361 | 87777.9 | -31582.1 | 119360 | HOP- 2. |
| 103.68  | 118.35  | 87770.1 | -32688.8 | 120459 | HOP- 2. |
| 103.692 | 118.345 | 87766.2 | -33726.1 | 121492 | HOP- 2. |
| 103.692 | 118.345 | 87766.2 | -161963  | 249729 | HOP- 2. |
| 103.692 | 118.345 | 87766.1 | -162823  | 250589 | HOP- 2. |
| 103.692 | 118.345 | 87766.1 | -163538  | 251304 | HOP- 2. |
| 103.692 | 118.345 | 87766.1 | -164108  | 251874 | HOP- 2. |
| 103.692 | 118.345 | 87766   | -164533  | 252299 | HOP- 2. |
| 103.692 | 118.345 | 87766   | -164811  | 252578 | HOP- 2. |
| 103.692 | 118.345 | 87766   | -164944  | 252710 | HOP- 2. |

INITIAL DEFLECTION (IN) OF TRAILS - 1.03318

DEFLECTION (IN) OF GUN BARREL AFTER 15 MSEC - .026204

HOP HEIGHT VALUES, IF ANY, ARE IN INCHES

VENUS> LO

M20E96

logged out at 8-APR-1987 13:06:53.62

EEEEEEEEEEEE  
EEEEEEEEEEEE  
EEEEEEEEEEEE

EEEEEEEEEE  
EEEEEEEEEE  
EEEEEEEEEE

A8600 System (VENUS)

44

Username: M20E96

Password:

Hello...

Last interactive login on Wednesday, 8-APR-1987 13:06

Last non-interactive login on Thursday, 26-MAR-1987 08:57

Last system boot on 5-MAR-1987 22:17:49.02

THE DATE AND TIME IS

8-APR-1987 13:07:23

VENUS> RUN HOP

FIND: 1. MAX. FORCES & MOMENTS

2. MOMENTS FROM FORCE DATA

(ENTER 1 OR 2):

? 2

FROM: 1. RECOIL.BAS OR 2. RECOIL.FORT

(ENTER 1 OR 2):

? 2

OUTPUT TO FILE? 1-YES 2-NO

? 2

INPUT TRUNNION HEIGHT, IN. (18.5 TO 31.25)

? 31.25

INPUT HORIZ. DIST. FROM TRUNNION TO

POINT OF GROUND CONTACT ON SPADE, IN. (24 TO 14.25)

? 14.25

INPUT SPRING CONSTANT OF EACH TRAIL (LBS/IN)

? 3000

INPUT TRAVERSE ANGLE OF GUN, DEGREES:

? 0

INPUT ELEVATION ANGLE OF GUN, DEGREES:

? 0

INPUT FORWARD (UPWARD) SLOPE OF HILL, DEGREES:

? 0

INPUT SIDE SLOPE OF HILL, DEGREES:

? 0

INITIAL CONDITIONS:

WEIGHT OF RECOILING COMPONENTS (LB) = 3870.15

WEIGHT OF NON-RECOILING COMPONENTS (LB) = 5029.85

SYSTEM WEIGHT (LB) = 8900

INDIV. TRAIL'S SPRING CONSTANT (LB/IN) = 3000

AT MAXIMUM EXTENSION OF BARREL:

CGZ (IN) = 153.685

CGY (IN) = 30.9765

CGX (IN) = 43.7133

DEFLECTION OF TRAILS (IN) = 1.0745

MASS MOMENT OF INERTIA (FT-LB-S<sup>2</sup>) = 63865.3

SWEEP ANGLE LEFT (DEGREES)

= 0

ELEVATION ANGLE (DEGREES)

= 0

UPWARD SLOPE OF HILL - FORWARD (DEGREES)

= 0

UPWARD SLOPE OF HILL - SIDE

(DEGREES) = 0

ENTER INPUT FORCE DATAFILE NAME, E.G., [.OUTPUT]XXX.LIS

? HOP3.DAT

DATA FILE: HOP3.DAT

| STROKE,<br>INCHES | CG -Z,<br>INCHES | STABLE<br>MOMENT,<br>FT-LBS | OVERTURN-<br>ING MOM.,<br>FT-LBS | SAFETY<br>MOMENT<br>FT-LBS | WT. AT<br>EA TRAIL<br>LBS |
|-------------------|------------------|-----------------------------|----------------------------------|----------------------------|---------------------------|
| .012              | 153.68           | 113979                      | 127000                           | -13020.8                   | 3223.3                    |
| .048              | 153.665          | 113968                      | 127001                           | -13032.8                   | 3223.3                    |
| .12               | 153.633          | 113945                      | 127002                           | -13056.9                   | 3223.1                    |
| .276              | 153.565          | 113894                      | 127037                           | -13142.6                   | 3222.8                    |
| .54               | 153.451          | 113809                      | 127175                           | -13365.3                   | 3222.3                    |
| .924              | 153.284          | 113685                      | 127557                           | -13872.1                   | 3221.7                    |
| 1.428             | 153.064          | 113523                      | 128396                           | -14873.6                   | 3221.0                    |
| 2.052             | 152.793          | 113322                      | 129931                           | -16609.3                   | 3220.1                    |
| 2.772             | 152.48           | 113089                      | 132387                           | -19297.4                   | 3219.1                    |
| 3.552             | 152.141          | 112838                      | 135964                           | -23126.1                   | 3217.9                    |
| 4.404             | 151.77           | 112563                      | 140820                           | -28256.8                   | 3216.5                    |
| 5.304             | 151.379          | 112273                      | 147078                           | -34805.3                   | 3214.8                    |
| 6.24              | 150.972          | 111971                      | 154833                           | -42861.7                   | 3212.8                    |
| 7.2               | 150.554          | 111661                      | 164055                           | -52393.6                   | 3210.4                    |
| 8.16              | 150.137          | 111352                      | 174666                           | -63314.3                   | 3207.5                    |
| 9.132             | 149.714          | 111038                      | 186675                           | -75636.8                   | 3204.0                    |
| 10.104            | 149.292          | 110725                      | 200080                           | -89355.6                   | 3199.7                    |
| 11.088            | 148.864          | 110407                      | 214874                           | -104467                    | 3194.6                    |
| 12.06             | 148.441          | 110094                      | 231046                           | -120952                    | 3188.5                    |
| 13.044            | 148.013          | 109776                      | 248298                           | -138521                    | 3181.2                    |
| 14.016            | 147.591          | 109463                      | 265427                           | -155964                    | 3172.5                    |
| 15                | 147.163          | 109146                      | 281061                           | -171916                    | 3162.2                    |
| 15.972            | 146.74           | 108832                      | 293841                           | -185009                    | 3150.1                    |
| 16.944            | 146.317          | 108519                      | 302448                           | -193929                    | 3136.1                    |
| 17.904            | 145.9            | 108209                      | 305611                           | -197402                    | 3120.0                    |
| 18.864            | 145.482          | 107899                      | 304999                           | -197099                    | 3101.8                    |
| 19.824            | 145.065          | 107590                      | 304278                           | -196688                    | 3081.4                    |
| 20.772            | 144.653          | 107284                      | 303480                           | -196195                    | 3058.8                    |
| 21.72             | 144.24           | 106978                      | 302604                           | -195625                    | 3034.0                    |
| 22.656            | 143.833          | 106676                      | 301650                           | -194974                    | 3007.0                    |
| 23.592            | 143.426          | 106375                      | 300619                           | -194244                    | 2977.8                    |
| 24.516            | 143.025          | 106077                      | 299509                           | -193433                    | 2946.4                    |
| 25.44             | 142.623          | 105779                      | 298322                           | -192543                    | 2912.8                    |
| 26.352            | 142.226          | 105484                      | 297056                           | -191572                    | 2877                      |
| 27.264            | 141.83           | 105190                      | 295712                           | -190522                    | 2838.9                    |
| 28.164            | 141.438          | 104900                      | 294290                           | -189390                    | 2798.6                    |
| 29.052            | 141.052          | 104614                      | 292789                           | -188176                    | 2756.2                    |
| 29.94             | 140.666          | 104327                      | 291211                           | -186883                    | 2711.5                    |
| 30.828            | 140.28           | 104041                      | 289554                           | -185513                    | 2664.6                    |
| 31.692            | 139.904          | 103762                      | 287820                           | -184057                    | 2615.5                    |
| 32.568            | 139.523          | 103480                      | 286008                           | -182528                    | 2564.2                    |
| 33.42             | 139.153          | 103205                      | 284118                           | -180913                    | 2510.7                    |
| 34.272            | 138.782          | 102930                      | 282152                           | -179222                    | 2455.0                    |
| 35.124            | 138.412          | 102655                      | 280109                           | -177453                    | 2397.2                    |
| 35.964            | 138.046          | 102384                      | 277989                           | -175605                    | 2337.2                    |
| 36.792            | 137.686          | 102117                      | 275793                           | -173676                    | 2275.0                    |
| 37.62             | 137.326          | 101850                      | 273522                           | -171672                    | 2210.7                    |
| 38.436            | 136.972          | 101587                      | 271176                           | -169589                    | 2144.3                    |
| 39.24             | 136.622          | 101328                      | 268743                           | -167415                    | 2075.8                    |
| 40.044            | 136.272          | 101068                      | 266045                           | -164976                    | 2005.2                    |
| 40.836            | 135.928          | 100813                      | 263042                           | -162229                    | 1932.5                    |
| 41.628            | 135.583          | 100558                      | 259759                           | -159201                    | 1857.7                    |
| 42.408            | 135.244          | 100306                      | 256217                           | -155911                    | 1781.0                    |
| 43.176            | 134.91           | 100058                      | 252440                           | -152382                    | 1702.2                    |
| 43.944            | 134.576          | 99810.5                     | 248451                           | -148640                    | 1621.5                    |
| 44.7              | 134.248          | 99566.6                     | 244272                           | -144705                    | 1538.9                    |
| 45.456            | 133.919          | 99322.8                     | 239917                           | -140594                    | 1454.4                    |



|        |         |         |          |          |         |
|--------|---------|---------|----------|----------|---------|
| 46.2   | 133.595 | 99082.8 | 235413   | -136331  | 1368.0  |
| 46.932 | 133.277 | 98846.7 | 230774   | -131927  | 1279.9  |
| 47.664 | 132.959 | 98610.6 | 226019   | -127408  | 1190.0  |
| 48.396 | 132.64  | 98374.4 | 221165   | -122790  | 1098.5  |
| 49.104 | 132.333 | 98146.1 | 216227   | -118081  | 1005.3  |
| 49.812 | 132.025 | 97917.7 | 211222   | -113305  | 910.52  |
| 50.52  | 131.717 | 97689.3 | 206167   | -108477  | 814.21  |
| 51.216 | 131.414 | 97464.8 | 201072   | -103608  | 716.43  |
| 51.9   | 131.117 | 97244.1 | 195951   | -98707.4 | 617.25  |
| 52.584 | 130.819 | 97023.4 | 190819   | -93796   | HOP- .2 |
| 53.256 | 130.527 | 96806.6 | 185686   | -88879.5 | HOP- .0 |
| 53.928 | 130.235 | 96589.8 | 180567   | -83976.9 | HOP- .1 |
| 54.588 | 129.948 | 96376.9 | 175450   | -79073.4 | HOP- .1 |
| 55.236 | 129.666 | 96167.8 | 170308   | -74140.2 | HOP- .1 |
| 55.884 | 129.384 | 95958.8 | 165142   | -69183.1 | HOP- .2 |
| 56.532 | 129.103 | 95749.7 | 159957   | -64207   | HOP- .2 |
| 57.168 | 128.826 | 95544.5 | 154752   | -59207.9 | HOP- .3 |
| 57.804 | 128.549 | 95339.3 | 149531   | -54191.8 | HOP- .3 |
| 58.416 | 128.283 | 95141.8 | 144295   | -49153.3 | HOP- .4 |
| 59.04  | 128.012 | 94940.5 | 139050   | -44109.1 | HOP- .4 |
| 59.652 | 127.746 | 94743   | 133792   | -39048.5 | HOP- .5 |
| 60.252 | 127.485 | 94549.4 | 128529   | -33979.2 | HOP- .5 |
| 60.852 | 127.224 | 94355.8 | 123261   | -28904.9 | HOP- .5 |
| 61.452 | 126.963 | 94162.2 | 117990   | -23827.9 | HOP- .6 |
| 62.04  | 126.707 | 93972.5 | 112717   | -18744.5 | HOP- .6 |
| 62.616 | 126.457 | 93786.6 | 107449   | -13662.1 | HOP- .7 |
| 63.192 | 126.206 | 93600.7 | 102185   | -8584.67 | HOP- .7 |
| 63.756 | 125.961 | 93418.7 | 96926.9  | -3508.18 | HOP- .8 |
| 64.32  | 125.716 | 93236.7 | 91678.3  | 1558.33  | HOP- .8 |
| 64.884 | 125.471 | 93054.6 | 86442.3  | 6612.34  | HOP- .9 |
| 65.436 | 125.231 | 92876.5 | 81221.4  | 11655.1  | HOP- .9 |
| 65.988 | 124.991 | 92698.3 | 76015.6  | 16682.8  | HOP- 1. |
| 66.528 | 124.756 | 92524.1 | 70830    | 21694.1  | HOP- 1. |
| 67.056 | 124.526 | 92353.6 | 65664.6  | 26689    | HOP- 1. |
| 67.584 | 124.297 | 92183.2 | 60527.3  | 31655.9  | HOP- 1. |
| 68.112 | 124.067 | 92012.8 | 55412.9  | 36599.9  | HOP- 1. |
| 68.628 | 123.843 | 91846.2 | 50329.1  | 41517.1  | HOP- 1. |
| 69.144 | 123.618 | 91679.7 | 45278.6  | 46401.1  | HOP- 1. |
| 69.66  | 123.394 | 91513.1 | 40261.4  | 51251.8  | HOP- 1. |
| 70.164 | 123.175 | 91350.4 | 35280    | 56070.4  | HOP- 1. |
| 70.656 | 122.961 | 91191.6 | 30339.7  | 60851.9  | HOP- 1. |
| 71.148 | 122.747 | 91032.8 | 25440.5  | 65592.3  | HOP- 1. |
| 71.64  | 122.533 | 90874   | 20587.6  | 70286.4  | HOP- 1. |
| 72.12  | 122.324 | 90719   | 15778.2  | 74940.8  | HOP- 1. |
| 72.6   | 122.115 | 90564.1 | 11020.3  | 79543.8  | HOP- 1. |
| 73.068 | 121.912 | 90413   | 6313.75  | 84099.3  | HOP- 1. |
| 73.536 | 121.708 | 90261.9 | 1661.09  | 88600.8  | HOP- 1. |
| 74.004 | 121.505 | 90110.8 | -2932.55 | 93043.4  | HOP- 1. |
| 74.46  | 121.307 | 89963.6 | -7469.85 | 97433.5  | HOP- 1. |
| 74.916 | 121.108 | 89816.4 | -11943.1 | 101760   | HOP- 1. |
| 75.36  | 120.915 | 89673.1 | -16355.1 | 106028   | HOP- 1. |
| 75.804 | 120.722 | 89529.7 | -20698.2 | 110228   | HOP- 1. |
| 76.248 | 120.529 | 89386.4 | -24975.1 | 114361   | HOP- 1. |
| 76.68  | 120.341 | 89246.9 | -29180.8 | 118428   | HOP- 1. |
| 77.112 | 120.153 | 89107.5 | -33310.4 | 122418   | HOP- 1. |
| 77.532 | 119.971 | 88971.9 | -37366.7 | 126339   | HOP- 2. |
| 77.952 | 119.788 | 88836.3 | -41344.9 | 130181   | HOP- 2. |
| 78.372 | 119.605 | 88700.7 | -45245.2 | 133946   | HOP- 2. |
| 78.78  | 119.428 | 88569   | -49060.2 | 137629   | HOP- 2. |
| 79.188 | 119.251 | 88437.2 | -52792.9 | 141230   | HOP- 2. |
| 79.584 | 119.078 | 88309.4 | -56438.5 | 144748   | HOP- 2. |
| 79.98  | 118.906 | 88181.6 | -59995   | 148177   | HOP- 2. |

|        |         |         |          |        |         |
|--------|---------|---------|----------|--------|---------|
| 80.376 | 118.734 | 88053.7 | -63460.1 | 151514 | HOP- 2. |
| 80.772 | 118.562 | 87925.9 | -66834.5 | 154760 | HOP- 2. |
| 81.156 | 118.395 | 87801.9 | -70116.1 | 157918 | HOP- 2. |
| 81.528 | 118.233 | 87681.9 | -73300.4 | 160982 | HOP- 2. |
| 81.912 | 118.066 | 87557.9 | -76385.5 | 163943 | HOP- 2. |
| 82.284 | 117.904 | 87437.8 | -79369.5 | 166807 | HOP- 2. |
| 82.644 | 117.748 | 87321.6 | -82255.8 | 169577 | HOP- 2. |
| 83.004 | 117.591 | 87205.4 | -85034.9 | 172240 | HOP- 2. |
| 83.364 | 117.435 | 87089.2 | -87710.1 | 174799 | HOP- 2. |
| 83.724 | 117.278 | 86973   | -90280   | 177253 | HOP- 2. |
| 84.072 | 117.127 | 86860.7 | -92742.7 | 179603 | HOP- 2. |
| 84.42  | 116.975 | 86748.4 | -95094.3 | 181843 | HOP- 2. |
| 84.768 | 116.824 | 86636.1 | -97333.2 | 183969 | HOP- 2. |
| 85.104 | 116.678 | 86527.7 | -99463.2 | 185991 | HOP- 2. |
| 85.44  | 116.532 | 86419.3 | -101478  | 187897 | HOP- 2. |
| 85.764 | 116.391 | 86314.7 | -103375  | 189690 | HOP- 2. |
| 86.1   | 116.245 | 86206.3 | -105160  | 191367 | HOP- 2. |
| 86.424 | 116.104 | 86101.8 | -106826  | 192928 | HOP- 2. |
| 86.736 | 115.968 | 86001.1 | -108374  | 194375 | HOP- 2. |
| 87.048 | 115.833 | 85900.4 | -109803  | 195704 | HOP- 2. |
| 87.36  | 115.697 | 85799.8 | -111113  | 196912 | HOP- 2. |
| 87.672 | 115.561 | 85699.2 | -112299  | 197998 | HOP- 2. |
| 87.972 | 115.431 | 85602.4 | -113366  | 198968 | HOP- 2. |
| 88.272 | 115.3   | 85505.6 | -114308  | 199814 | HOP- 2. |
| 88.572 | 115.17  | 85408.9 | -115127  | 200536 | HOP- 2. |
| 88.872 | 115.039 | 85312.1 | -115823  | 201135 | HOP- 2. |
| 89.16  | 114.914 | 85219.3 | -116394  | 201613 | HOP- 2. |
| 89.436 | 114.794 | 85130.3 | -116840  | 201971 | HOP- 2. |
| 89.724 | 114.669 | 85037.4 | -117162  | 202199 | HOP- 2. |
| 90     | 114.549 | 84948.4 | -117358  | 202306 | HOP- 2. |
| 90.276 | 114.429 | 84859.5 | -117430  | 202290 | HOP- 2. |
| 90.552 | 114.309 | 84770.5 | -117374  | 202145 | HOP- 2. |
| 90.816 | 114.194 | 84685.4 | -117192  | 201878 | HOP- 2. |
| 91.08  | 114.079 | 84600.3 | -116884  | 201484 | HOP- 2. |
| 91.344 | 113.965 | 84515.2 | -116452  | 200967 | HOP- 2. |
| 91.596 | 113.855 | 84434   | -115892  | 200326 | HOP- 2. |
| 91.848 | 113.745 | 84352.8 | -115208  | 199561 | HOP- 2. |
| 92.1   | 113.636 | 84271.6 | -114399  | 198671 | HOP- 2. |
| 92.352 | 113.526 | 84190.4 | -113464  | 197655 | HOP- 2. |
| 92.592 | 113.422 | 84113.1 | -112405  | 196518 | HOP- 2. |
| 92.832 | 113.317 | 84035.8 | -111224  | 195260 | HOP- 2. |
| 93.072 | 113.213 | 83958.5 | -109919  | 193877 | HOP- 2. |
| 93.312 | 113.109 | 83881.2 | -108491  | 192372 | HOP- 2. |
| 93.54  | 113.01  | 83807.8 | -106940  | 190748 | HOP- 2. |
| 93.768 | 112.91  | 83734.4 | -105270  | 189004 | HOP- 2. |
| 93.984 | 112.817 | 83664.8 | -103477  | 187142 | HOP- 2. |
| 94.212 | 112.717 | 83591.4 | -101569  | 185160 | HOP- 2. |
| 94.428 | 112.623 | 83521.9 | -99539.6 | 183061 | HOP- 2. |
| 94.644 | 112.53  | 83452.4 | -97395   | 180847 | HOP- 2. |
| 94.86  | 112.436 | 83382.8 | -95133.8 | 178517 | HOP- 2. |
| 95.064 | 112.347 | 83317.2 | -92759.8 | 176077 | HOP- 2. |
| 95.268 | 112.258 | 83251.5 | -90271.8 | 173523 | HOP- 2. |
| 95.472 | 112.169 | 83185.9 | -87671   | 170857 | HOP- 2. |
| 95.664 | 112.086 | 83124.1 | -84961.6 | 168086 | HOP- 2. |
| 95.868 | 111.997 | 83058.5 | -82142.5 | 165201 | HOP- 2. |
| 96.06  | 111.914 | 82996.7 | -79217.9 | 162215 | HOP- 2. |
| 96.252 | 111.83  | 82934.9 | -76186.9 | 159122 | HOP- 2. |
| 96.432 | 111.752 | 82877   | -73053.7 | 155931 | HOP- 1. |
| 96.624 | 111.669 | 82815.3 | -69817.6 | 152633 | HOP- 1. |
| 96.804 | 111.59  | 82757.4 | -66483.1 | 149240 | HOP- 1. |
| 96.972 | 111.517 | 82703.4 | -63049.4 | 145753 | HOP- 1. |
| 97.152 | 111.439 | 82645.5 | -59521.2 | 142167 | HOP- 1. |

|         |         |         |          |          |         |
|---------|---------|---------|----------|----------|---------|
| 97.32   | 111.366 | 82591.5 | -55898   | 138489   | HOP= 1. |
| 97.488  | 111.293 | 82537.4 | -52184.4 | 134722   | HOP= 1. |
| 97.656  | 111.22  | 82483.4 | -48380.1 | 130864   | HOP= 1. |
| 97.824  | 111.147 | 82429.4 | -44489.9 | 126919   | HOP= 1. |
| 97.98   | 111.079 | 82379.3 | -40513.5 | 122893   | HOP= 1. |
| 98.136  | 111.011 | 82329.1 | -36458.4 | 118788   | HOP= 1. |
| 98.292  | 110.943 | 82279   | -32319.4 | 114598   | HOP= 1. |
| 98.448  | 110.875 | 82228.8 | -28106.5 | 110335   | HOP= 1. |
| 98.592  | 110.813 | 82182.5 | -23817.3 | 106000   | HOP= 1. |
| 98.736  | 110.75  | 82136.3 | -19454.1 | 101590   | HOP= 1. |
| 98.88   | 110.688 | 82090   | -15024.9 | 97114.9  | HOP= 1. |
| 99.024  | 110.625 | 82043.7 | -10527.2 | 92570.9  | HOP= 1. |
| 99.156  | 110.568 | 82001.3 | -5963.55 | 87964.8  | HOP= 1. |
| 99.3    | 110.505 | 81955   | -1342.05 | 83297    | HOP= 1. |
| 99.432  | 110.447 | 81912.6 | 3339.78  | 78572.8  | HOP= 1. |
| 99.552  | 110.395 | 81874   | 8079.05  | 73795    | HOP= .9 |
| 99.684  | 110.338 | 81831.6 | 12867.7  | 68963.9  | HOP= .8 |
| 99.804  | 110.286 | 81793   | 17708    | 64085    | HOP= .8 |
| 99.924  | 110.234 | 81754.5 | 22594.4  | 59160.1  | HOP= .7 |
| 100.044 | 110.181 | 81715.9 | 27526.4  | 54189.5  | HOP= .7 |
| 100.164 | 110.129 | 81677.3 | 32496    | 49181.3  | HOP= .6 |
| 100.272 | 110.082 | 81642.6 | 37505.2  | 44137.4  | HOP= .5 |
| 100.38  | 110.035 | 81607.9 | 42548.4  | 39059.5  | HOP= .5 |
| 100.488 | 109.988 | 81573.2 | 47625    | 33948.2  | HOP= .4 |
| 100.596 | 109.941 | 81538.5 | 52726.8  | 28811.7  | HOP= .4 |
| 100.704 | 109.894 | 81503.8 | 57855.7  | 23648.1  | HOP= .3 |
| 100.8   | 109.853 | 81472.9 | 63006    | 18466.9  | HOP= .2 |
| 100.896 | 109.811 | 81442   | 68174.5  | 13267.5  | HOP= .2 |
| 100.992 | 109.769 | 81411.2 | 73360.7  | 8050.46  | HOP= .1 |
| 101.088 | 109.727 | 81380.3 | 78556.1  | 2824.23  | HOP= .1 |
| 101.172 | 109.691 | 81353.3 | 83762.6  | -2409.32 | HOP= .4 |
| 101.256 | 109.654 | 81326.3 | 88974.5  | -7648.22 | 626.9   |
| 101.34  | 109.618 | 81299.3 | 94188.5  | -12889.2 | 779.66  |
| 101.424 | 109.581 | 81272.3 | 99403.9  | -18131.7 | 932.25  |
| 101.508 | 109.545 | 81245.2 | 104612   | -23367.1 | 1084.5  |
| 101.58  | 109.513 | 81222.1 | 109816   | -28593.7 | 1236.5  |
| 101.652 | 109.482 | 81198.9 | 115006   | -33806.7 | 1388    |
| 101.724 | 109.451 | 81175.7 | 120184   | -39008.1 | 1538.9  |
| 101.796 | 109.42  | 81152.6 | 125345   | -44192.2 | 1689.2  |
| 101.856 | 109.393 | 81133.3 | 130485   | -49351.8 | 1838.8  |
| 101.916 | 109.367 | 81114   | 135604   | -54490.2 | 1987.5  |
| 101.976 | 109.341 | 81094.6 | 140694   | -59598.9 | 2135.4  |

INITIAL DEFLECTION (IN) OF TRAILS = 1.07446

DEFLECTION (IN) OF GUN BARREL AFTER 15 MSEC = .648644E-02

HOP HEIGHT VALUES, IF ANY, ARE IN INCHES

VENUS> LO

M20E96

logged out at 8-APR-1987 13:08:08.04

FFFFFFFFFF  
FFFFFFFFFF  
FFFFFFFFFF

49

|    |      |       |       |    |       |
|----|------|-------|-------|----|-------|
|    | DDDD | AAA   | TTTTT | ;; | 222   |
|    | D D  | A A   | T     | ;; | 2 2   |
|    | D D  | A A   | T     |    | 2     |
|    | D D  | A A   | T     | ;; | 2     |
|    | D D  | AAAAA | T     | ;; | 2     |
| .. | D D  | A A   | T     | ;  | 2     |
| .. | DDDD | A A   | T     | :  | 22222 |

Job HOPRUN1 (1349) queued to LN on 8-APR-1987 13:17 by user M20E96, UIC [M20,DACKO SG], under account M22 at priority 100, started on printer VENUS\$TXM6: on 8-APR-1987 13:18 from queue LNSYS.

FFFFFFFFFF  
FFFFFFFFFF  
FFFFFFFFFF

A8600 System (VENUS)

Username: M20E96

Password:

Hello...

Last interactive login on Wednesday, 8-APR-1987 13:08

Last non-interactive login on Thursday, 26-MAR-1987 08:57

Last system boot on 5-MAR-1987 22:17:49.02

THE DATE AND TIME IS

8-APR-1987 13:09:07

VENUS> RUN HOP

FIND: 1. MAX. FORCES & MOMENTS

2. MOMENTS FROM FORCE DATA

(ENTER 1 OR 2):

? 2

FROM: 1. RECOIL.BAS OR 2. RECOIL.FORT

(ENTER 1 OR 2):

? 2

OUTPUT TO FILE? 1-YES 2-NO

? 2

INPUT TRUNNION HEIGHT, IN. (18.5 TO 31.25)

? 31.25

INPUT HORIZ. DIST. FROM TRUNNION TO

POINT OF GROUND CONTACT ON SPADE, IN. (24 TO 14.25)

? 14.25

INPUT SPRING CONSTANT OF EACH TRAIL (LBS/IN)

? 3000

INPUT TRAVERSE ANGLE OF GUN, DEGREES:

? 0

INPUT ELEVATION ANGLE OF GUN, DEGREES:

? 0

INPUT FORWARD (UPWARD) SLOPE OF HILL, DEGREES:

? 0

INPUT SIDE SLOPE OF HILL, DEGREES:

? 0

INITIAL CONDITIONS:

WEIGHT OF RECOILING COMPONENTS (LB) = 3870.15

WEIGHT OF NON-RECOILING COMPONENTS (LB) = 5029.85

SYSTEM WEIGHT (LB) = 8900

INDIV. TRAIL'S SPRING CONSTANT (LB/IN) = 3000

AT MAXIMUM EXTENSION OF BARREL:

CGZ (IN) = 153.685

CGY (IN) = 30.9765

CGX (IN) = 43.7133

DEFLECTION OF TRAILS (IN) = 1.0745

MASS MOMENT OF INERTIA (FT-LB-S<sup>2</sup>) = 63865.3

SWEEP ANGLE LEFT (DEGREES) = 0

ELEVATION ANGLE (DEGREES) = 0

UPWARD SLOPE OF HILL - FORWARD (DEGREES) = 0

UPWARD SLOPE OF HILL - SIDE (DEGREES) = 0

ENTER INPUT FORCE DATAFILE NAME, E.G., [.OUTPUT]XXX.LIS

? HOP3.BAT

DATA FILE: HOP3.BAT

| STROKE,<br>INCHES | CG -Z,<br>INCHES | STABLE<br>MOMENT,<br>FT-LBS | OVERTURN-<br>ING MOM.,<br>FT-LBS | SAFETY<br>MOMENT<br>FT-LBS | WT. AT<br>EA TRAI<br>LBS |
|-------------------|------------------|-----------------------------|----------------------------------|----------------------------|--------------------------|
| 36.012            | 138.026          | 102369                      | 151780                           | -49411.5                   | 2895.0                   |
| 36.036            | 138.015          | 102361                      | 152311                           | -49950.2                   | 2894.7                   |
| 36.12             | 137.979          | 102334                      | 154443                           | -52109.3                   | 2893.8                   |
| 36.276            | 137.911          | 102284                      | 160629                           | -58345                     | 2892.3                   |
| 36.528            | 137.801          | 102203                      | 173905                           | -71702.5                   | 2890.0                   |
| 36.9              | 137.639          | 102083                      | 195179                           | -93096.6                   | 2887.0                   |
| 37.404            | 137.42           | 101920                      | 222655                           | -120734                    | 2883.0                   |
| 38.004            | 137.159          | 101727                      | 250427                           | -148701                    | 2877.7                   |
| 38.7              | 136.857          | 101502                      | 277508                           | -176006                    | 2870.7                   |
| 39.468            | 136.523          | 101254                      | 301383                           | -200129                    | 2861.7                   |
| 40.296            | 136.163          | 100987                      | 320933                           | -219946                    | 2850.4                   |
| 41.148            | 135.792          | 100713                      | 335005                           | -234292                    | 2836.4                   |
| 42.048            | 135.401          | 100422                      | 312843                           | -212421                    | 2819.6                   |
| 42.948            | 135.009          | 100132                      | 312176                           | -212044                    | 2800                     |
| 43.848            | 134.618          | 99841.8                     | 311413                           | -211572                    | 2777.6                   |
| 44.76             | 134.222          | 99547.7                     | 310556                           | -211008                    | 2752.6                   |
| 45.66             | 133.83           | 99257.4                     | 309602                           | -210345                    | 2724.9                   |
| 46.572            | 133.434          | 98963.3                     | 308553                           | -209590                    | 2694.5                   |
| 47.472            | 133.042          | 98673                       | 307408                           | -208735                    | 2661.3                   |
| 48.372            | 132.651          | 98382.7                     | 306167                           | -207784                    | 2625.4                   |
| 49.26             | 132.265          | 98096.3                     | 304829                           | -206733                    | 2586.8                   |
| 50.148            | 131.879          | 97809.9                     | 303396                           | -205586                    | 2545.5                   |
| 51.036            | 131.492          | 97523.5                     | 301866                           | -204342                    | 2501.5                   |
| 51.924            | 131.106          | 97237.2                     | 300240                           | -203003                    | 2454.7                   |
| 52.8              | 130.725          | 96954.6                     | 298518                           | -201564                    | 2405.2                   |
| 53.676            | 130.344          | 96672.1                     | 296701                           | -200028                    | 2353.0                   |
| 54.54             | 129.969          | 96393.4                     | 294787                           | -198394                    | 2298.1                   |
| 55.404            | 129.593          | 96114.8                     | 292776                           | -196661                    | 2240.5                   |
| 56.256            | 129.223          | 95840                       | 290673                           | -194833                    | 2180.2                   |
| 57.108            | 128.852          | 95565.2                     | 288475                           | -192909                    | 2117.3                   |
| 57.948            | 128.487          | 95294.3                     | 286180                           | -190886                    | 2051.6                   |
| 58.788            | 128.121          | 95023.4                     | 283794                           | -188771                    | 1983.4                   |
| 59.616            | 127.761          | 94756.3                     | 281313                           | -186557                    | 1912.5                   |
| 60.444            | 127.401          | 94489.2                     | 278739                           | -184250                    | 1838.9                   |
| 61.26             | 127.047          | 94226                       | 276076                           | -181850                    | 1762.8                   |
| 62.064            | 126.697          | 93966.7                     | 273320                           | -179353                    | 1684.1                   |
| 62.868            | 126.347          | 93707.4                     | 270474                           | -176766                    | 1602.9                   |
| 63.66             | 126.003          | 93451.9                     | 267538                           | -174086                    | 1519.1                   |
| 64.452            | 125.659          | 93196.5                     | 264514                           | -171317                    | 1432.8                   |
| 65.232            | 125.319          | 92944.9                     | 261402                           | -168457                    | 1344.1                   |
| 66                | 124.985          | 92697.2                     | 258204                           | -165507                    | 1252.9                   |
| 66.768            | 124.651          | 92449.4                     | 254919                           | -162469                    | 1159.3                   |
| 67.524            | 124.323          | 92205.6                     | 251551                           | -159346                    | 1063.3                   |
| 68.28             | 123.994          | 91961.7                     | 248101                           | -156140                    | 965.00                   |
| 69.024            | 123.67           | 91721.7                     | 244567                           | -152845                    | 864.37                   |
| 69.756            | 123.352          | 91485.6                     | 240955                           | -149470                    | 761.45                   |
| 70.488            | 123.034          | 91249.5                     | 237262                           | -146013                    | 656.31                   |
| 71.208            | 122.721          | 91017.2                     | 233492                           | -142475                    | 548.98                   |
| 71.928            | 122.408          | 90784.9                     | 229645                           | -138860                    | HOP= .3                  |
| 72.624            | 122.105          | 90560.4                     | 225725                           | -135164                    | HOP= .7                  |
| 73.332            | 121.797          | 90332                       | 221732                           | -131400                    | HOP= .1                  |
| 74.016            | 121.5            | 90111.3                     | 217668                           | -127556                    | HOP= .1                  |
| 74.7              | 121.202          | 89890.7                     | 213535                           | -123644                    | HOP= .2                  |
| 75.372            | 120.91           | 89673.9                     | 209334                           | -119660                    | HOP= .2                  |
| 76.044            | 120.618          | 89457.1                     | 205068                           | -115611                    | HOP= .3                  |
| 76.704            | 120.331          | 89244.1                     | 200736                           | -111492                    | HOP= .3                  |
| 77.352            | 120.049          | 89035                       | 196345                           | -107310                    | HOP= .4                  |

|         |         |         |          |          |         |
|---------|---------|---------|----------|----------|---------|
| 78      | 119.767 | 88826   | 191892   | -103066  | HOP= .4 |
| 78.636  | 119.491 | 88620.8 | 187384   | -98763.5 | HOP= .5 |
| 79.26   | 119.219 | 88419.4 | 182819   | -94399.1 | HOP= .5 |
| 79.884  | 118.948 | 88218   | 178200   | -89981.6 | HOP= .6 |
| 80.496  | 118.682 | 88020.6 | 173530   | -85509.4 | HOP= .6 |
| 81.096  | 118.421 | 87826.9 | 168812   | -80984.8 | HOP= .7 |
| 81.696  | 118.16  | 87633.3 | 164047   | -76413.9 | HOP= .7 |
| 82.284  | 117.904 | 87443.5 | 159239   | -71795.3 | HOP= .8 |
| 82.86   | 117.654 | 87257.6 | 154389   | -67131.5 | HOP= .9 |
| 83.436  | 117.403 | 87071.7 | 149498   | -62426.1 | HOP= .9 |
| 84      | 117.158 | 86889.7 | 144573   | -57683   | HOP= 1. |
| 84.552  | 116.918 | 86711.5 | 139611   | -52899.5 | HOP= 1. |
| 85.104  | 116.678 | 86533.4 | 134621   | -48087.4 | HOP= 1. |
| 85.644  | 116.443 | 86359   | 129599   | -43240.1 | HOP= 1. |
| 86.172  | 116.214 | 86188.6 | 124552   | -38362.9 | HOP= 1. |
| 86.7    | 115.984 | 86018.1 | 119481   | -33462.5 | HOP= 1. |
| 87.216  | 115.76  | 85851.6 | 114389   | -28537.6 | HOP= 1. |
| 87.732  | 115.535 | 85685   | 109280   | -23595   | HOP= 1. |
| 88.224  | 115.321 | 85526.1 | 104156   | -18629.6 | HOP= 1. |
| 88.728  | 115.102 | 85363.4 | 99019.2  | -13655.8 | HOP= 1. |
| 89.208  | 114.893 | 85208.4 | 93873.4  | -8665.05 | HOP= 1. |
| 89.688  | 114.685 | 85053.4 | 88718.6  | -3665.16 | HOP= 1. |
| 90.156  | 114.481 | 84902.3 | 83562.7  | 1339.6   | HOP= 1. |
| 90.612  | 114.283 | 84755   | 78403.6  | 6351.47  | HOP= 1. |
| 91.068  | 114.085 | 84607.8 | 73246.7  | 11361.1  | HOP= 1. |
| 91.512  | 113.891 | 84464.4 | 68097.6  | 16366.8  | HOP= 1. |
| 91.956  | 113.698 | 84321   | 62954    | 21366.9  | HOP= 1. |
| 92.376  | 113.516 | 84185.3 | 57821.6  | 26363.7  | HOP= 2. |
| 92.808  | 113.328 | 84045.7 | 52703.2  | 31342.5  | HOP= 2. |
| 93.216  | 113.151 | 83913.9 | 47602    | 36312    | HOP= 2. |
| 93.624  | 112.973 | 83782.1 | 42518.2  | 41264    | HOP= 2. |
| 94.02   | 112.801 | 83654.2 | 37460    | 46194.2  | HOP= 2. |
| 94.404  | 112.634 | 83530.1 | 32428    | 51102.2  | HOP= 2. |
| 94.788  | 112.467 | 83406.1 | 27422.3  | 55983.8  | HOP= 2. |
| 95.16   | 112.305 | 83285.9 | 22448.7  | 60837.2  | HOP= 2. |
| 95.532  | 112.143 | 83165.6 | 17512.7  | 65653    | HOP= 2. |
| 95.892  | 111.987 | 83049.3 | 12612    | 70437.3  | HOP= 2. |
| 96.24   | 111.836 | 82936.8 | 7752.38  | 75184.5  | HOP= 2. |
| 96.576  | 111.689 | 82828.2 | 2936.56  | 79891.7  | HOP= 2. |
| 96.912  | 111.543 | 82719.6 | -1832.35 | 84552    | HOP= 2. |
| 97.236  | 111.402 | 82614.9 | -6551.58 | 89166.5  | HOP= 2. |
| 97.56   | 111.262 | 82510.2 | -11218.2 | 93728.3  | HOP= 2. |
| 97.86   | 111.131 | 82413.2 | -15831.8 | 98245    | HOP= 2. |
| 98.172  | 110.995 | 82312.3 | -20384.5 | 102697   | HOP= 2. |
| 98.46   | 110.87  | 82219.2 | -24878.6 | 107098   | HOP= 2. |
| 98.748  | 110.745 | 82126.1 | -29306.1 | 111432   | HOP= 3. |
| 99.024  | 110.625 | 82036.8 | -33669.4 | 115706   | HOP= 3. |
| 99.288  | 110.51  | 81951.4 | -37963.3 | 119915   | HOP= 3. |
| 99.552  | 110.395 | 81866.1 | -42185   | 124051   | HOP= 3. |
| 99.804  | 110.286 | 81784.6 | -46331.9 | 128116   | HOP= 3. |
| 100.056 | 110.176 | 81703.1 | -50401.2 | 132104   | HOP= 3. |
| 100.296 | 110.072 | 81625.4 | -54390.6 | 136016   | HOP= 3. |
| 100.524 | 109.973 | 81551.7 | -58297.4 | 139849   | HOP= 3. |
| 100.74  | 109.879 | 81481.8 | -62121.7 | 143603   | HOP= 3. |
| 100.956 | 109.785 | 81411.9 | -65855.9 | 147268   | HOP= 3. |
| 101.16  | 109.696 | 81345.9 | -69502.8 | 150849   | HOP= 3. |
| 101.364 | 109.607 | 81279.9 | -73054.8 | 154335   | HOP= 3. |
| 101.544 | 109.529 | 81221.6 | -76515   | 157737   | HOP= 3. |
| 101.736 | 109.446 | 81159.5 | -79878.4 | 161038   | HOP= 3. |
| 101.904 | 109.373 | 81105.1 | -83142.9 | 164248   | HOP= 3. |
| 102.072 | 109.299 | 81050.7 | -86306.3 | 167357   | HOP= 3. |
| 102.228 | 109.232 | 81000.2 | -89366.7 | 170367   | HOP= 3. |

|         |         |         |          |        |         |
|---------|---------|---------|----------|--------|---------|
| 102.372 | 109.169 | 80953.6 | -92322   | 173276 | HOP- 3. |
| 102.516 | 109.106 | 80907   | -95172.9 | 176080 | HOP- 3. |
| 102.648 | 109.049 | 80864.2 | -97912.2 | 178776 | HOP- 3. |
| 102.78  | 108.992 | 80821.5 | -100544  | 181365 | HOP- 3. |
| 102.9   | 108.939 | 80782.6 | -103060  | 183843 | HOP- 3. |
| 103.008 | 108.892 | 80747.6 | -105465  | 186213 | HOP- 3. |
| 103.104 | 108.851 | 80716.5 | -107754  | 188471 | HOP- 3. |
| 103.2   | 108.809 | 80685.4 | -109926  | 190612 | HOP- 3. |
| 103.284 | 108.772 | 80658.2 | -111980  | 192638 | HOP- 3. |
| 103.356 | 108.741 | 80634.9 | -113914  | 194549 | HOP- 4. |
| 103.428 | 108.71  | 80611.5 | -115726  | 196338 | HOP- 4. |
| 103.488 | 108.684 | 80592   | -117416  | 198008 | HOP- 4. |
| 103.548 | 108.658 | 80572.6 | -118986  | 199558 | HOP- 4. |
| 103.596 | 108.637 | 80557   | -120428  | 200985 | HOP- 4. |
| 103.632 | 108.621 | 80545.3 | -121747  | 202292 | HOP- 4. |
| 103.656 | 108.611 | 80537.5 | -122937  | 203474 | HOP- 4. |
| 103.68  | 108.6   | 80529.7 | -124002  | 204532 | HOP- 4. |
| 103.692 | 108.595 | 80525.7 | -124940  | 205466 | HOP- 4. |
| 103.692 | 108.595 | 80525.7 | -340730  | 421256 | HOP- 4. |
| 103.692 | 108.595 | 80525.6 | -341343  | 421868 | HOP- 4. |
| 103.692 | 108.595 | 80525.6 | -341691  | 422216 | HOP- 4. |

INITIAL DEFLECTION (IN) OF TRAILS = .965015

DEFLECTION (IN) OF GUN BARREL AFTER 15 MSEC = .476448E-01  
HOP HEIGHT VALUES, IF ANY, ARE IN INCHES

VENUS> LO

M20E96

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**PART 4 : 7500 LB. LTHD  
FIRING STABILITY ANALYSIS**

B. Dacko - 3/10/86

7500 pound LTHD

ANALYSIS NOT DONE  
UNDER CONTRACT

Tow weight: 7500 lbs  
Fire weight: 6900 lbs  
Recoil comp. wt: 3030 lbs

Breech and auto primer wt reduced by 92.5 lbs, from 820 to 727.5 lbs.  
Cannon wt reduced by 1488.5 lbs, from 2506 to 1017.5 lbs.  
Previous recoil comp. wt was 4611 lbs.

Worst-case zone 8 is over max allowable recoil force by 25% over stroke length.

Worst-case zone 7 is under max allowable recoil force by 29% over stroke length.

With a zone 7 and M483 projectile, the range is roughly 14,540 meters, or 59.9% of the range (24,250 meters) provided by a 9000 lb LTHD.

1. 80716

| <u>F</u> | <u>Dist.</u> |
|----------|--------------|
|          | .02          |
| 50,911   | .546         |
| 47,946   | 1.03         |
| 43,217   | 2            |
| 37,789   | 3            |
| 25,916   | 5            |
| 18,774   | 6            |

Stroke = 6.70 ft

F<sub>max</sub> exceeded by 5.1%

INITIAL CONDITIONS:

WEIGHT OF RECOILING COMPONENTS (LB) = 3030  
 WEIGHT OF NON-RECOILING COMPONENTS (LB) = 3870  
 SYSTEM WEIGHT (LB) = 6900  
 INDIV. TRAIL'S SPRING CONSTANT (LB/IN) = 0  
 PLAY IN END OF TRAILS (IN) = 0

AT MAXIMUM EXTENSION OF BARREL:

CGZ (IN) = 173.139  
 CGY (IN) = 27.4492  
 CGX (IN) = 43.4391  
 DEFLECTION OF TRAILS (IN) = 0  
 MASS MOMENT OF INERTIA (FT-LB-SEC<sup>2</sup>) = 57754.4

SWEEP ANGLE LEFT (DEGREES) = 0  
 ELEVATION ANGLE (DEGREES) = 0  
 UPWARD SLOPE OF HILL - FORWARD (DEGREES) = 0  
 UPWARD SLOPE OF HILL - SIDE (DEGREES) = 0

| STROKE,<br>MAX FORCE<br>FEET<br>LBS, W/O | CG-Z,<br>INCHES | MAX FORCE<br>LBS, W/O<br>BACKW MDP | STA MOM<br>FT-LBS | CG X,<br>INCHES |
|------------------------------------------|-----------------|------------------------------------|-------------------|-----------------|
| -----                                    | -----           | -----                              | -----             | -----           |
| 0<br>999999                              | 173.139         | 49777.3                            | 99554.7           | 43.4391         |
| .25<br>999999                            | 171.821         | 49398.6                            | 98797.2           | 43.4391         |
| .5<br>999999                             | 170.504         | 49019.8                            | 98039.7           | 43.4391         |
| .75<br>999999                            | 169.186         | 48641.1                            | 97282.2           | 43.4391         |
| 1<br>999999                              | 167.869         | 48262.3                            | 96524.7           | 43.4391         |
| 1.25<br>999999                           | 166.552         | 47883.6                            | 95767.2           | 43.4391         |
| 1.5<br>999999                            | 165.234         | 47504.8                            | 95009.7           | 43.4391         |
| 1.75<br>999999                           | 163.917         | 47126.1                            | 94252.2           | 43.4391         |
| 2<br>999999                              | 162.599         | 46747.3                            | 93494.7           | 43.4391         |
| 2.25<br>999999                           | 161.282         | 46368.6                            | 92737.2           | 43.4391         |
| 2.5<br>999999                            | 159.965         | 45989.8                            | 91979.7           | 43.4391         |
| 2.75<br>999999                           | 158.647         | 45611.1                            | 91222.2           | 43.4391         |
| 3<br>999999                              | 157.33          | 45232.3                            | 90464.7           | 43.4391         |
| 3.25<br>999999                           | 156.013         | 44853.6                            | 89707.2           | 43.4391         |
| 3.5<br>999999                            | 154.695         | 44474.8                            | 88949.7           | 43.4391         |
| 3.75<br>999999                           | 153.378         | 44096.1                            | 88192.2           | 43.4391         |
| 4                                        | 152.06          | 43717.3                            | 87434.7           | 43.4391         |

|        |         |         |         |         |
|--------|---------|---------|---------|---------|
| 999999 |         |         |         |         |
| 4.25   | 150.743 | 43338.5 | 56677.2 | 43.4391 |
| 999999 |         |         |         |         |
| 4.5    | 149.426 | 42959.5 | 65419.7 | 43.4391 |
| 999999 |         |         |         |         |
| 4.75   | 148.108 | 42581.1 | 85162.2 | 43.4391 |
| 999999 |         |         |         |         |
| 5      | 146.791 | 42202.3 | 64404.7 | 43.4391 |
| 999999 |         |         |         |         |
| 5.25   | 145.473 | 41823.5 | 63647.2 | 43.4391 |
| 999999 |         |         |         |         |
| 5.5    | 144.156 | 41444.8 | 62889.7 | 43.4391 |
| 999999 |         |         |         |         |
| 5.75   | 142.839 | 41065.1 | 82132.2 | 43.4391 |
| 999999 |         |         |         |         |
| 6      | 141.521 | 40687.3 | 81374.7 | 43.4391 |
| 999999 |         |         |         |         |
| 6.25   | 140.204 | 40308.5 | 60617.2 | 43.4391 |
| 999999 |         |         |         |         |
| 6.5    | 138.886 | 39929.5 | 79859.7 | 43.4391 |
| 999999 |         |         |         |         |
| 6.75   | 137.569 | 39551.1 | 79102.2 | 43.4391 |
| 999999 |         |         |         |         |
| 7      | 136.252 | 39172.3 | 78344.7 | 43.4391 |
| 999999 |         |         |         |         |
| 7.25   | 134.934 | 38793.5 | 77587.2 | 43.4391 |
| 999999 |         |         |         |         |
| 7.5    | 133.617 | 38414.5 | 76829.7 | 43.4391 |
| 999999 |         |         |         |         |
| 7.75   | 132.299 | 38035.1 | 76072.2 | 43.4391 |
| 999999 |         |         |         |         |
| 8      | 130.982 | 37657.3 | 75314.7 | 43.4391 |
| 999999 |         |         |         |         |
| 8.25   | 129.665 | 37278.5 | 74557.2 | 43.4391 |
| 999999 |         |         |         |         |

HDP HT VALUES, IF ANY, ARE IN INCHES

INITIAL CONDITIONS:

WEIGHT OF RECOILING COMPONENTS (LB) = 3398.31  
 WEIGHT OF NON-RECOILING COMPONENTS (LB) = 3000.35  
 SYSTEM WEIGHT (LB) = 6398.63  
 INDIV. TRAIL'S SPRING CONSTANT (LB/IN) = 0  
 PLAY IN END OF TRAILS (IN) = 0

WT, 7100.45

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AT MAXIMUM EXTENSION OF BARREL:

CGZ (IN) = 181.377  
 CGY (IN) = 26.6073  
 CGX (IN) = 43.5311  
 DEFLECTION OF TRAILS (IN) = 0  
 MASS MOMENT OF INERTIA (FT-LB-SEC<sup>2</sup>) = 57248.6

SWEEP ANGLE LEFT (DEGREES) = 0  
 ELEVATION ANGLE (DEGREES) = 0  
 UPWARD SLOPE OF HILL - FORWARD (DEGREES) = 0  
 UPWARD SLOPE OF HILL - SIDE (DEGREES) = 0

| STROKE,<br>MAX FORCE<br>FEET<br>LBS, W/O | CG-Z,<br>INCHES | MAX FORCE<br>LBS, W/O<br>BACKW HDP | STA M.M<br>FT-LBS | CG X,<br>INCHES |
|------------------------------------------|-----------------|------------------------------------|-------------------|-----------------|
| -----<br>-----                           | -----           | -----                              | -----             | -----           |
| 0<br>999999                              | 181.377         | 48357                              | 95714             | 43.5311         |
| .25<br>999999                            | 179.784         | 47932.2                            | 95564.4           | 43.5311         |
| .5<br>999999                             | 178.191         | 47507.4                            | 95414.5           | 43.5311         |
| .75<br>999999                            | 176.598         | 47082.6                            | 95264.6           | 43.5311         |
| 1<br>999999                              | 175.004         | 46657.8                            | 95114.7           | 43.5311         |
| 1.25<br>999999                           | 173.411         | 46233.1                            | 94964.8           | 43.5311         |
| 1.5<br>999999                            | 171.818         | 45808.3                            | 94814.9           | 43.5311         |
| 1.75<br>999999                           | 170.224         | 45383.5                            | 94665.0           | 43.5311         |
| 2<br>999999                              | 168.631         | 44958.7                            | 94515.1           | 43.5311         |
| 2.25<br>999999                           | 167.038         | 44533.9                            | 94365.2           | 43.5311         |
| 2.5<br>999999                            | 165.444         | 44109.1                            | 94215.3           | 43.5311         |
| 2.75<br>999999                           | 163.851         | 43684.3                            | 94065.4           | 43.5311         |
| 3<br>999999                              | 162.258         | 43259.5                            | 93915.5           | 43.5311         |
| 3.25<br>999999                           | 160.665         | 42834.7                            | 93765.6           | 43.5311         |
| 3.5<br>999999                            | 159.071         | 42410                              | 93615.7           | 43.5311         |
| 3.75<br>999999                           | 157.478         | 41985.2                            | 93465.8           | 43.5311         |
| 4                                        | 155.885         | 41560.4                            | 93315.9           | 43.5311         |

|        |      |         |         |         |         |
|--------|------|---------|---------|---------|---------|
| 999999 | 4.25 | 154.291 | 41135.4 | 62271.2 | 43.5311 |
| 999999 | 4.5  | 150.690 | 40710.8 | 61421.0 | 43.5311 |
| 999999 | 4.75 | 151.105 | 40280   | 60572   | 43.5311 |
| 999999 | 5    | 144.512 | 39851.2 | 74722.5 | 43.5311 |
| 999999 | 5.25 | 147.910 | 39435.4 | 73872.9 | 43.5311 |
| 999999 | 5.5  | 145.325 | 39011.7 | 73023.3 | 43.5311 |
| 999999 | 5.75 | 144.732 | 38586.9 | 77173.7 | 43.5311 |
| 999999 | 6    | 143.138 | 38162.1 | 76324.2 | 43.5311 |
| 999999 | 6.25 | 141.545 | 37737.3 | 75474.6 | 43.5311 |
| 999999 | 6.5  | 139.952 | 37312.5 | 74625   | 43.5311 |
| 999999 | 6.75 | 138.358 | 36887.7 | 73775.4 | 43.5311 |
| 999999 | 7    | 136.765 | 36462.9 | 72925.9 | 43.5311 |
| 999999 | 7.25 | 135.172 | 36038.1 | 72075.3 | 43.5311 |
| 999999 | 7.5  | 133.579 | 35613.3 | 71225.7 | 43.5311 |
| 999999 | 7.75 | 131.985 | 35188.5 | 70377.1 | 43.5311 |
| 999999 | 8    | 130.392 | 34763.8 | 69527.5 | 43.5311 |
| 999999 | 8.25 | 128.799 | 34339   | 68676   | 43.5311 |

HDP HT VALUES, IF ANY, ARE IN INCHES

# INITIAL CONDITIONS:

WEIGHT OF RECOILING COMPONENTS (LB) = 3928.57  
 WEIGHT OF NON-RECOILING COMPONENTS (LB) = 3458.49  
 SYSTEM WEIGHT (LB) = 7397.06  
 INDIV. TRAIL'S SPRING CONSTANT (LB/IN) = 0  
 PLAY IN END OF TRAILS (IN) = 0

WT. 8000.45

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## AT MAXIMUM EXTENSION OF BARREL:

CGZ (IN) = 181.377  
 CGY (IN) = 26.6073  
 CGX (IN) = 43.5311  
 DEFLECTION OF TRAILS (IN) = 0  
 MASS MOMENT OF INERTIA (FT-LB-SEC<sup>2</sup>) = 55239.4

SWEEP ANGLE LEFT (DEGREES) = 0  
 ELEVATION ANGLE (DEGREES) = 0  
 UPWARD SLOPE OF HILL - FORWARD (DEGREES) = 0  
 UPWARD SLOPE OF HILL - SIDE (DEGREES) = 0

| STROKE,<br>MAX FORCE<br>FEET<br>LBS, W/D | CG-Z,<br>INCHES | MAX FORCE<br>LBS, W/D | STA MOM<br>FT-LBS | CG X,<br>INCHES |
|------------------------------------------|-----------------|-----------------------|-------------------|-----------------|
| SIDE HOP                                 |                 | BACKW HOP             |                   |                 |
| 0                                        | 181.377         | 55902.5               | 111805            | 43.5311         |
| 999999                                   |                 |                       |                   |                 |
| .25                                      | 179.734         | 55411.5               | 110823            | 43.5311         |
| 999999                                   |                 |                       |                   |                 |
| .5                                       | 178.191         | 54920.4               | 109841            | 43.5311         |
| 999999                                   |                 |                       |                   |                 |
| .75                                      | 176.598         | 54429.3               | 108859            | 43.5311         |
| 999999                                   |                 |                       |                   |                 |
| 1                                        | 175.004         | 53938.2               | 107876            | 43.5311         |
| 999999                                   |                 |                       |                   |                 |
| 1.25                                     | 173.411         | 53447.2               | 106894            | 43.5311         |
| 999999                                   |                 |                       |                   |                 |
| 1.5                                      | 171.818         | 52956.1               | 105912            | 43.5311         |
| 999999                                   |                 |                       |                   |                 |
| 1.75                                     | 170.224         | 52465                 | 104930            | 43.5311         |
| 999999                                   |                 |                       |                   |                 |
| 2                                        | 168.631         | 51974                 | 103948            | 43.5311         |
| 999999                                   |                 |                       |                   |                 |
| 2.25                                     | 167.038         | 51482.9               | 102966            | 43.5311         |
| 999999                                   |                 |                       |                   |                 |
| 2.5                                      | 165.445         | 50991.8               | 101984            | 43.5311         |
| 999999                                   |                 |                       |                   |                 |
| 2.75                                     | 163.851         | 50500.3               | 101002            | 43.5311         |
| 999999                                   |                 |                       |                   |                 |
| 3                                        | 162.258         | 50009.7               | 100019            | 43.5311         |
| 999999                                   |                 |                       |                   |                 |
| 3.25                                     | 160.665         | 49518.5               | 99037.2           | 43.5311         |
| 999999                                   |                 |                       |                   |                 |
| 3.5                                      | 159.071         | 49027.5               | 98055.1           | 43.5311         |
| 999999                                   |                 |                       |                   |                 |
| 3.75                                     | 157.478         | 48536.5               | 97072.9           | 43.5311         |
| 999999                                   |                 |                       |                   |                 |
| 4                                        | 155.885         | 48045.4               | 96090.5           | 43.5311         |

|        |      |         |         |         |         |
|--------|------|---------|---------|---------|---------|
| 999999 | 4.25 | 154.291 | 47554.3 | 95108.6 | 43.5311 |
| 999999 | 4.5  | 152.698 | 47063.2 | 94126.5 | 43.5311 |
| 999999 | 4.75 | 151.105 | 46572.2 | 93144.3 | 43.5311 |
| 999999 | 5    | 149.512 | 46081.1 | 92162.2 | 43.5311 |
| 999999 | 5.25 | 147.918 | 45590   | 91180.1 | 43.5311 |
| 999999 | 5.5  | 146.325 | 45099   | 90197.9 | 43.5311 |
| 999999 | 5.75 | 144.732 | 44607.9 | 89215.8 | 43.5311 |
| 999999 | 6    | 143.138 | 44116.8 | 88233.6 | 43.5311 |
| 999999 | 6.25 | 141.545 | 43625.7 | 87251.5 | 43.5311 |
| 999999 | 6.5  | 139.952 | 43134.7 | 86269.3 | 43.5311 |
| 999999 | 6.75 | 138.358 | 42643.6 | 85287.2 | 43.5311 |
| 999999 | 7    | 136.765 | 42152.5 | 84305.1 | 43.5311 |
| 999999 | 7.25 | 135.172 | 41661.5 | 83322.9 | 43.5311 |
| 999999 | 7.5  | 133.579 | 41170.4 | 82340.8 | 43.5311 |
| 999999 | 7.75 | 131.985 | 40679.3 | 81358.6 | 43.5311 |
| 999999 | 8    | 130.392 | 40188.2 | 80376.5 | 43.5311 |
| 999999 | 8.25 | 128.799 | 39697.2 | 79394.3 | 43.5311 |
| 999999 |      |         |         |         |         |

HOP HT VALUES, IF ANY, ARE IN INCHES



AD-A183 985

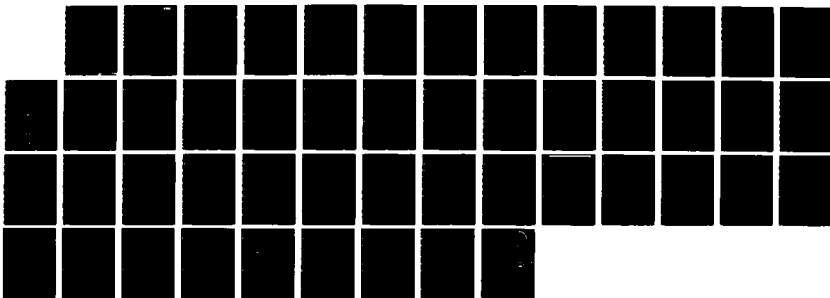
LIGHTWEIGHT TOWED HOWITZER DEMONSTRATOR PHASE 1 AND  
PARTIAL PHASE 2 VOLUM (U) FMC COR MINNEAPOLIS MINN  
NORTHERN ORDNANCE DIV R RATHE ET AL APR 87  
FMC-E-3841-VOL-C-PT-1 DAA21-86-C-8847

3/3

UNCLASSIFIED

F/G 19/6

NL

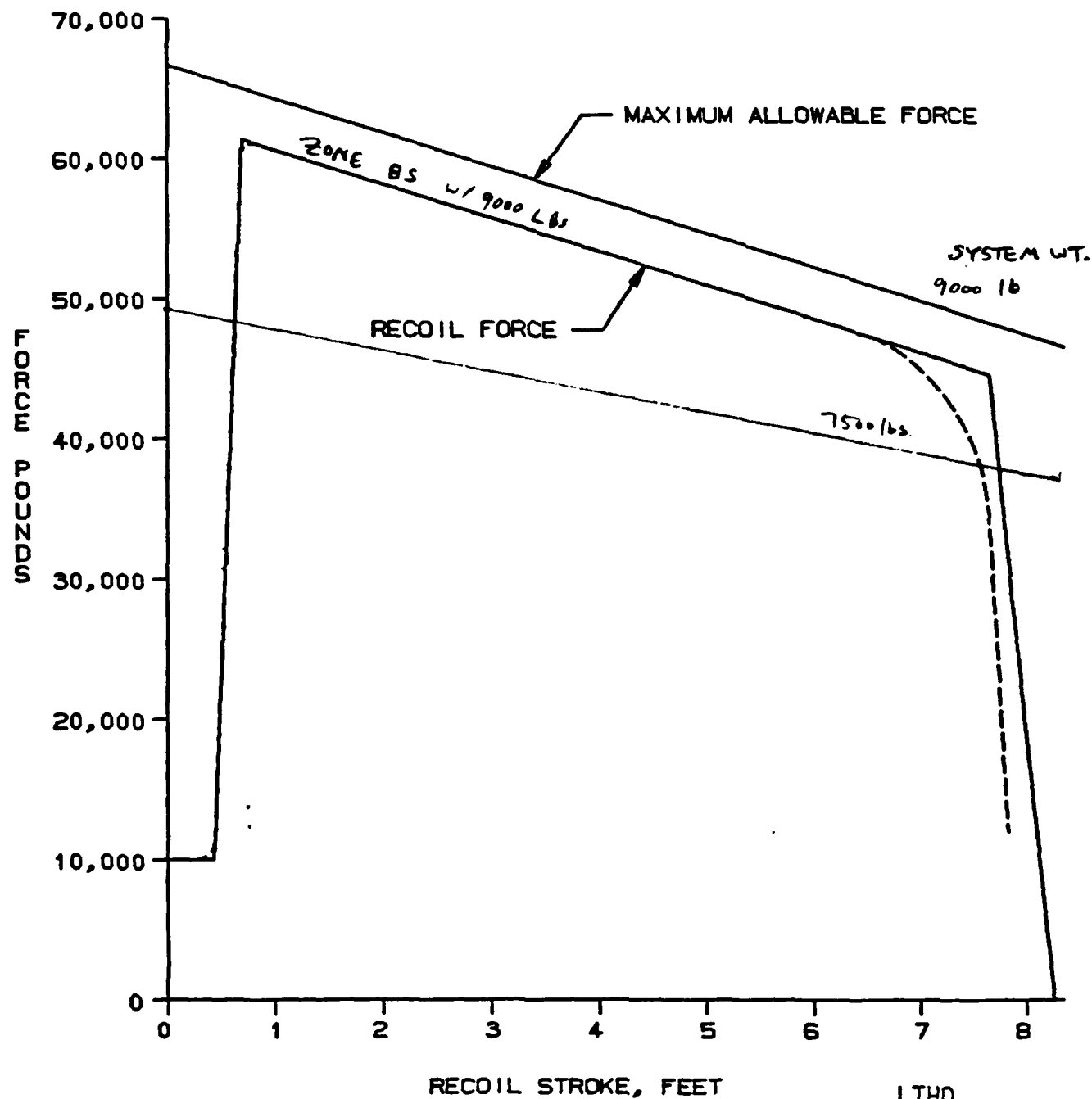




MICROCOPY RESOLUTION TEST CHART

**FMC**

(62)

RECOIL FORCE VS STROKE  
WORST CASE

LTHD

4 MARCH 1986

SD

COMPETITION SENSITIVE

(C)

BL = 198.6"

Free = 10,000 lbs.

63

# RECOIL DIST, FT

| Time, sec.          | MASS = 860 lbs<br>20.2" B.L. |        |        | MASS = 3030 lbs<br>20.2" B.L. |        |        |
|---------------------|------------------------------|--------|--------|-------------------------------|--------|--------|
|                     | 85AKMMSLR                    | 8M483R | 7M483R | 85AKMMSLR                     | 8M483R | 7M483R |
| 11                  | .3297                        | .156   | .098   | .500                          | .238   | .149   |
| 12                  | .397                         | .201   | .130   | .604                          | .306   | .198   |
| 13                  | .466                         | .249   | .164   | .709                          | .379   | .250   |
| 14                  | .536                         | .300   | .200   | .815                          | .457   | .305   |
| 15                  | .606                         | .352   | .238   | .921                          | .536   | .363   |
| 16                  | .676                         | .406   | .278   | 1.028                         | .613   | .422   |
| 17                  | .746                         | .461   | .318   | 1.136                         | .701   | .489   |
| 18                  | .817                         | .516   | .359   | 1.244                         | .785   | .547   |
| 19                  | .889                         | .571   | .401   | 1.353                         | .869   | .611   |
| 20                  | .961                         | .626   | .443   | 1.462                         | .953   | .674   |
| Est.<br>at BL = 202 |                              | .410   | .390   |                               |        |        |
| 10                  |                              |        |        | .432                          |        |        |

What  
Should  
Safety  
margin  
be?

BL = 202"  
5" : .416  
6" : .5 (16.8% Safety margin)  
7" : .583  
6.5" : .596 (13.9%) " "

39 1/3 cal = 242"  
= 202" BL

∴ 5" → 6.5"  
6.5" free recoil

Zone 8S is design charge for  
free recoil length determination  
9.35" free recoil

①

9.55, .76, 8.39, 6., 21.35, 10000, 0  
 Rec. Mass = 3030

% change in  $F = \frac{21.349}{21.35\%}$

$F_{max} = 45,501.7$

50%  
 149,777

147.2  
 $F = 381$

$F_{max} = 6.9\%$  under:  
45,135

29.58.6  
 at 40"

76%

9.55%

9.55%

83.69%

71.8 6%

10

10

70"

90"

10

9

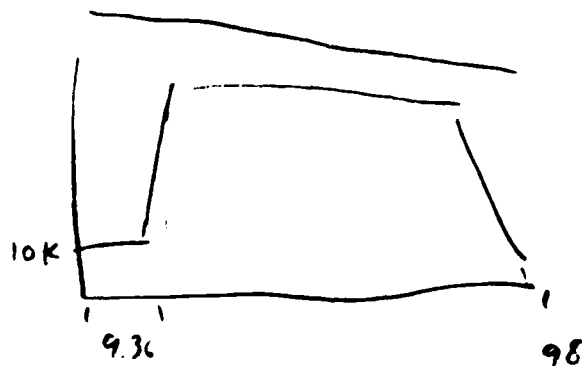
②

$$198.6 \div 199 + 2 = 200.6'' \text{ Barrel.}$$

65

Lighter Wt. : 3030 lbs Rec. Mass

Must have: 9.36" free recoil



see ①

Results cannot Fire Zone 8 w/ M483

CAN Fire Zone 7 w/ M483

6.9% under: Stroke = 6.26'

Recoil must be looped out of to change trapezoids!

| $F_{max}$ | Stroke |                   |
|-----------|--------|-------------------|
| 40K       | 6.65   |                   |
| 45,155    | 6.26   |                   |
| 34K       | 7.89   |                   |
| 32K       | over   | is flt/ser.       |
|           |        | % under max F =   |
|           |        | 29.89             |
|           |        | <u><u>30%</u></u> |

③

8M483R

66

Frax

% under/over

str, D

45,155

- 6.9

8,16 +

48,501

0

8,16 + (V = 40.78)

58,201

+ 20

" (V = 18)

63,051

+ 30

7,59

over by = 25 %

PART NUMBER: 12585727, Lanyard Actuator

DESCRIPTION: LANYARD ACTUATOR

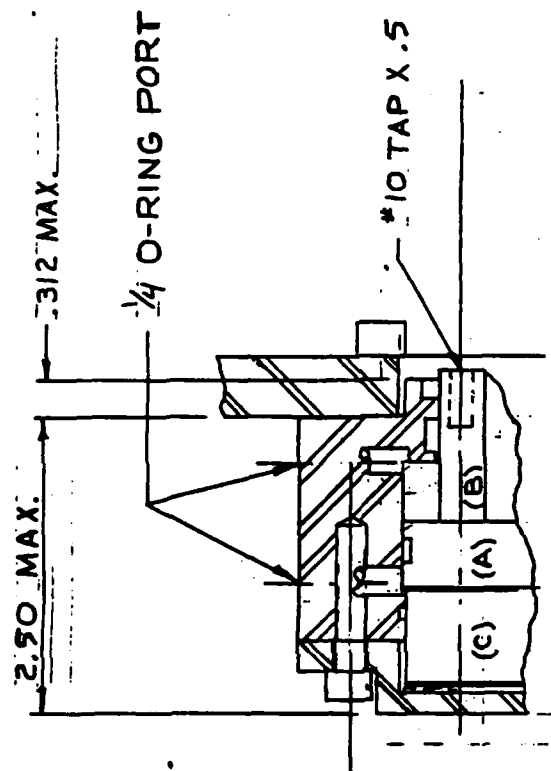
STATUS:

Size and mounting specifications were provided to York for final design. These requirements were developed to be compatible with the FMC primer autoloader.

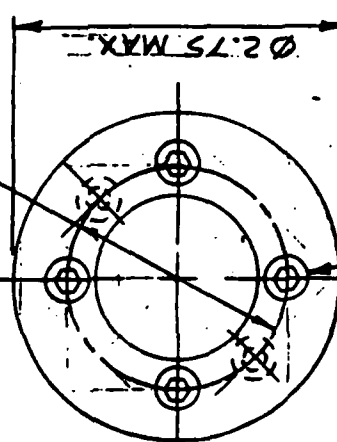
All hoses, fittings and connectors have been finalized and are specified on FMC TDP gang-sheets. Layouts of the lanyard actuator and hoses can be found in the TDP, Cannon Assembly.

AUTHOR: Joe Turek





1.875 BC MAX.



1/4-28 UNF X .75 DR.  
6 PLACES

# LTHD ACTUATORS.

LANYARD ACTUATOR

(A) PISTON DIA. .9687

(B) ROD .375

(C) ROD .875

WORKING PRESSURE 3000 PSI

STROKE .5

RETURN PRESSURE 100 - 300 PSI

SHOCK FACTOR 20 g's

EXTEND FORCE 345 Lbs.

EXTEND OIL FLOW .14 GPM.

ACTUATOR WEIGHT 1 Lbs.

## LTHD ACTUATORS

## LANYARD ACTUATOR

|                  |      |      |
|------------------|------|------|
| PISTON DIA       |      | in.  |
| ROD DIA          |      | in.  |
| WORKING PRESSURE | 3000 | psi  |
| PROOF PRESSURE   | 4500 | psi  |
| EXTEND FORCE     | 200  | lbs. |
| EXTEND OIL FLOW  |      | gpm  |
| RETRACT FORCE    | 50   | lbs. |
| RETRACT OIL FLOW |      | gpm  |

|                        |       |     |
|------------------------|-------|-----|
| EXTENDED LENGTH        | 4.125 | in. |
| RETRACTED LENGTH       | 3.5   | in. |
| STROKE                 | 0.500 | in. |
| EXTEND CUSHION LENGTH  |       | in. |
| RETRACT CUSHION LENGTH |       | in. |

## ACTUATOR ENDS:

CYLINDER END

 BOLTED TO  
 AUTO-PRIMER  
 EYE

ROD END

|                 |    |      |
|-----------------|----|------|
| ACTUATOR WEIGHT | 1  | lbs. |
| SHOCK FACTOR    | 20 | g's  |

COMMENTS:

1/27/87

4

LANYARD P. 1051

.25 SEC  $\frac{60}{.25} = 240 \times .5 = 120$  " PER MIN <sup>STROKE</sup>

A 1" = .785      .1358 X 120 =  $\frac{16.294}{231} = .0705$  GPM  
 A =  $\frac{7}{8}$  = .6013  
 A =  $\frac{31}{32}$  = .737      .737 - .1104 = .6266       $\frac{.0705 \times 2}{.1411}$   
 A =  $\frac{3}{8}$  = .1104

| P        | A       | F      |
|----------|---------|--------|
| 3000 PSI | X .1358 | = 408  |
| 100 PSI  | X .6266 | = 62.7 |
| 300 PSI  | X .6266 | = 188  |

$\begin{array}{r} 408 \\ - 62.7 \\ \hline 345 \# \end{array}$

345 ON LANYARD      NEEDED 200  
 OK PER TIM      1/27/87

A X LGH.      SQ  
 .1358 X .187 = .0254      S =  $\frac{345}{.0254} = 13,585$   
 ON O-RING LAND  
 Y = 50,000 (.577) = 28,850

A =  $\frac{1}{8}$  = .125  
 A =  $\frac{3}{8}$  = .375  
 DIFF = .375 - .125 = .25  
 X 3000 PSI  
 F = 1,178 #


.3927 X .187 = .0734  
 $\frac{P}{A} = \frac{1178}{.0734} = S = 16,049$

## LANYARD

(A) PRES. HOSE LG. = 16.00

$$R = 4.238 = C \quad 26.628 \div 2 = 13.314 + .312 + .312 + 1.58 + 1.58$$

$$= 17.098 - (.55 \times 2) = 15.998$$

$$*.55 = x =$$


(B) RETURN HOSE LG. = 16.375

$$R. 4.062 + .30 = 4.362 = C = 27.4073 \div 2 = 13.703$$

$$13.703 + (.312 \times 2) + (1.58 \times 2) = 17.487 - (.55 \times 2) = 16.387$$

$$16.375$$

( BOTH HOSES TO BE 16.375 LG.  
3/2/87

PRIMER TO LANYARD HOSES

~~OVER~~ OVER ALL LG 17.487

PART NUMBER: 12585728, Load Position Actuator

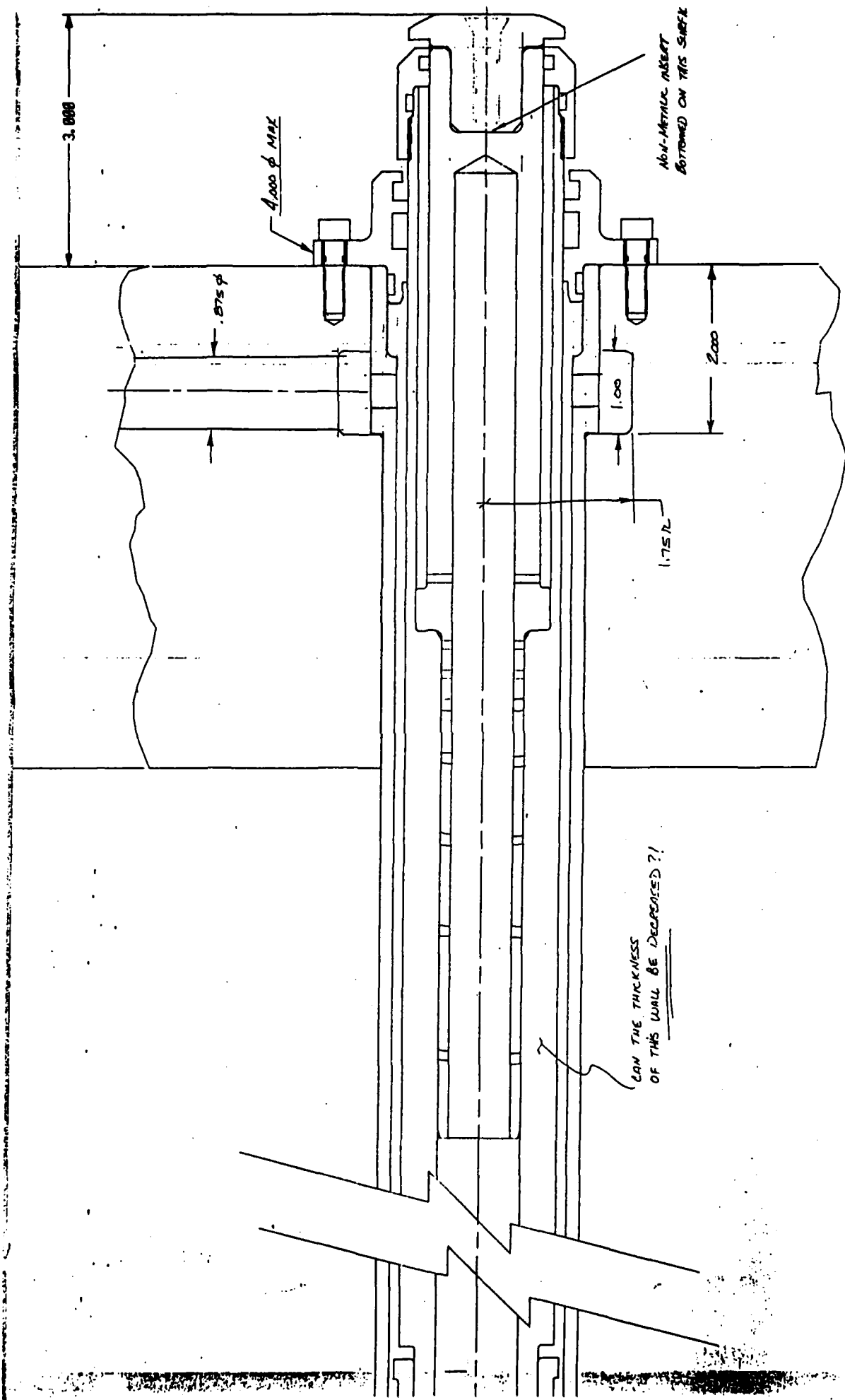
DESCRIPTION: LOAD POSITION ACTUATOR

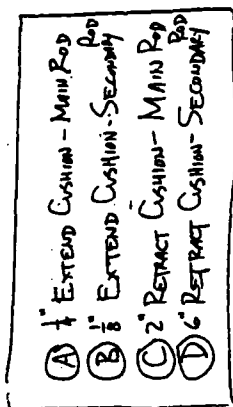
This actuator controls the cannon position. The actuator is used to drive the cannon to the load position from battery, hold the cannon to the load position, or return the cannon to the battery position from the load position. It also serves as a counter-recoil buffer when returning to either load or battery positions.

STATUS:

Size and mounting specifications were provided to York for finalized design.

AUTHOR: Jeff Ireland





|           |          |                      |
|-----------|----------|----------------------|
| T-1258    | 5717     | YORK SPREAD SHEET    |
| 1258      | 5710-460 | HYDRAULIC FUNCTIONAL |
| REF. DWG. |          | DESCRIPTION          |

**PART NO.**

[illegible]

## DESCRIPTION: LOADING SYSTEM

The LTHD loading system consists of a load tray, projectile carrier, inertial rammer actuator and ram velocity control valve, and ram control. For a description of the operational procedures for loading, the reader is referred to the TDP, Dwg. 12585710-825, pp. 3 (Loading Controls), 12 (Max Rate of Fire Timeline), 13-14 (Max Rate of Fire Procedures) and 15-17 (Sustained Rate of Fire Procedures).

## STATUS:

**Load Tray.** Layouts of the load tray design have been completed and a majority of the components can be found in the TDP as preliminary drawings. The current load tray assembly uses graphite epoxy as the primary material; however, a study was begun to re-evaluate the use of aluminum. The load tray configuration was designed to withstand all LTHD load conditions with the exception of being able to withstand firing loads with a projectile in the tray at the time of firing.

**Projectile Carrier.** The function of the separable projectile carrier is to provide a simple means for two cannoneers to carry projectiles to the load tray and place the projectile in the tray without getting their fingers or hands pinched or injured. This part has not yet reached the layout stage.

**Rammer Actuator and Ram Velocity Control Valve.** A ramming system consisting of a hydraulic actuator (TDP, Dwg. 12585729) and ram velocity control valve (TDP, Dwg. 12585902) has been developed to ram the load tray and projectile and provide the required ram velocity for proper projectile seating at all loading QE's. The motion provided includes an initial slow velocity to round the travel path bend that exists between 0 and 600 mils, and then fast ram velocity which seats the projectile. Actuator sizing and preliminary orifice sizing have been determined; fine-tuning of the system to achieve required ram velocities would take place during testing.

**Ram Control.** A Marotta-developed ram control valve (TDP, Dwg. 12585900-002) initiates the ram cycle and the cannoneer has a choice of ramming either fast or slow. The slow ram option is only used if a projectile such as a Copperhead is to be manually rammed or if the load tray is to be positioned behind the breech to remove an unfired or stuck projectile. All requirements for this component have been completed.

**AUTHORS:** Kent Williams, Ron Larson, Bart Anderson, Jeff Ireland



J.V. 2  
3/9/87

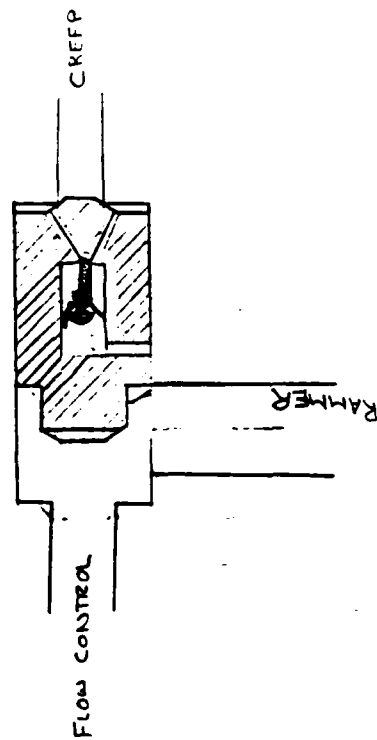
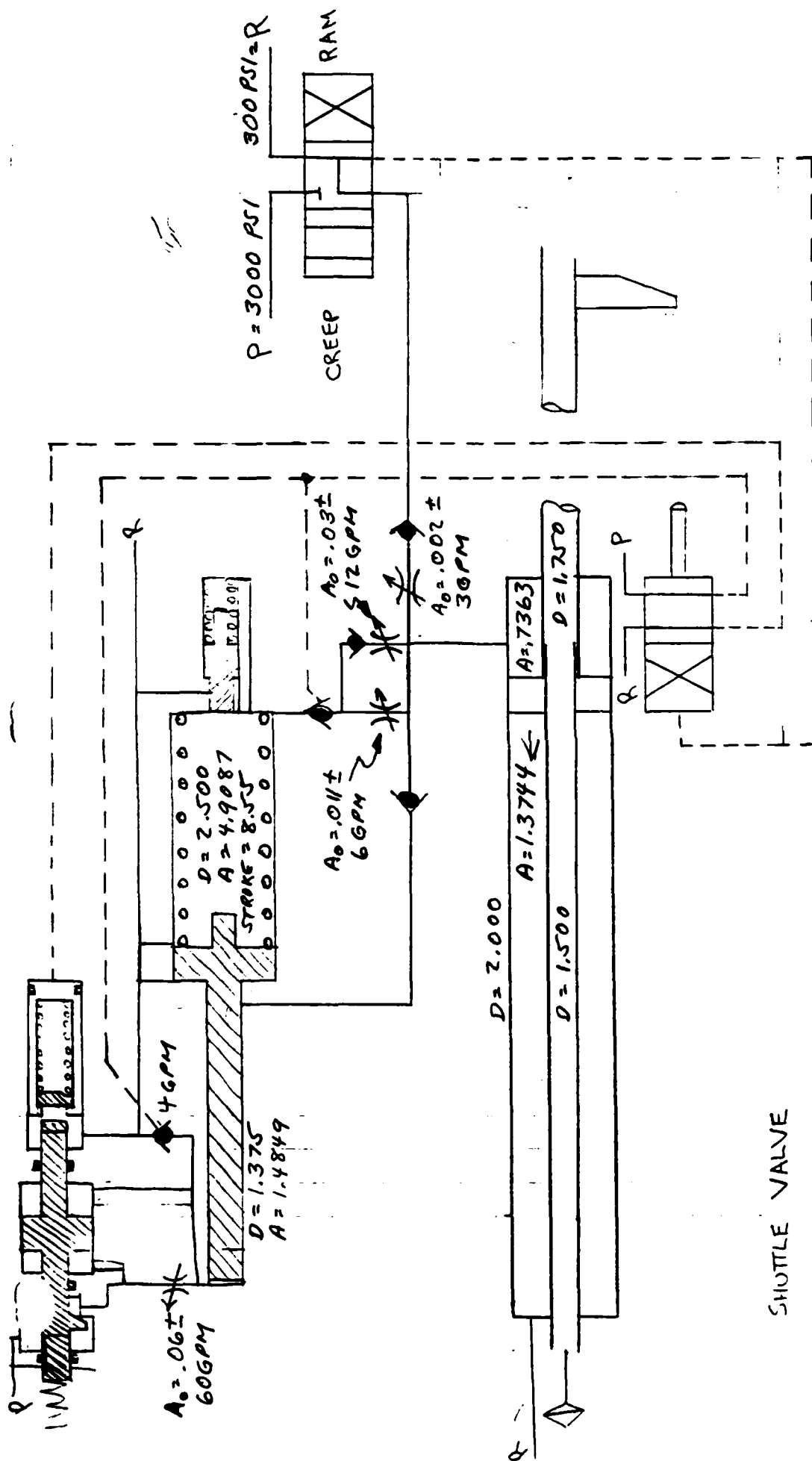
### LTHD Rammer Circuit

The attached circuit diagram and calculator printouts show the critical dimensions and performance predictions for the rammer system.

Analysis of the operating parameters indicates the need for four variable orifices for independent control of slow speed control of the projectile and tray through the transition tracks, high speed control of maximum ramming velocity, control of creep speed when using copperhead projectile, and control of tray return speed to the load position.

The two calculator runs at the extreme ends of operating temperature range indicate a minimal sensitivity to temperature, and optimum performance should be obtainable with fine tuning adjustments on the demonstrator model.

Additional analysis of the de-equalizer shows that the ratio of areas of 3.3:1 is near optimum. However, piston diameters can be changed if desirable as long as this area ratio is maintained.



1/10/17  
MIC CONS.  
TIME CYCLE  
FX1B1C17Y

# RAMMER DATA

03/02/87 11:36:10 AM

M1=0.0130  
M2=0.4275  
PA=3.000.0000  
PR=300.0000  
D1=1.3750  
D2=2.5000  
D3=2.0000  
D4=1.7500  
D5=1.5000  
D6=1.8900  
D7=1.8500  
A01=0.0600  
A02=0.0300  
A03=0.0110  
A04=0.7854  
A05=0.7854  
L1=18.2500  
L2=2.0000  
L3=4.0000  
L4=87.0000  
MU=0.8000  
RHO=0.0308  
G=386.0000  
MU=0.0001  
A1=1.4849  
A2=3.4238  
A3=4.9027  
A4=0.7363  
A5=1.3744  
C1=0.0256  
C2=0.0928  
C3=0.0699  
C4=0.0122  
C5=1.7116  
WT=165.0000  
ANG=33.7500  
FRC=0.1000

R66= 711.9815  
R61= 0.5795  
R62= 10.2705  
R63= 0.0047  
R64= 711.9815  
R65= 0.5795  
R66= 15.6912  
R67= -2.7056  
R68= 711.9815  
R69= 0.5795  
R70= 4.8497  
R71= 0.0047  
R72= 3.956.4063  
R73= 0.0203  
R74= 4.8531  
R75= 0.0047  
R76= -1.319.2192  
R77= 0.1996  
R78= 12.3193  
R79= 0.0120

→ (-25°F.)

TIME X VEL ACC

0.00 0.0 0.0 712.0  
0.01 3.6-02 7.1 609.5  
0.02 0.1 13.2 475.1  
0.03 0.3 18.0 340.4  
0.04 0.5 21.4 227.8  
0.05 0.7 23.6 145.0  
0.06 1.0 25.1 89.1  
0.07 1.2 26.0 53.5  
0.08 1.5 26.5 31.7  
0.09 1.7 26.8 18.6  
0.10 2.0 27.0 11.8  
0.11 2.3 27.1 26.8  
0.12 2.6 27.4 36.0  
0.13 2.8 27.8 42.1  
0.14 3.1 28.2 46.4  
0.15 3.4 28.7 49.2  
0.16 3.7 29.2 52.7  
0.17 4.0 29.7 55.3  
0.18 4.3 30.2 35.0  
0.20 4.9 30.9 6.7  
0.22 5.5 31.1 1.1  
0.24 6.1 31.1 0.1  
0.26 6.6 31.1-0.1  
0.28 7.4 31.1-0.1  
0.30 8.0 31.1-0.1  
0.32 8.6 31.1-0.1  
0.34 9.2 31.1-0.1  
0.36 9.9 31.1-0.1  
0.38 10.5 31.1-0.1  
0.40 11.1 31.1-0.1  
0.42 11.7 31.1-0.1  
0.44 12.3 31.1-0.1  
0.46 13.0 31.1-0.1  
0.48 13.6 31.1-0.1  
0.50 14.2 31.1-0.1  
1.66 50.2 30.9-0.1  
1.68 50.9 30.9-0.1  
1.70 51.4 30.9-0.1  
1.72 52.0 30.9-0.1  
1.74 52.7 30.9-0.1  
1.76 53.3 30.9-0.1  
1.78 53.9 30.9-0.1  
1.80 54.5 30.9-0.1  
1.82 55.1 30.9-0.1  
1.84 55.7 30.9-0.1  
1.86 56.4 30.9-0.1  
1.88 57.0 30.9-0.1  
1.90 57.6 30.9 3.778.6  
1.91 58.1 68.7 3.508.3  
1.92 59.0 103.8 3.205.2  
1.93 60.2 135.8 2.804.0  
1.94 61.7 164.7 2.558.0  
1.95 63.4 190.3 2.241.2  
1.96 65.4 212.7 1.940.4  
1.97 67.7 232.1 1.662.6  
1.98 70.1 248.7 1.411.5  
1.99 72.6 262.8 1.180.6  
2.00 75.3 274.7 993.7  
2.01 78.1 284.6 825.3  
2.02 81.0 292.9 681.5  
2.03 84.0 299.7 553.6  
2.04 87.0 305.7 457.1

RETRACT RAM

0.00 87.0 0.0-1.319.2  
0.02 86.7-26.4-827.7  
0.04 86.0-42.9-377.8  
0.06 85.1-50.5-136.6  
0.08 84.1-53.2-44.2  
0.10 83.0-54.1-14.2  
0.12 81.9-54.4-5.0  
0.14 80.8-54.5-2.2  
0.16 79.7-54.5-1.4  
0.18 78.6-54.6-1.1  
0.20 77.6-54.6-1.1  
0.22 76.5-54.6-1.0  
0.24 75.4-54.6-1.0  
0.26 74.3-54.7-1.0  
0.28 73.2-54.7-1.0  
0.30 72.1-54.7-1.0  
0.32 71.0-54.7-1.0  
0.34 69.9-54.7-1.0  
0.36 68.8-54.8-1.0  
0.38 67.7-54.8-1.0  
0.40 66.6-54.8-1.0  
0.42 65.5-54.8-1.0  
0.44 64.4-54.8-1.0  
0.46 63.3-54.9-1.0  
0.48 62.2-54.9-1.0  
0.50 61.1-54.9-1.0  
0.52 60.0-54.9-1.0  
0.54 58.9-54.9-1.0  
0.56 57.8-55.0-1.0  
0.58 56.7-55.0-1.0  
0.60 55.6-55.0-1.0  
0.62 54.5-55.0-1.0  
1.02 32.4-55.4-1.1  
1.04 31.3-55.5-1.1  
1.06 30.2-55.5-1.1  
1.08 29.1-55.5-1.1  
1.10 28.0-55.5-1.1  
1.12 26.9-55.5-1.1  
1.14 25.8-55.6-1.1  
1.16 24.7-55.6-1.1  
1.18 23.6-55.6-1.1  
1.20 22.4-55.6-1.1  
1.22 21.3-55.7-1.1  
1.24 20.2-55.7-1.1  
1.26 19.1-55.7-1.1  
1.28 18.0-55.7-1.1  
1.30 16.9-55.7-1.1  
1.32 15.8-55.8-1.1  
1.34 14.6-55.8-1.1  
1.36 13.5-55.8-1.1  
1.38 12.4-55.8-1.1  
1.40 11.3-55.8-1.1  
1.42 10.2-55.9-1.1  
1.44 9.1-55.9-1.1  
1.46 7.9-55.9-1.1  
1.48 6.8-55.9-1.1  
1.50 5.7-56.0-1.1  
1.52 4.6-56.0-1.1  
1.54 3.5-56.0-1.1  
1.56 2.3-56.0-1.1  
1.58 1.2-56.0-1.1  
1.60 0.1-56.1-1.1  
END OF STROKE

4

# RAMMER DATA

03/02/87 1:20:10 PM

M1=0.0130  
M2=0.4275  
PA=3.000.0000  
PR=300.0000  
B1=1.3750  
B2=2.5000  
B3=2.0000  
B4=1.7500  
B5=1.5000  
B6=1.8800  
B7=1.8500  
A01=0.0600  
A02=0.0300  
A03=0.0110  
A04=0.7854  
A05=0.7854  
L1=18.2500  
L2=2.0000  
L3=4.0000  
L4=87.0000  
NU=0.0000  
RHO=0.0300  
G=386.0000  
MU=6.3834E-7  
A1=1.4849  
A2=3.4238  
A3=4.9087  
A4=0.7362  
A5=1.3744  
C1=0.0003  
C2=0.0009  
C3=0.0007  
C4=0.0001  
C5=0.0171  
WT=165.0000  
ANG=33.7500  
FRC=0.1000

R60= 711.9815  
R61= 0.5795  
R62= 0.1027  
R63= 4.7298-05  
R64= 711.9815  
R65= 0.5795  
R66= 0.1569  
R67= -0.0271  
R68= 711.9815  
R69= 0.5795  
R70= 0.0485  
R71= 4.7298-05  
R72= 3.956.4063  
R73= 0.0203  
R74= 0.0485  
R75= 4.7330-05  
R76= -1.319.2192  
R77= 0.1996  
R78= 0.1232  
R79= 0.0001

→ (+160° F.)

TIME X VEL ACC

0.00 0.0 0.0 712.0  
0.01 3.6-02 7.1 681.9  
0.02 0.1 13.9 598.0  
0.03 0.3 19.9 480.0  
0.04 0.5 24.7 355.3  
0.05 0.8 28.3 245.9  
0.06 1.1 30.7 161.5  
0.07 1.4 32.3 102.3  
0.08 1.7 33.4 63.2  
0.09 2.1 34.0 38.6  
0.10 2.4 34.4 23.6  
0.11 2.8 34.6 14.4  
0.12 3.1 34.8 8.9  
0.13 3.5 34.9 5.7  
0.14 3.8 34.9 3.7  
0.15 4.2 34.9 2.4  
0.17 4.9 35.0 0.4  
0.19 5.6 35.0 0.1  
0.21 6.3 35.0 1.4-02  
0.23 7.0 35.0 1.5-02  
0.25 7.7 35.0-5.7-04  
0.27 8.4 35.0-1.3-03  
0.29 9.1 35.0-1.4-03  
0.31 9.8 35.0-1.4-03  
0.33 10.5 35.0-1.4-03  
0.35 11.2 35.0-1.4-03  
0.37 11.9 35.0-1.4-03  
0.39 12.6 35.0-1.4-03  
0.41 13.3 35.0-1.4-03  
0.43 14.0 35.0-1.4-03  
0.45 14.7 35.0-1.4-03  
0.47 15.4 35.0-1.4-03  
0.49 16.1 35.0-1.4-03  
1.43 49.0 35.0-1.4-03  
1.45 49.7 35.0-1.4-03  
1.47 50.4 35.0-1.4-03  
1.49 51.1 35.0-1.4-03  
1.51 51.8 35.0-1.4-03  
1.53 52.5 35.0-1.4-03  
1.55 53.2 35.0-1.4-03  
1.57 53.9 35.0-1.4-03  
1.59 54.6 35.0-1.4-03  
1.61 55.3 35.0-1.4-03  
1.63 56.0 35.0-1.4-03  
1.65 56.7 35.0-1.4-03  
1.67 57.4 35.0 3.929.7  
1.68 57.9 74.3 3.040.5  
1.69 58.0 112.7 3.692.8  
1.70 60.2 149.6 3.494.2  
1.71 61.0 184.6 3.255.4  
1.72 63.8 217.1 2.908.3  
1.73 66.2 247.0 2.705.2  
1.74 68.8 274.1 2.417.6  
1.75 71.6 298.2 2.135.5  
1.76 74.7 319.5 1.866.5  
1.77 79.0 338.3 1.616.3  
1.78 81.5 354.4 1.368.1  
1.79 85.1 363.3 1.185.7

RETRACT RAM

0.00 87.0 0.0-1.319.2  
0.02 86.7-26.4-1.176.7  
0.04 86.0-49.9-815.1  
0.06 84.8-66.2-435.0  
0.08 83.4-74.9-188.6  
0.10 81.9-78.7-72.5  
0.12 80.3-80.1-26.3  
0.14 78.7-80.7-9.4  
0.16 77.1-80.9-3.3  
0.18 75.4-80.9-1.2  
0.20 73.8-81.0-0.4  
0.22 72.2-81.0-0.2  
0.24 70.6-81.0-0.1  
0.26 69.0-81.0-4.2-02  
0.28 67.3-81.0-3.0-02  
0.30 65.7-81.0-2.6-02  
0.32 64.1-81.0-2.5-02  
0.34 62.5-81.0-2.5-02  
0.36 60.9-81.0-2.4-02  
0.38 59.2-81.0-2.4-02  
0.40 57.6-81.0-2.4-02  
0.42 56.0-81.0-2.4-02  
0.44 54.4-81.0-2.4-02  
0.46 52.8-81.0-2.4-02  
0.48 51.1-81.0-2.4-02  
0.50 49.5-81.0-2.4-02  
0.52 47.9-81.0-2.4-02  
0.54 46.3-81.0-2.4-02  
0.56 44.7-81.0-2.4-02  
0.58 43.0-81.0-2.4-02  
0.60 41.4-81.0-2.4-02  
0.62 39.8-81.0-2.4-02  
0.64 38.2-81.0-2.4-02  
0.66 36.6-81.0-2.4-02  
0.68 34.9-81.0-2.4-02  
0.70 33.3-81.0-2.4-02  
0.72 31.7-81.0-2.4-02  
0.74 30.1-81.0-2.4-02  
0.76 28.5-81.0-2.4-02  
0.78 26.9-81.0-2.4-02  
0.80 25.2-81.0-2.4-02  
0.82 23.6-81.0-2.4-02  
0.84 22.0-81.0-2.4-02  
0.86 20.4-81.0-2.4-02  
0.88 18.8-81.0-2.4-02  
0.90 17.1-81.0-2.4-02  
0.92 15.5-81.0-2.4-02  
0.94 13.9-81.0-2.4-02  
0.96 12.3-81.0-2.4-02  
0.98 10.7-81.0-2.4-02  
1.00 9.0-81.0-2.4-02  
1.02 7.4-81.0-2.4-02  
1.04 5.8-81.0-2.4-02  
1.06 4.2-81.0-2.4-02  
1.08 2.6-81.0-2.4-02  
1.10 0.9-81.0-2.4-02

END OF STROKE

01\*LBL "RAMMER"

FIX 4 .013 STO 11

3000 STO 13 300

STO 14 1.375 STO 15

2.5 STO 16 2 STO 17

1.75 STO 18 1.5

STO 19 1.88 STO 20

1.05 STO 21 .06

STO 22 .03 STO 23

.011 STO 24 .7854

STO 25 .7854 STO 26

18.25 STO 27 2 STO 28

4 STO 29 87 STO 30

.008 STO 31 .0308

STO 32 165 STO 57 386

STO 33 / STO 12 33.75

STO 58 .1 STO 59

55\*LBL "MU"

RCL 31 RCL 32 \*

RCL 33 / STO 34

62\*LBL "A1"

RCL 15 X12 PI \* 4 /

STO 35

70\*LBL "A2"

RCL 16 X12 RCL 15 X12

- PI \* 4 / STO 36

81\*LBL "A3"

RCL 16 X12 PI \* 4 /

STO 37

89\*LBL "A4"

RCL 17 X12 RCL 18 X12

- PI \* 4 / STO 38

100\*LBL "A5"

RCL 17 X12 RCL 19 X12

- PI \* 4 / STO 39

111\*LBL "C1"

17 STO 53 12 STO 54

XEQ "CX" STO 40

118\*LBL "C2"

20 STO 53 XEQ "CX"

STO 41

123\*LBL "C3"

17 STO 53 21 STO 54

XEQ "CX" STO 42

130\*LBL "C4"

RCL 17 X12 RCL 19 X12

- STO 56 RCL 17

RCL 19 / LN STO 55 \*

RCL 17 X12 X12 RCL 19

X12 X12 - RCL 55 \*

RCL 56 X12 - / 32 \*

RCL 34 \* STO 43

161\*LBL "C5"

20 STO 53 XEQ "CX"

STO 44 GTO "B1"

167\*LBL "CX"

RCL IND 53 X12 2 \*

RCL IND 53 RCL IND 54

/ LN STO 55 \*

RCL IND 53 X12

RCL IND 54 X12 -

STO 56 - RCL IND 53

X12 X12 RCL IND 54

X12 X12 - RCL 55 \*

RCL 56 X12 - / 16 \*

RCL 34 \* RTN

203\*LBL "B1"

RCL 35 RCL 13 \*

RCL 36 RCL 14 \* +

RCL 37 \* RCL 38 \*

RCL 39 RCL 14 \*

RCL 37 X12 \* -

RCL 58 COS RCL 59 \*

RCL 58 SIN + RCL 57

\* RCL 37 X12 \* -

RCL 12 RCL 37 X12 \*

RCL 11 RCL 38 X12 \*

+ / STO 60 STO 64

STO 68

240\*LBL "B1+"

RCL 38 RCL 13 \*

RCL 39 RCL 14 \* -

RCL 58 COS RCL 59 \*

RCL 58 SIN + RCL 57

\* - RCL 12 / STO 72

269\*LBL "B1--"

RCL 38 RCL 39 -

RCL 14 \* RCL 58 COS

RCL 59 \* CHS RCL 58

SIN + RCL 57 100 -

\* - RCL 12 100

ENTER 386 / - /

STO 76

296\*LBL "B2"

RCL 38 RCL 35 \* 3

Y1X RCL 37 / RCL 22

X12 / RCL 38 3 Y1X

RCL 37 X12 \* RCL 24

X12 / + RCL 38 3

Y1X RCL 37 X12 \*

RCL 25 X12 / +

RCL 39 3 Y1X RCL 37

X12 \* RCL 26 X12 /

+ RCL 12 RCL 37 X12

\* RCL 11 RCL 38 X12

\* \* / 115.5 X12 /

STO 61 STO 65 STO 69

353\*LBL "B2+"

RCL 38 3 Y1X RCL 25

X12 / RCL 39 3 Y1X

RCL 26 X12 / +

STO 77 RCL 38 3 Y1X

RCL 22 X12 / +

RCL 12 / 115.5 X12 /

STO 73

381\*LBL "B2--"

RCL 77 RCL 39 3 Y1X

RCL 23 X12 / +

RCL 12 100 ENTER 386

/ - / 115.5 X12 /

STO 77

401\*LBL "B3B4"

RCL 27 RCL 28 +

RCL 29 - RCL 40 \*

RCL 29 RCL 28 -

RCL 42 \* + RCL 28

RCL 44 \* + STO 62

RCL 27 RCL 40 \*

RCL 29 RCL 29 -

RCL 41 \* + RCL 29

RCL 44 \* + STO 66

RCL 27 RCL 29 -

RCL 40 \* RCL 28

RCL 41 \* + RCL 29

RCL 42 \* + STO 70

STO 74 RCL 40 STO 63

STO 71 STO 75 RCL 41

RCL 42 + RCL 44 -

STO 67 RCL 38 ST\* 62

ST\* 63 ST\* 66 ST\* 67

ST\* 70 ST\* 71 ST\* 74

ST\* 75 RCL 38 RCL 43

\* RCL 39 \* ST+ 62

ST+ 66 ST+ 70 ST+ 74

RCL 43 RCL 39 \*

ST- 63 ST- 67 ST- 71

ST- 75 RCL 12 RCL 37

X12 \* RCL 11 RCL 38

X12 \* + RCL 37 X12

/ ST/ 62 ST/ 63

ST/ 66 ST/ 67 ST/ 70

ST/ 71 RCL 12 ST/ 74

ST/ 75 RCL 74 STO 78

RCL 75 STO 79 65

ENTER 165 / ST/ 78

ST/ 79 FS? 02

GTO "DIF"

517\*LBL "DATA"

"RAMMER DATA" SF 12

PRA CF 12 CLA DATE

ADATE "T" TIME ATIME

AVIEW ADV "M1="

ARCL 11 AVIEW "M2="

ARCL 12 AVIEW "PA="

ARCL 13 AVIEW "PR="

ARCL 14 AVIEW "D1="

ARCL 15 AVIEW "D2="

ARCL 16 AVIEW "D3="

ARCL 17 AVIEW "D4="

ARCL 18 AVIEW "D5="

ARCL 19 AVIEW "D6="

ARCL 20 AVIEW "D7="

ARCL 21 AVIEW "A01="

ARCL 22 AVIEW "A02="

ARCL 23 AVIEW "A03="

ARCL 24 AVIEW "A04="

ARCL 25 AVIEW "A05="

ARCL 26 AVIEW "L1="

ARCL 27 AVIEW "L2="

ARCL 28 AVIEW "L3="

ARCL 29 AVIEW "L4="

ARCL 30 AVIEW "NU="

ARCL 31 AVIEW "RHO="

ARCL 32 AVIEW "G="

ARCL 33 AVIEW "MU="

ARCL 34 AVIEW "A1="

ARCL 35 AVIEW "A2="

ARCL 36 AVIEW "A3="

ARCL 37 AVIEW "A4="

ARCL 38 AVIEW "A5="

ARCL 39 AVIEW "C1="

ARCL 40 AVIEW "C2="

ARCL 41 AVIEW "C3="

ARCL 42 AVIEW "C4="

ARCL 43 AVIEW "C5="

ARCL 44 AVIEW "WT="

ARCL 57 AVIEW "ANG="

ARCL 58 AVIEW "FRC="

ARCL 59 AVIEW 60.079

PRREGX ADV

644\*LBL "DIF"

"TIME X"

"FVEL ACC" AVIEW

-----

"-----" AVIEW

SF 21 "RAM" ASTO 07

"X0=?" PROMPT STO 02

"Y0=?" PROMPT STO 03

"Y0.=?" PROMPT STO 04

663\*LBL "OUT"

XEQ IND 07 STO 05 CLA

FIX 2 RCL 02 ACY

FIX 1 RCL 03 ACX

RCL 04 ACX RCL 05 ACX

PRDEF CLE

679\*LBL 18  
 RCL 04 RCL 03 RCL 02  
 XEQ IND 07 XEQ 07  
 STO 05 STO 00 RCL 01  
 XEQ 06 STO 06 STO 00  
 RCL 01 RCL 00 RCL 04  
 + RCL 05 XEQ 05  
 ST+ 06 ENTER+ +  
 STO 00 RCL 01 ENTER+  
 + XEQ 06 RCL 06  
 ENTER+ + + RCL 05 +  
 3 / RCL 04 + STO 04  
 LASTX RCL 06 RCL 05 +  
 3 / + RCL 01 ENTER+  
 + STO 05 \* ST+ 03  
 RCL 05 ST+ 02 0  
 RCL 03 X<=Y?  
 GTO "DONE" GTO "OUT"

736\*LBL "DONE"  
 "END OF STROKE" ADVIEW  
 ADV ADV ADV ADV ADV  
 CF 00 CF 01 FIX 4  
 STOP

748\*LBL 04  
 RCL 03 + RCL 02  
 RCL 01 + XEQ IND 07  
 XEQ 07 RTN

757\*LBL 06  
 RCL 00 RCL 04 +  
 RCL 00

762\*LBL 05  
 2 / RCL 04 + R+ \*  
 RCL 03 + RCL 02 R+ +  
 XEQ IND 07

775\*LBL 07  
 RCL 01 \* RTN

779\*LBL "RAM"  
 FS? 00 GTO "AA" .005  
 STO 01 .01 FS?C 0!  
 STO 01 RCL 03 2 -  
 SIGN RCL 03 4 - SIGN  
 + RCL 03 57 - SIGN  
 + RCL 03 87 - SIGN  
 + 4 + 2 \* 60 +  
 STO 00 1 + STO 09 1  
 + STO 10 ! + STO 11  
 79 X=Y? SF 00 0 -  
 X=Y? SF 01 FC? 00  
 GTO "AA" "RETRACT RAM"  
 SF 12 PRA CF 12 0  
 STO 02 87 STO 03 0  
 STO 04 .01 STO 01  
 GTO "OUT"

844\*LBL "AA"  
 RCL IND 08 RCL IND 09  
 RCL 04 X12 \* FS? 00  
 CHS - RCL IND 10  
 RCL IND 11 RCL 03 \* +  
 RCL 04 \* - STO 52  
 RTN .END.

### LTHD Rammer Hydraulic Circuit

The rammer circuit is shown in the attached illustration and consists of a flow control valve, a de-intensifier, variable orifices for controlling actuator speeds, a ramming actuator, a three position four way control valve providing a selection of ram or creep speeds, and a pilot actuated / mechanical reset two position control valve for reversing the actuator direction.

Operation of the hydraulic ramming circuit is as follows:

1. When the primary control valve is set to the ram position, a pilot signal is sent to the secondary control valve which shifts the two position spool to start the ramming action.
2. Main supply pressure is directed to the back of the flow control valve which sets the piston and spring assembly to open the valve and provide the desired flow characteristics to the rest of the circuit. At the same time, the pilot operated check valve at the inlet to the de-intensifier is closed.
3. Flow from the main flow control valve is directed through a variable speed controlling orifice to the small piston of the de-intensifier.

4. This is a two speed rammer, and the purpose of the de-intensifier is to provide a large measured volume of low pressure fluid to the ramming actuator during the initial slow speed travel of the projectile tray through the transition tracks from the horizontal loading position to the barrel elevation angle, while making the most efficient use of the high pressure supply from the accumulator.
5. Flow from the large piston of the de-intensifier is directed to the ramming actuator through a variable, speed controlling orifice. This orifice is adjusted to provide a full flow actuator speed of thirty inches/second. This actuator speed is maintained throughout the first fifty-seven inches of actuator travel.
6. When the actuator travel reaches fifty-seven inches, the de-intensifier piston opens porting which allows a direct flow path from the main flow control valve to the actuator. The variable orifice at the outlet of the flow control valve is adjusted to provide a maximum ramming velocity of three hundred inches/second.



7. When the actuator reaches the end of the ramming stroke, a mechanical contact shifts the two position control valve to the return position. This removes pressure from the back of the main flow control valve, thus shutting off any flow from the main accumulator. At the same time, the two pilot operated check valves at either end of the de-intensifier are opened.
8. At this point, both ends of the ramming actuator are open to reservoir pressure. Due to the differential area of the piston in the actuator, the rod will extend, moving the projectile tray back to the load position.
9. Flow from the actuator is directed back to the reservoir through a variable, speed controlling orifice. This orifice is adjusted to provide a full flow actuator speed of sixty inches / second. This actuator speed is maintained throughout the full return stroke of actuator travel.

RAMMER EQUATIONS

$$M_1 \ddot{x}_1 = A_1 P_1 + A_2 P_2 - A_3 P_3$$

$$M_2 \ddot{x}_2 = A_4 P_4 - A_5 P_5 - W(\sin \theta + f \cos \theta)$$

$$\dot{x}_1 = \frac{A_4 \dot{x}_2}{A_3}$$

$$\dot{x}_1 = \frac{A_4 \dot{x}_2}{A_3}$$

$$\ddot{x}_1 = \frac{A_4 \ddot{x}_2}{A_3}$$

$$P_1 = P_A - \left( \frac{A_1 \dot{x}_1}{115.5 A_{01}} \right)^2 = P_0 - \left( \frac{A_1 A_4 \dot{x}_2}{115.5 A_3 A_{01}} \right)^2$$

$$P_2 = P_R$$

$$P_3 = \frac{A_1 P_1 + A_2 P_2 - M_1 \ddot{x}_1}{A_3} = \frac{A_1 P_1 + A_2 P_2 - \frac{M_1 A_4 \ddot{x}_2}{A_3}}{A_3}$$

$$P_4 = P_3 - \left( \frac{A_4 \dot{x}_2}{115.5 A_{03}} \right)^2 - \left( \frac{A_4 \dot{x}_2}{115.5 A_{04}} \right)^2 - K_1 \dot{x}_2$$

$$P_5 = P_R + \left( \frac{A_5 \dot{x}_2}{115.5 A_{05}} \right)^2 + K_2 \dot{x}_2$$

$$A_1 = D_1^2 \pi (.25)$$

$$A_2 = (D_2^2 - D_1^2) \pi (.25)$$

$$A_3 = D_2^2 \pi (.25)$$

$$A_4 = (D_3^2 - D_4^2) \pi (.25)$$

$$A_5 = (D_3^2 - D_5^2) \pi (.25)$$

$$C_1 = 16\mu \left[ \frac{2 D_3^2 \ln\left(\frac{D_3}{D_4}\right) - (D_3^2 - D_4^2)}{(D_3^4 - D_4^4) \ln\left(\frac{D_3}{D_4}\right) - (D_3^2 - D_4^2)^2} \right]$$

$$C_2 = 16\mu \left[ \frac{2 D_6^2 \ln\left(\frac{D_6}{D_4}\right) - (D_6^2 - D_4^2)}{(D_6^4 - D_4^4) \ln\left(\frac{D_6}{D_4}\right) - (D_6^2 - D_4^2)^2} \right]$$

$$C_3 = 16\mu \left[ \frac{2 D_3^2 \ln\left(\frac{D_3}{D_7}\right) - (D_3^2 - D_7^2)}{(D_3^4 - D_7^4) \ln\left(\frac{D_3}{D_7}\right) - (D_3^2 - D_7^2)^2} \right]$$

$$C_4 = 32\mu \left[ \frac{(D_3^2 - D_5^2) \ln\left(\frac{D_3}{D_5}\right)}{(D_3^4 - D_5^4) \ln\left(\frac{D_3}{D_5}\right) - (D_3^2 - D_5^2)^2} \right]$$

$$C_5 = 16\mu \left[ \frac{2 D_6^2 \ln\left(\frac{D_6}{D_7}\right) - (D_6^2 - D_7^2)}{(D_6^4 - D_7^4) \ln\left(\frac{D_6}{D_7}\right) - (D_6^2 - D_7^2)^2} \right]$$

$$\mu = \frac{\nu \rho}{g}$$

for  $x = 0$  to  $(l_3 - l_2)$

$$K_1 = C_1(l_1 + l_2 - l_3 + x) + C_2(0) + C_3(l_3 - l_2) + C_5(l_2)$$

$$\text{let } R_1 = C_1(l_1 + l_2 - l_3) + C_3(l_3 - l_2) + C_5(l_2)$$

$$R_2 = C_1$$

$$K_1 = R_1 + R_2 x$$

for  $x = (l_3 - l_2)$  to  $l_3$

$$K_1 = C_1(l_1) + C_2(l_2 - l_3 + x) + C_3(x) + C_5(l_3 - x)$$

$$\text{let } R_1 = C_1(l_1) + C_2(l_2 - l_3) + C_5(l_3)$$

$$\text{let } R_2 = C_2 + C_3 - C_5$$

$$K_1 = R_1 + R_2 x$$

for  $x = l_3$  to  $l_4$

$$K_1 = C_1(l_1 - l_3 + x) + C_2(l_2) + C_3(l_3) + C_5(0)$$

$$\text{let } R_1 = C_1(l_1 - l_3) + C_2(l_2) + C_3(l_3)$$

$$R_2 = C_1$$

$$K_1 = R_1 + R_2 x$$

for  $x = 0$  to  $l_4$

$$K_2 = C_4(l_4 - x)$$

$$\text{let } R_3 = C_4(l_4)$$

$$K_2 = R_3 - C_4 x$$

$$M_2 \ddot{x}_2 = A_4 P_4 - A_5 P_5 - W (\sin \theta + f \cos \theta)$$

$$M_2 \ddot{x}_2 = A_4 \left[ \frac{A_1 P_1 + A_2 P_2}{A_3} - \left( \frac{A_4 \dot{x}_2}{115.5 A_{03}} \right)^2 - \left( \frac{A_4 \dot{x}_2}{115.5 A_{04}} \right)^2 - K_1 \dot{x}_2 \right]$$

$$= \frac{A_4^2 M_1 \ddot{x}_2}{A_3^2} - A_5 P_5 - W (\sin \theta + f \cos \theta)$$

$$\ddot{x}_2 = A_4 \left[ \frac{A_1 P_1 + A_2 P_2}{A_3} - \left( \frac{A_4 \dot{x}_2}{115.5 A_{03}} \right)^2 - \left( \frac{A_4 \dot{x}_2}{115.5 A_{04}} \right)^2 - K_1 \dot{x}_2 \right] - A_5 P_5 - W (\sin \theta + f \cos \theta)$$

$$M_2 + \frac{A_4^2 M_1}{A_3^2}$$

$$\frac{A_4 A_1 P_1}{A_3} = \frac{A_4 A_1 P_A}{A_3} - \frac{A_4^3 A_1^3 \dot{x}_2^2}{(115.5)^2 A_3^3 A_{01}^2}$$

$$\frac{A_4 A_2 P_2}{A_3} = \frac{A_4 A_2 P_R}{A_3}$$

$$A_5 P_5 = A_5 P_R + \frac{A_5^3 \dot{x}_2^2}{(115.5)^2 A_{05}^2} + A_5 K_2 \dot{x}_2$$

$$A_4 K_1 \dot{x}_2 = (A_4 R_1 + A_4 R_2 x) \dot{x}_2$$

$$A_5 K_2 \dot{x}_2 = (A_5 R_3 - A_5 C_4 x) \dot{x}_2$$

$$\text{let } B_1 = \frac{A_4 A_1 P_A + \frac{A_4 A_2 P_R}{A_3} - A_5 P_R - W(\sin \theta + f \cos \theta)}{M_2 + \frac{A_4^2}{A_3^2} M_1}$$

$$\text{let } B_2 = \frac{\frac{A_4^3}{A_{03}^2} + \frac{A_4^3}{A_{04}^2} + \frac{A_4^3 A_1^3}{A_3^3 A_{01}^2} + \frac{A_5^3}{A_{05}^2}}{(115.5)^2 \left( M_2 + \frac{A_4^2}{A_3^2} M_1 \right)}$$

$$\text{let } B_3 = \frac{A_4 R_1 + A_5 R_3}{M_2 + \frac{A_4^2}{A_3^2} M_1}$$

$$\text{let } B_4 = \frac{A_4 R_2 - A_5 C_4}{M_2 + \frac{A_4^2}{A_3^2} M_1}$$

$$\ddot{x}_2 = B_1 - B_2 \dot{x}_2^2 - (B_3 + B_4 \dot{x}_2) \dot{x}_2$$

Above equations hold for  $x = 0$  to 57 inches

For 57 in. to 87 in. let

$$\begin{aligned} A_3 &= A_1 \\ A_2 &= 0 \\ M_1 &= 0 \\ A_{03} &= \infty \end{aligned}$$

For retract 87 in to 0 in let

$$\begin{aligned} A_3 &= A_2 \\ A_{01} &= 0 \\ A_{03} &= A_{02} \\ P_A &= 0 \\ M_1 &= 0 \\ W &= W - 100 \# \\ M_2 &= M_2 - 100/386 \end{aligned}$$

WWW  
WWW  
WWW

```

M      M      222      000      EEEEE      222      000
MM MM  2      2      0      0      E      2      2      0      0
M M M      2      0      00      E      2      0      00
M      M      2      0      0      0      EEEE      2      0      0      0
M      M      2      00      0      E      2      00      0
M      M      2      0      0      E      2      0      0
M      M      22222      000      EEEEE      22222      000

```

|          |    |            |    |      |      |
|----------|----|------------|----|------|------|
| RRRRRRRR |    | AAAAAA     |    | MM   | MM   |
| RRRRRRRR |    | AAAAAA     |    | MM   | MM   |
| RR       | RR | AA         | AA | MMMM | MMMM |
| RR       | RR | AA         | AA | MMMM | MMMM |
| RR       | RR | AA         | AA | MM   | MM   |
| RR       | RR | AA         | AA | MM   | MM   |
| RRRRRRRR |    | AA         | AA | MM   | MM   |
| RRRRRRRR |    | AA         | AA | MM   | MM   |
| RR       | RR | AAAAAAAAAA |    | MM   | MM   |
| RR       | RR | AAAAAAAAAA |    | MM   | MM   |
| RR       | RR | AA         | AA | MM   | MM   |
| RR       | RR | AA         | AA | MM   | MM   |
| RR       | RR | AA         | AA | MM   | MM   |
| RR       | RR | AA         | AA | MM   | MM   |

|      |            |        |          |          |    |      |        |
|------|------------|--------|----------|----------|----|------|--------|
|      | FFFFFFFFFF | OOOOOO | RRRRRRRR | ;;;;     | 11 |      |        |
|      | FFFFFFFFFF | OOOOOO | RRRRRRRR | ;;;;     | 11 |      |        |
|      | FF         | OO     | OO       | RR       | RR | ;;;; | 1111   |
|      | FF         | OO     | OO       | RR       | RR | ;;;; | 1111   |
|      | FF         | OO     | OO       | RR       | RR |      | 11     |
|      | FF         | OO     | OO       | RR       | RR |      | 11     |
|      | FFFFFFFFFF | OO     | OO       | RRRRRRRR |    | ;;;; | 11     |
|      | FFFFFFFFFF | OO     | OO       | RRRRRRRR |    | ;;;; | 11     |
|      | FF         | OO     | OO       | RR       | RR | ;;;; | 11     |
|      | FF         | OO     | OO       | RR       | RR | ;;;; | 11     |
| .... | FF         | OO     | OO       | RR       | RR | ;;   | 11     |
| .... | FF         | OO     | OO       | RR       | RR | ;;   | 11     |
| .... | FF         |        | OOOOOO   | RR       | RR | ;;   | 111111 |
| .... | FF         |        | OOOOOO   | RR       | RR | ;;   | 111111 |

File HSC000\$DUA9:[M20.IRELAND JV.VMS]RAM.FOR;1 (1699,21,1), last revised on 16-MAR-1987 09:52, is a 4 block sequential file owned by UIC [M20,IRELAND JV]. The records are variable length with implied (CR) carriage control. The longest record is 61 bytes.

Job AODAT (375) queued to LN on 24-APR-1987 11:31 by user M20E20, UIC [M20,IRELAND\_JV], under account M22 at priority 100, started on printer VENUS\$TXA6: on 24-APR-1987 11:36 from queue TXA6.

WWW  
WWW  
WWW

17

```

DP=2.0
DR=1.75
DTR=0.
DOV=1.0
DOP=1.5
DOTR1=.15
DOTR2=.75
G=386.087
PA=775.
PR=300.
RHO=.0308
VISCOS=.8
W=150.
THETA=45.
CF=.3
PI=3.14159
AOV=PI*DOV*DOV/4.
AOP=PI*DOP*DOP/4.
AOTR1=PI*DOTR1*DOTR1/4.
AOTR2=PI*DOTR2*DOTR2/4.
RP=DP/2.
RR=DR/2.
AP=PI*RP*RP
AR=PI*RR*RR
ATR=PI*DTR*DTR/4.
APR=AP-AR
AP=1.374
E1=(APR/(115.5*AOV))**2.
E4=(AP/(115.5*AOP))**2.
E5=(ATR/(115.5*AOTR1))**2.
E6=(ATR/(115.5*AOTR2))**2.
S=E5
F1=LOG(RP/RR)
F2=RP*RP
F3=RR*RR
F4=F2-F3
F5=F2+F3
E2=4.*RHO*VISCOS*(2.*F2*F1-F4)/((F5*F1-F4)*F4*G)
ANGLE=THETA*PI/180.
E3=PA*APR-PR*AP-W*(SIN(ANGLE)+CF*COS(ANGLE))
XRAM=0.
XDRAM=0.
T=0.
COUNT=4.
DT=.005
100 C1=-1.
    C2=1.
    C3=-1.
    DXRAM=0.
    DXDRAM=0.
    XRAMK=0.
    XDRAML=0.
    DO 200 I=1,4
    C1=C1+2.*C2
    C2=C2-.5
    D1=1.5-C1*.5+C3
    C3=0.
    XEFF=XRAM+D1*XRAMK
    XDEFF=XDRAM+D1*XDRAML
    XRAMK=DT*XDEFF
    R=E3-((3.*E1*APR+E4*AP+E5*ATR)*XDEFF+E2*APR*XEFF)*XDEFF
    XDRAML=DT*(G/W)*R

```



```
DXRAM=DXRAM+C1*XRAMK
DXDRAM=DXDRAM+C1*XDRAML
200 CONTINUE
T=T+DT
XRAM=XRAM+DXRAM/6.
XDRAM=XDRAM+DXDRAM/6.
IF(E5.GT.S) GO TO 250
IF(COUNT.LT.4.) GO TO 350
250 PRINT 300,T,XRAM,XDRAM
300 FORMAT(3X,F6.4,4X,F7.3,4X,F7.3)
COUNT=0.
350 IF(XRAM.GT.57.) E5=E6
IF(XRAM.GE.85.) GO TO 400
IF(T.GE.2.5) GO TO 400
COUNT=COUNT+1.
GO TO 100
400 STOP
END
```

PART NUMBERS: 1258570-225, AIR/HYDRAULIC SERVICE BRAKE  
SYSTEM ASSY  
12585748, Rotor

DESCRIPTION: PARKING AND SERVICE BRAKES

See status section below for detailed description of system.

STATUS:

The LTHD air/hydraulic service brake system assembly and functional schematic can be found in TDP, Dwg. 12585710-225. FMC has worked with Hayes Industrial Brake to finalize all specifications for the service brake system. Drawings for all parts can be found in the TDP. The basic operating principles for the service brake system are identical to that of the M198. In addition, on-line filters were added to keep contaminants out of the emergency valve, since contaminants in the valve has been the cause of past M198 brake system malfunctions. Service brakes are used on all four wheels.

The LTHD also uses a parking brake on each front wheel. The two parking brakes must be set to hold the LTHD on sloping ground during the displacement operation. The system consists of Tol-O-Matic brake calipers and a linkage and brake handle on the left and right hand front side. The completed drawings for this design can be found in the TDP.

The rotor (TDP, Dwg. 12585748) for each wheel consists of machined 6061 25v/o Al/SiCp extrusion (TDP, Dwg. 12586016-003).

Calculations of the load holding requirements for each of the brakes can be found in the following pages of this section.

AUTHOR: Dave Boudreau

LTHD

10-27-86 24  
JR Bondman

# TORQUE PER WHEEL FOR REQD BRAKING REF. - LANE SLACK LOCKET

$$\tau = \frac{WgRx12}{gN} = \frac{(9000)(16.3)\left(\frac{14}{12}\right)(\pi)}{(32.2)(4)} = 15,946 \text{ POUNDS IN PER WHEEL}$$

TO TORQUE PER WHEEL IN POUNDS INCH

FOR WEIGHT OF VEHICLE IN POUNDS

63,782 PER 4 WHEELS

$g = \text{ACCEL IN } \text{m}^2/\text{SEC}^2$

$R = \text{EFFECTIVE ROLL RADIUS IN FT}$

$N = \text{NO. OF WHEELS}$

$J = 32.2$

$$a = \frac{1.457V}{T_s} \text{ OR } \frac{1.076V^2}{J_s}$$

$$\frac{1.076(55)^2}{200} = 16 \text{ m/sec}$$

$a = \text{ACCEL IN } \text{m}^2/\text{SEC}^2$

$V = \text{VELOCITY IN MPH}$

$T_s = \text{STOP TIME IN SEC}$

$J_s = \text{DIST IN FT.}$

HAYES SERIES 41-25 LEADERS AT 3000 POUNDS  
PER PAD CAPABLE 250 @ 1500 PSI @ 6000 PSI.

BASED ON REQmts ON MIL HDBK-405

LTND

BRAKE  
STOPPING T

10-29-86  
8/12

③  
2

$$a = \frac{1.076 V^2}{S_s} = \frac{1.076 (20)^2}{30} = 14.34 \text{ FT/SEC}^2$$

$$T = \frac{W a R \times 12}{g N} = \frac{(9000)(14.34)(14)(12)}{(32.2)(4)} = 14,028$$

POUND INCHES/INCH

BASED ON 20 MPH STOP IN 30 FEET

PARK BRAKE REQ.

$$T = \frac{W \sin \theta \times R}{G R}$$

T = TORQUE IN IN.

W = WT. OF CAR

$\theta$  = ANGLE IN DEGREES

R = ROLL RADIUS IN INCHES

GR = GEAR RATIO

$$T = \frac{(9000)(\sin 31^\circ)(14)}{1/1}$$

$$T = 64,894 \text{ POUND IN.}$$

$$T = \frac{(9000)(\sin 11^\circ)(14)}{1/1} = 24,042 \text{ POUND IN.}$$

3. 11-5-86  
Dr. 12 (4)

LTHD

BRAKE  
STOPPING TORQUE

$$a = \frac{1.076 V^2}{DS} = \frac{1.076 (20)^2}{30} = 14.34 \text{ F/sec}^2$$

$$T = \frac{WbR \times 12}{9 N} = \frac{(9000)(14.34) \left(\frac{14}{2}\right) (1)}{(32.2)(4)} = 14,028$$

POUND INCH

= 12R HAYES 4125

$$T = 2.9 P (R - .75) \text{ W R. 70}$$

$$= (2.9)(1500)(7.5 - .75)$$

$$= 29,319 \text{ POUND INCH}$$

SERIES 41-25

HAS A HIGHER  
RATING

HAYES 41

$$T = 4.14 \mu P \left( \frac{D_1^2}{2} - .75 \right)$$

M - ASSUME COEF. OF .35

$$= (4.14)(.35)(1500) \left( \frac{15}{2} - .75 \right)$$

$$= 14,671 \text{ POUND INCH}$$

# Selecting the Right Brake

## Optimum performance for your application

To pick the brake and rotor combination that will provide the optimum performance for your particular application, three major factors must be considered — the braking torque required, which affects the choice of caliper unit; the maximum kinetic energy absorption required, which affects the choice of rotor; and the mechanical and environmental requirements, which affect the installation.

### Torque...

Torque requirements are very often the primary consideration in selecting a design. Torque curves and torque ratings given for each caliper unit listed, indicate a torque that can safely be expected under normal operating conditions with the rotor and applied force specified. A simple torque formula is given for each brake, based on the effective rotor radius and the applied braking effort.

In selecting an appropriate brake unit the following equations are useful for estimating torque requirements:

#### For Stopping a Rotating Mass

$$T = \frac{0.00326 \text{ in} \times 12}{t} \quad \text{where } T = \text{required torque in lbs. in.}$$

$I = \text{inertia of mass in lbs. ft}^2$   
 $n = \text{initial velocity of mass in rpm}$   
 $t = \text{time of stop in seconds}$

$$T = \frac{5252 \text{ H} \times 12}{n} \quad \text{where } T = \text{required torque in lbs. in.}$$

$H = \text{horsepower absorbed in hp}$   
 $n = \text{constant velocity in rpm}$

#### For Braking a Moving Vehicle

$$T = \frac{W a R \times 12}{g N} \quad \text{where } T = \text{torque per wheel in lbs. in.}$$

$W = \text{total vehicle weight in lbs.}$   
 $a = \text{rate of deceleration in ft./sec}^2$   
 $R = \text{effective rolling radius in ft.}$   
 $N = \text{number of braked wheels}$   
 $g = 32.2$

#### For Braking a Parked Vehicle

$$T = \frac{W \sin \theta \times R}{Gr} \quad \text{where } T = \text{torque required in lbs. in.}$$

$W = \text{total vehicle weight in lbs.}$   
 $\theta = \text{angle in degrees}$   
 $R = \text{effective rolling radius in in.}$   
 $Gr = \text{gear ratio to braked shaft}$

#### For Determining Deceleration Rates

$$a = \frac{1.076 V^2}{D_s} \quad \text{where } a = \text{deceleration in ft./sec}^2$$

$V = \text{velocity in miles per hour}$   
 $t_s = \text{stop time in seconds}$   
 $D_s = \text{distance to stop in ft.}$

$$a = \frac{1.467 V}{t_s}$$

### Energy Absorption...

Any moving object possesses kinetic energy and arresting that motion necessarily generates heat that must be dissipated. Disc brakes, by the very nature of

their design, offer superior energy absorbing characteristics. The rotor acts as an excellent 'heat sink'. Since at any given time it is receiving heat through only a small fraction of its surface area, the rest of the rotor is available to dissipate heat to the surrounding air. Just as torque affects caliper unit design, kinetic energy absorption affects rotor design. Under normal conditions disc brakes are relatively fade free and can be operated successfully at far higher temperatures than a comparable drum or band type brake.

The ability of a disc brake to absorb and dissipate heat (kinetic energy) depends on several factors:

1. The effective rubbed area of the rotor
2. The effective rotor mass
3. Ambient temperature and additional forced cooling
4. Rotor design and material
5. Permissible maximum operating temperature

The following equations are useful for estimating kinetic energy requirements:

#### For a Rotating Mass

$$KE = 0.00017 I n^2 \quad \text{where } KE = \text{kinetic energy in ft. lbs.}$$

$I = \text{inertia of mass in lbs. ft}^2$   
 $n = \text{initial velocity in rpm}$

#### For Stopping a Moving Vehicle

$$KE = 0.0334 W V^2 \quad \text{where } KE = \text{kinetic energy in ft. lbs.}$$

$W = \text{total weight of vehicle in lbs.}$   
 $V = \text{initial velocity in mph}$

#### For Total Energy Input Over a Specified Period

$$KE = \frac{2 n N T}{12} \quad \text{where } KE = \text{kinetic energy in ft. lbs.}$$

$N = \text{total number of rotor revolutions in that time}$   
 $T = \text{applied torque in lbs. in.}$   
 $n = 3.1416$

### Mechanical and Environmental Considerations

Although the basic specification of the brake may well be determined by the first two considerations, the actual design and configuration finally selected is often dictated by the operating environment and space restrictions imposed by the equipment in question. The physical layout may determine whether simple mechanical actuation is feasible or the more flexible hydraulic or pneumatic actuation is to be preferred. It may also determine the choice of fixed or floating mount configurations.

Operating environment and duty cycle are frequently the major factors in brake selection. Some models will work well in dirty environments, others will not. The result of comprehensive life cycle testing on your machine in its expected duty cycle and operating environment is the final brake decision factor.

PART NUMBERS: 12585802, Primer Autoloader  
12585710-240, Assembly  
12585726, Primer Actuator

DESCRIPTION: PRIMER AUTOLOADER

See status section below for detailed description of system.

STATUS:

Primer Autoloader -

The FMC LTHD uses a modified FMC-developed primer autoloader (TDP, Dwgs. 12585802, 12585710-240 - assembly) in order to meet LTHD loading time cycle requirements. This autoloader was not funded under contract. The autoloader holds 20 primers in a replaceable drum and can be actuated hydraulically (as in normal operation) or manually (in a degraded mode). An operational description of the autoloader can be found within the writeup of Misfire Procedure Tasks (TDP, Dwg. 12585710-825, shts 24-26) since primer inspection is required in these tasks.

A prototype FMC primer autoloader is currently being manufactured at this time, with a rigorous testing program to follow. The LTHD-required modifications to the autoloader include the addition of a hydraulic lanyard actuator as well as a ring to hook on a lanyard for use in degraded operation. The locations and specifications for tapped holes in the Benet Breech Housing have been approved by Benet.

Primer Actuator and Hoses -

Mounting and size requirements for the primer actuator (TDP, Dwg. 12585726) have been determined and were provided to York to be finalized. These requirements were developed to be compatible with both the FMC primer autoloader and also the Benet Breech Housing.

All hoses, fittings and connectors have been finalized and are specified on FMC TDP gang-sheets. Layouts of the primer actuator and hoses can be found in the TDP, Cannon Assembly.

AUTHORS: Tim Doering, Joe Turek, Jeff Ireland

**LTHD ACTUATORS**  
**AUTO PRIMER ACTUATOR**

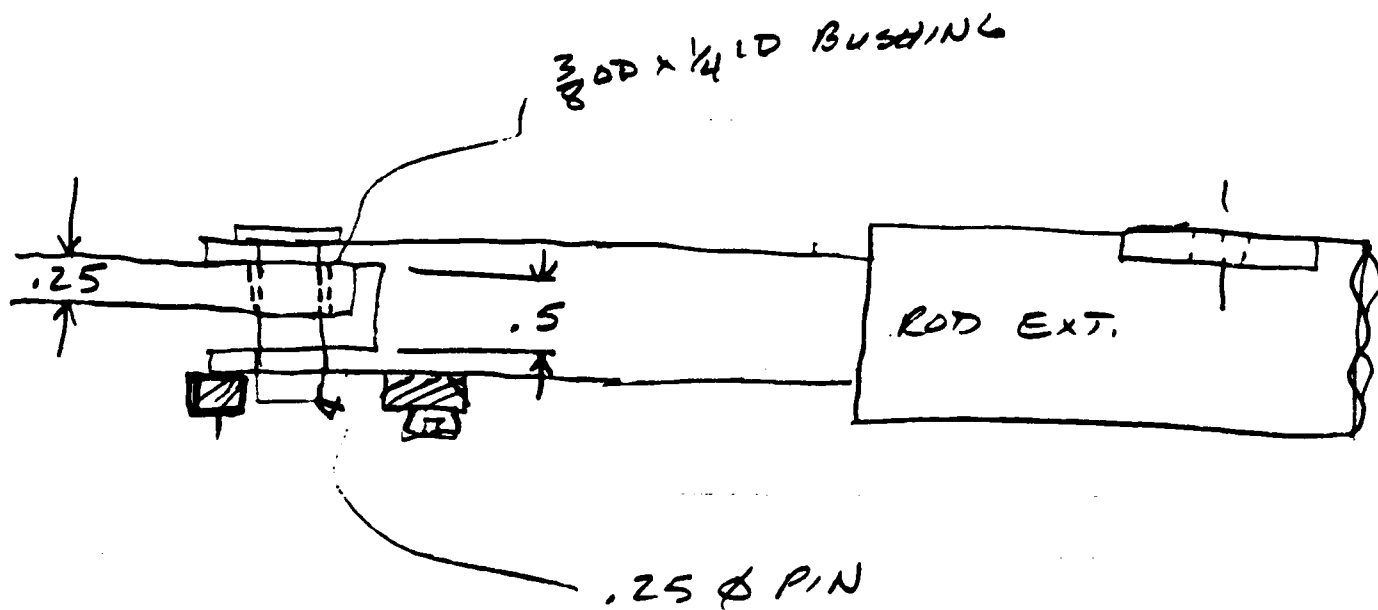
|                        |                    |      |
|------------------------|--------------------|------|
| PISTON DIA             |                    | in.  |
| ROD DIA                |                    | in.  |
| WORKING PRESSURE       | 3000               | psi  |
| PROOF PRESSURE         | 4500               | psi  |
| EXTEND FORCE           | 50                 | lbs. |
| EXTEND OIL FLOW        |                    | gpm  |
| RETRACT FORCE          | 20                 | lbs. |
| RETRACT OIL FLOW       |                    | gpm  |
| EXTENDED LENGTH        | 12.125             | in.  |
| RETRACTED LENGTH       | 7.625              | in.  |
| STROKE                 | 4.5                | in.  |
| EXTEND CUSHION LENGTH  |                    | in.  |
| RETRACT CUSHION LENGTH |                    | in.  |
| ACTUATOR ENDS:         |                    |      |
| CYLINDER END           | CYL BOLTED TO BAND |      |
| ROD END                | ROD END THREADED   |      |
|                        | TO PRIMER INDEXING |      |
|                        | SLIDE.             |      |
| ACTUATOR WEIGHT        | 2.5                | lbs. |
| SHOCK FACTOR           | 20                 | g's  |
| COMMENTS:              |                    |      |



A-Z

3

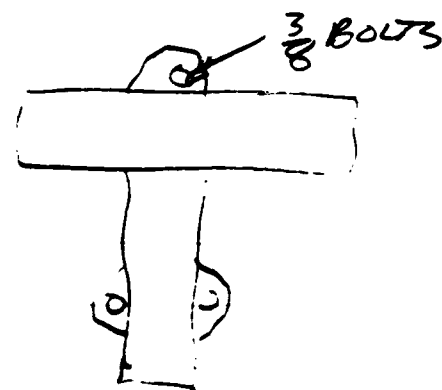
AUTO PRIMER



ALLOW .25 MAX FOR BRACKET  
MOVEMENT

$$.25 \text{ PIN } A = .0491$$

$$S = \frac{195.9}{.0491} = 3,989$$



$$\frac{3}{8} \text{ BOLT } A = .1104$$

$$S = \frac{195.9}{.1104} = 1,774 \quad 1 \text{ BOLT}$$

$$3 \text{ BOLT} = \frac{1774}{3} = 591.48$$

AUTO PRIMER P1  
A.C.

4

$$.0883 \times 3000 = 264.90$$

$$.6896 \times 100 = 68.96$$

$$.0883 \times 300 = 26.49$$

$$.6896 \times 300 = 206.88$$

$$.0883 \times 100 = 8.83$$

$$\begin{array}{r} 3000 \quad 264.90 \\ 100 \quad - \quad 68.96 \\ \hline 195.94 \end{array}$$

$$\begin{array}{r} 3000 \quad 264.90 \\ 300 \quad - \quad 206.88 \\ \hline 58.02 \end{array}$$

$$\begin{array}{r} 100 \quad 68.96 \\ 100 \quad \quad 8.83 \\ \hline 60.13 \end{array}$$

$$\begin{array}{r} 300 \quad 206.88 \\ 300 \quad \quad 26.49 \\ \hline 180.39 \end{array}$$

P 2

1/28/86

5

$$\frac{15}{76} = .19883$$

$$\frac{7}{8} = .875$$

100 PSI

$$15/16 \times 7/8$$

$$264.90$$

3000

$$- \frac{8.83}{256.07}$$

100 PSI

$$264.90$$

3000

$$26.49$$

300

$$238.41$$

$$P_{IN} = \frac{256.07}{.25} = 1024.28$$

RUSHING 1/4 ID X 3/8 OD

$$A = .25 \times .25 = .0625$$

$$\frac{256.07}{.0625} = P = 4097$$

$$206.88$$

300

$$- 26.49$$

300

$$180.39$$

$$68.96$$

100

$$- 8.83$$

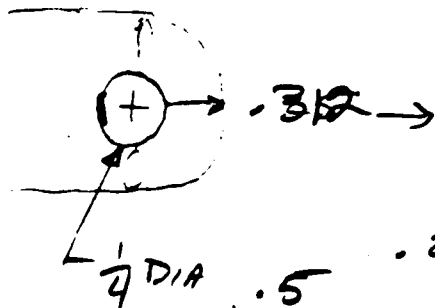
100

$$60.13$$

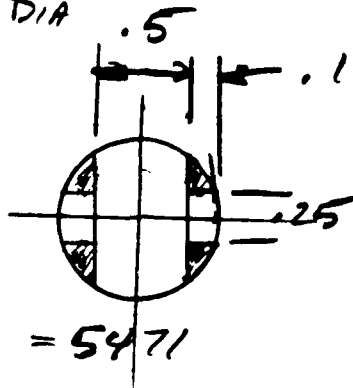
DISOGRIN # 110-006 P43D

ROD WIPER .875 X 1.375 D X .362 LGTH.

ROD SEAL .875 X 1.125 X .281 001-054 P. 9D



$$.25 \times .25 = \frac{256.07}{.0625} = P = 4097$$



$$.187 \times .187 = .035$$

$$\frac{256.07}{.0468} = 5471$$

$$\frac{264.9}{.0350} = 7568$$

SEE

A-1

P3

1/28/86

6

$$\frac{60}{.4} = 150 \times 4.5 = 675 \text{ " PER MIN}$$

$$1" A = .785$$

$$\frac{7}{16} A = .6013$$

$$\frac{15}{16} A = .6896$$

$$\begin{array}{r} .785 \\ - .6013 \\ \hline .1837 \end{array}$$

$$\frac{3}{8} A = .1104$$

$$.1837 \times 3000 \text{ psi} = 551.03$$

$$.0954 \times 3000 \text{ psi} = 286.32$$

$$.0883 \times 3000 = 264.90 \times$$

$$\begin{array}{r} * \\ .6896 \quad 551.03 \\ - .6013 \quad 286.50 \\ \hline .0883 \quad 472.53 \end{array}$$

$$.785 \times 300 \text{ psi} = 235.5$$

$$.785 \times 100 \text{ psi} = 78.50$$

$$.0954 \times 300 \text{ psi} = 28.62$$

$$.0883 \times 300$$

$$.0883 \times 100$$

$$.6896 \times 300 = 206.88 \times$$

$$.6896 \times 100 = 68.96 \times$$

$$.5792 \times 100 = 57.91$$

$$.5792 \times 300 = 173.74$$

$$.6896 \times 3000 = 2069 \times \text{STAIR}$$

$$\begin{array}{r} 264.90 \\ - 206.88 \\ \hline 58.02 \end{array}$$

$$\begin{array}{r} .6896 \\ - .1104 \\ \hline .5792 \end{array}$$

$$\begin{array}{r} 264.90 \\ - 173.74 \\ \hline 91.15 \end{array}$$

$$\begin{array}{r} 57.91 \\ - 26.49 \\ \hline 31.42 \end{array}$$

|      |        |        |        |         |
|------|--------|--------|--------|---------|
|      | 3000   | 300    | 100    | 3000    |
| 3000 | 264.90 | 264.90 | 206.88 | 68.96   |
| 300  | 206.88 | 68.96  | 26.49  | 2,068.9 |
|      | 58.02  | 195.94 | 180.39 | 68.96   |
|      |        |        | 60.00  | 2000    |

$$3000 \times .6896 = 2,068.8$$

$$2000 \div .0491 = 40,733$$

$$120,000 \times (.577) = 69,240$$

$$\begin{array}{l} 1/4 \text{ PIN SEEN } 3000 \text{ psi} \\ = 1.7 \text{ TO } 1 \end{array}$$

P4

7

$$A \frac{1}{8} = .994$$

$$A \frac{3}{8} = \underline{.6013}$$

$$.3927 \times .187 = \underline{.0734}$$

$$3000 \text{ psi} \times .3927 = 1.178 = p = 16,050$$

$$4 \text{ } 50,000 (.577) = 24,850 \div 16,050 = 1.8 \text{ to } 1$$

$$\frac{60}{14} = 150 \times 4.5 = 675 \text{ " PER MIN}$$

$$.6496 \times 675 = \frac{465.48}{231} = 2.015 \text{ GPM}$$

$$\begin{array}{r} \times 2 \\ \hline 4.03 \end{array}$$

26' PER SEC  $\phi .25$  HOLE

$$.04883 \times 675 = \frac{59.60}{231} = .258$$

$$\begin{array}{r} \times 2 \\ \hline .516 \end{array}$$

3' PER SEC  $\phi .25$  HOLE

$$M \ddot{x} = -(A_p - A_r) \left[ P_r + \frac{(A_p - A_r) \dot{x}^2}{115.5 A_{op}} \right] + \left[ P_r - \frac{(A_p) \dot{x}^2}{115.5 A_{op}} \right] A$$

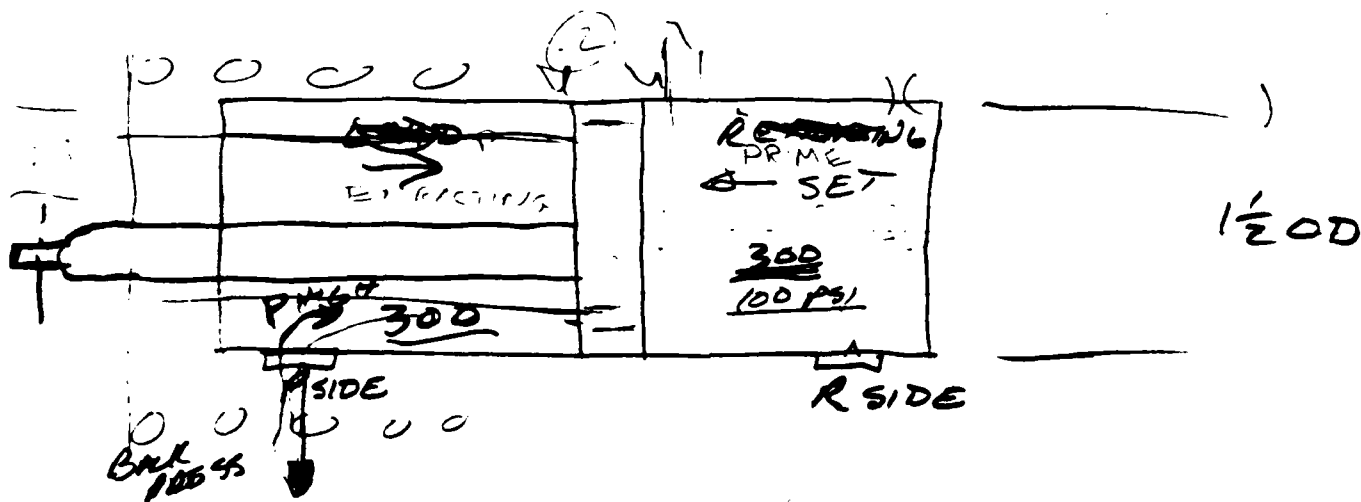
$$F = P A$$

$$F = 50 \text{ lb}$$

$$P = 3000$$

RETURN 300

2.0017  
1.75



$$\frac{1}{2} \text{ ROD } A = .1963$$

CUBIC IN  
OR

$$U = 4.5 \times .785 = 3.53$$

$$GPM = \frac{3.53}{2.31} = .0153$$

$$\frac{F 50}{P 3000} = A$$

$$A = .0167$$

$$\frac{50}{.0167}$$

$$1" A = .785$$

$$3/4 A = .4418$$

$$\begin{array}{r} 3/4 \text{ ROD} \\ .4418 \\ 1/2 \text{ ROD} \\ .1963 \\ \hline .2455 \end{array} \rightarrow \boxed{.4418}$$

$$U = 4.5 \times .4418 = \frac{1.9881}{2.31} = .009$$

$$U = 4.5 \times .2455 = \frac{1.1048}{2.31} = .005$$

A-1

$$h = .187$$

$$C = .717$$

$$L = .8399$$

$$R = .4375$$

$$\alpha = 110^\circ$$

$$CIR = 2.7489$$

$$A = \frac{1}{2} [ .4375 (.8399) - 717 (.4375 - .187) ]$$

$$.3675 - 717 (.25)$$

$$.3675 - .1793 =$$

$$A = \frac{1}{2} [.1883]$$

$$A = .5 (.1883)$$

$$A = .0941 \quad \times 2 = .188$$

$$A = .188 \quad . - .093 = .094$$

$$\frac{196}{.094} = 2085$$

$$\frac{2000}{.094} \text{ BENDING ?}$$

$$= 21,276$$

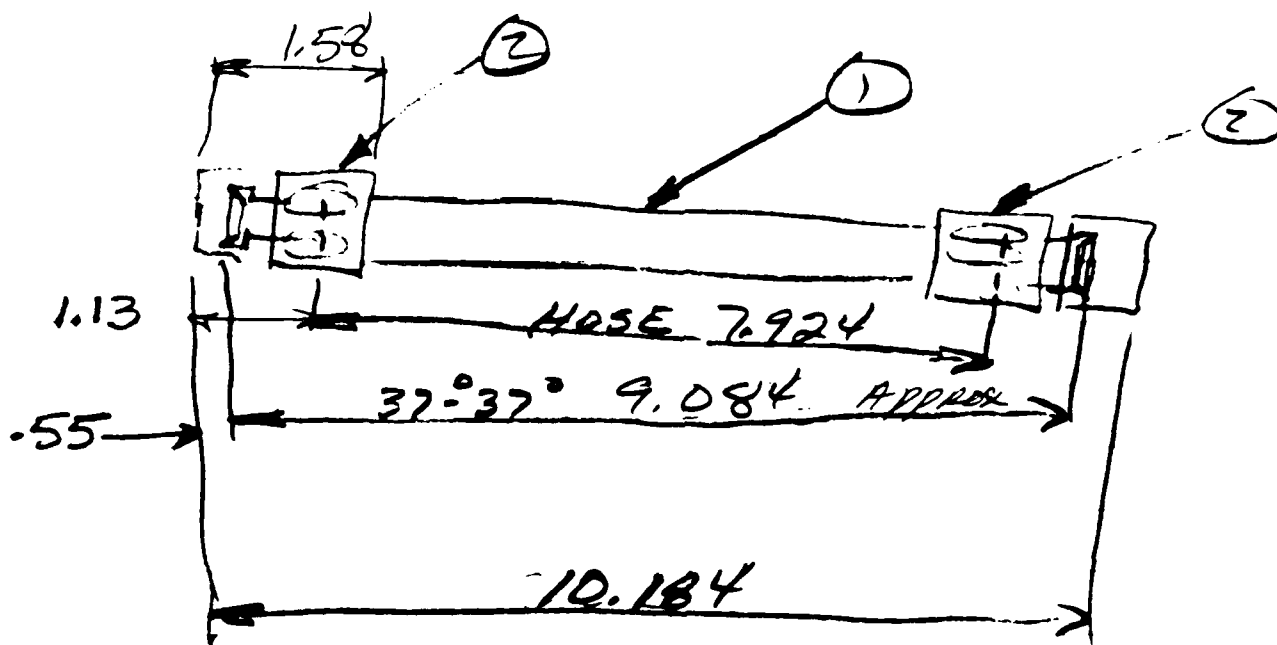


T-12586037/A (004)

11

3/7/87

HOSE FOR PRIMER TO  
BAND



ITEM 1 HOSE QTY 1 AERD 2807-4  
X 9.56 LG

FITTING 63-190600-4 S.STL 37° F  
BOTH ENDS

87/3/7

①

$$5'' R = C \ 31.4159 / 360 \times 15^\circ = 1.309$$

$$6.75 + 2.18 + 1.309 = 10.184$$

②

$$5.875 = 36.9137 / 360 \times 15 = 1.538$$

$$6.5 + 2.22 + 1.538 = 10.16$$

15°

③

$$8.5 = 53.4071 / 360 \times 10 = 1.483$$

$$6 + 2.625 + 1.483 = \underline{10.108}$$

END

10-87

DTIC